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# Probability theory and mathematical statistics for IT students

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# Contents

## Introduction

a.	Basic concepts and notations	2	
b.	b. Probability		
c.	Conditional probability and independence	30	
d.	Random variable	44	
e.	Numerical characteristics of random variables	68	
f.	Frequently used discrete distributions	88	
g.	Frequently used continuous distributions	110	
h.	Law of large numbers	138	
i.	Central limit theorem	154	
j.	Basic concepts of mathematical statistics	175	
References		202	
Tables			

#### Introduction

The aim of this booklet is to introduce the students to the world of random phenomena. The real world is plenty of random things. Without striving to completeness, for example, think for waiting time in the post office, or the working time of a machine, the cost of the repair of an instrument, insurance, stock market and rate of exchange, damages caused by computer viruses and so on. It is obvious that these random phenomena have economic significance as well; consequently their random behaviour has to be handled. The method of handling is served by probability theory.

The concept of probability was developing during centuries. It originates in gambles, for example playing cards, games with dice but the idea and the developed methods can be applied to economic phenomena, as well. Since medieval ages people realized that random phenomena have a certain type of regularity. Roughly spoken, although one can not predict what happens during one experiment but it can be predicted what happens during many experiments. The mentioned regularities are investigated and formed by formal mathematical apparatus. The axiomatic set up of probability was published by Kolmogorov in 1933 and since then the theory of probability, as a branch of mathematics, has been growing incredibly. Nevertheless there are problems which are very simple to understand but very difficult to solve. Solving techniques require lots of mathematical knowledge in analysis, combinatory, differential and integral equation. On the other hand computer technique is developing very quickly, as well; hence great immense of random experiences can be performed. The behaviour of stochastic phenomena can be investigated experimentally, as well. Moreover, difficult probabilistic problems can be solved easily by simulation after performing a great amount of computations.

This booklet introduces the main definitions connected to randomness, highlights the concept of distribution, density function, expectation and dispersion. It investigates the most important discrete and continuous distributions and shows the connections among them. It leads the students from the properties of probability to the central limit theorem. Finally it ends in the basis of statistics preparing the reader for further statistical studies.

# a. Basic concepts and notations

#### The aim of this chapter

This chapter aims with getting acquainted with the concept of outcome of an experiment, events, occurrence of an event, operations with event. We introduce  $\sigma$  algebra of events.

## Preliminary knowledge

The applied mathematical apparatus: sets and set operations.

#### Content

- a.1. Experiments, possible outcome, sample space, events
- a.2. Operations with events
- a.3.  $\sigma$  algebra of events

# a.1. Experiments, possible outcome, sample space, events

The fundamental conception of the probability theory is experiment.

#### Experiment is observation of a phenomenon.

This phenomenon can be an artificial (caused by people) one or a phenomenon in the nature, as well. We do not bother whether the experiment originates from home made or natural circumstances. We require that the observation should be repeated many times. Actually we list some experiments:

• Measure the water level of a river.

- Measure air pollution in a town.
- Measure the falling time of a stone from a tower to the ground.
- Measure the waiting time at an office.
- Measure the amount of rainfall at a certain place.
- Count the number of failures of a machine during a time period.
- Count the number of complains connected to a certain product of a factory.
- Count the infected files on a computer at a time point.
- Count the number of shooting stars at night in August.
- Count the number of heads if you flip 100 coins.
- Investigate the result of flipping a coin.
- Investigate if there is an odd number among three rolls of a die.
- Investigate the energy consumption of a factory during a time period.
- Investigate the demand of circulation of banknotes at a bank machine.
- Investigate the working time of a part of a machine.
- Investigate the cost of the treatment of a patient in a hospital.
- Sum the daily income of a supermarket.
- Sum the amount of claims at an insurance company during a year.
- List the winning numbers of the lottery.

If one "takes measure", "counts", "investigates", "sums" and so on, one observes a phenomenon.

In some cases the result of the observation is unique. These experiments are called deterministic experiment. In other cases the observation may end in more than one results. These experiments are called stochastic or random experiments. Probability theory deals with stochastic experiments.

If one performs an experiment (trial), he can take into consideration what may happen. The possible results are called **possible outcomes**, or, in other words, **elementary events**. The set of possible outcomes will be called as **sample space**.

We denote a possible outcome by  $\omega$ , and the sample space by  $\Omega$ .

What is considered as "possible outcome" of an experiment? It is optional. First, it depends on what we are interested in. If we flip a coin, we are interested if the result is head (H) or tail (T) but usually we are not interested in the number of turnings. We can also decide whether the result of a measurement should be an integer or a real number. What should be the unit of measurement? If you investigate the water level of a river, usually the most important thing is the danger of flood. Consequently low-medium-high might be enough as possible outcomes.

But possible outcomes are influenced by the things that are worth investigating to have such cases which are simple to handle. If we are interested in the number of heads during 100 flips, we have to decide whether we take into consideration the order of heads and tails or it is unnecessary. Therefore, during a probabilistic problem the first task is to formulate possible outcomes and determine their set.

In the examples of previous list, if we measure something, a possible result may be a nonnegative real number, therefore  $\Omega = R_0^+$ . If we count something, possible outcomes are

nonnegative integer, therefore  $\Omega = N$ . If we investigate the result of a flip, the possible outcomes are head and tail, so  $\Omega = \{H, T\}$ . This set does not contain numbers. The sample space may be an abstract set. If we list the winning numbers of the lottery (5 numbers are drawn of 90), a possible outcome is  $\omega_1 = \{1,2,3,4,5\}$ , and another one is  $\omega_2 = \{10,20,50,80,90\}$ . Possible outcomes are sets themselves. Consequently, the sample space is a set of sets, which is an abstract set again.

If an experiment is performed, then one of its possible outcomes will be realized. If we repeat the experiment, the result of the observation is a possible outcome which might be different from the previous one. This is due the random behaviour. After performing the trial we know its result, before making the trial we are only able to take into consideration the possible results.

In practice events are investigated: they occur or not.

**Events** are considered as a subset of the sample space. That means, certain possible outcomes are in a fixed event, others are not contained in it. We say that the **event A occurs** during an experiment if the outcome in which the trial results is the element of the set A. If the outcome observed during the actual experiment is not in A, we say that A does not occur during the actual experiment. If the observed outcomes are different during the experiments, the event A may occur in one experiment and may not in another one.

This meaning coincides with the common meaning of occurrence. Let us consider some very simple examples.

E1. Roll a single six-sided die. The possible outcomes are: 1 point is on the upper surface, 2 points are on the upper surface, ..., 6 points are on the upper surface. Briefly,  $\Omega = \{1,2,3,4,5,6\}$  i=1,2,3,4,5,6 indicates the possible outcomes by the number of points. Let  $A \subset \Omega$ ,  $A = \{1,3,5\}$ . The elements of A are the odd numbers on the surface. If the result of the roll is  $\omega_1 = 1$ , then  $\omega_1 \in A$ . We say that A occurs during this experiment. On the other side, in common parlance we usually say that the result of the roll is odd number. In case the result of the experiment is  $\omega_6 = 6$ , then  $\omega_6 \notin A$ , A does not occur during this experiment. The roll is not odd. Although A is a set, A expresses the "sentence" that the result of the trial is odd. If the trial ends in showing up  $\omega_6 = 6$ , we shortly say that the result of the roll is "six".

E2. Measure the level of a river.  $\Omega = R_0^+$ . Suppose that if the level of the river is more than 800cm, then there is danger of flood. The sentence "there is danger of flood" can be expressed by the event (set)  $A = \{x \in R_0^+ : 800 < x\} \subset \Omega$ . If the result of the measurement is  $\omega = 805$ cm, then  $\omega \in A$ . A occurs, and indeed, there is danger of flood. If the result is the measurement is  $\omega = 650$  cm, then  $\omega \notin A$ . We say A does not occur, and really, there is no danger of flood in that case.

E3. Count complains connected to a certain type of product. Now  $\Omega = N$ . If "too much problems" means that the number of complains reaches a level, for example 100, then sentence "too much problem" is the set  $A = \{n \in N : 100 \le n\}$ . If the number of complaints is  $\omega = 160$ , then  $\omega \in A$ . The event A occurs and there are too much complains. If the number of complains is  $\omega = 86$ , then  $\omega \notin A$ . A does not occurs, and indeed, the result of the trial does not mean too much problems.

The event  $\Omega$  is called **certain** or **sure event**. It occurs sure, as whatever the outcome of the experiment is, it is included in  $\Omega$ , therefore  $\Omega$  occurs.

The event  $\emptyset$  (empty set) is called **impossible event**. It can not occur, as whatever the outcome of the experiment is, it is not the element of  $\emptyset$ .

Further examples for events:

E4. Flip twice a coin. Take into consideration of the order of the results of separate flip. Now  $\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$ , where the outcome (H, T) represents that the first flip is head, the second one is tail.

The event "there at least one head among the flips" is the set  $A = \{(H, H), (H, T), ((T, H))\}$ . The event "there at most one head among the flips" is the set  $B = \{(H, T), (T, H), (T, T)\}$ .

The event "there is no head among the flips" is the set  $C = \{(T, T)\}$ .

The event "there is no tail among the flips" is the set  $D = \{(H, H)\}$ . The event "the first flip is tail among the flips" is the set  $E = \{(T, H), (T, T)\}$ .

The event "the flips are different" is the set  $F = \{(H, T), (T, H)\}$ .

The event "the flips are the same" is the set  $G = \{(H, H), (T, T)\}$ .

We note that the number of subsets of sample space  $\Omega$  is  $4^2 = 16$ , consequently there are 16 events in this example including certain and impossible event, as well.

E5. Roll twice a die. Take into consideration the order of rolls. In that case  $\Omega = \{(1,1), (1,2), (1,3), (1,4), (1,5), (1,6), (2,1), \dots, (6,6)\} = = \{(i, j): 1 \le i \le 6, 1 \le j \le 6, i, j \text{ are integer}\}.$ The event "there is no 6 between the rolls" is  $A = \{(1,1), (1,2), (1,3), (1,4), (1,5), (2,1), \dots, (2,5), \dots, (5,1), \dots, (5,5)\}.$ The event "the sum of the rolls is 6" is  $B = \{(1,5), (2,4), (3,3), (4,2), (5,1)\}$ . The event "the maximum of the rolls is 3" is  $C = \{(1,3), (2,3), (3,2), (3,2), (3,1)\}$ . The event "the minimum of the rolls is at most 5" is  $D = \{(5,5), (5,6), (6,5), (6,6)\}$ .

As the number of possible outcomes is  $6 \cdot 6 = 36$ , therefore the number of events is  $2^{36} = 6.87 \cdot 10^{10}$ .

Pick one card from a pack of Hungarian cards containing 32 playing cards. E6. Now,  $\Omega = \begin{cases} \text{ace of hearts ace of leaves, ace of acorns ace of bells, under of hearts,...,} \\ \text{upper of hearts,..., king of hearts,..., ten of hearts, seven of hearts,...} \end{cases}$ 

The event "the picked card is heart" is

A =  $\begin{cases} \text{ace of hearts, upper of hearts, under of hearts, king of hearts,} \end{cases}$ 

ten of hearts, nine of hearts, eight of hearts, seven of hearts

The event "the picked card is ace" is

 $B = \{ace of hearts, ace of leaves, ace of acorns, ace of bells\}.$ 

The event "the picked card is ace and heart" is  $C = \{ace of hearts\}$ .

E7. Pick two cards from a pack of Hungarian playing cards without replacing the chosen card. Do not take into consideration the order of the card. In this case the sample space is

{ace of hearts,ace of leaves}, {ace of hearts,upper of hearts},...., {seven of acorns,ten of acorns},.....  $\Omega =$ 

containing all the sets of two different elements of cards. The event "both cards are ace" is

{ace of hearts, ace of leaves}, {ace of hearts, ace of bells}, ]

 $A = \left\{ \{ ace of hearts, ace of acorns \}, \{ ace of leaves, ace of bells \}, \right\}$ .

{ace of leaves, ace of acorns}, {ace of bells, ace of acorns}

The event" both cards are hearts" is

 $B = \{\{ace of hearts, king of hearts\}, \{ace of hearts, upper of hearts\}, ....\}$ .

If we want to express the event the "first card is heart", it can not be expressed actually, because we do not take into consideration the order of cards. If we want to express this event, we have to modify the sample space as follows:

 $\Omega^{\text{mod}} = \{ (\text{ace of hearts, ace of leaves}), (\text{ace of leaves, ace of hearts}), \dots \}$ 

The outcome (ace of hearts, ace of leaves) means that the first card is the ace of hearts; the second one is the ace of leaves. The outcome (ace of leaves, ace of hearts) means that the first card is the ace of leaves; the second one is the ace of hearts. To clarify the difference, we emphasize that outcome {ace of hearts, ace of leaves} means that one of the picked playing

cards is ace of hearts, the other one is ace of leaves. In the sample space  $\Omega^{mod}$ , the event "first card is heart" can be written easily. This is an example in which the formulation of the sample space depends on the question of the problem, not only on the trial.

E8. Choose a number from the interval [0,1]. In that case  $\Omega = [0,1]$ .

The event "first digital of the number is 6" is A = [0.6, 0.7).

The event "second digital is zero" is

 $C = [0,0.01) \cup [0.1,0.11] \cup [0.2,0.21] \cup ... \cup [0.9,0.91].$  The event "all of the digital of the number are the same" is  $B = \{0,0.1,0.2,...,0.9\}$ .

In this example the number of all possible outcomes and the number of events are infinity.

## a.2. Operations with events

As events are sets, the operations with events mean operations on sets. In this subsection we interpret the set operations by the terminology of events.

• Union (or sum) of events

First recall that union of two or more sets contains all the elements of the sets.

Let A and B be events, that is  $A \subset \Omega$  and  $B \subset \Omega$ . Now  $A \cup B \subset \Omega$  holds as well.  $A \cup B$  occurs if  $\omega \in A \cup B$  holds, consequently  $\omega \in A$  or  $\omega \in B$ . If  $\omega \in A$ , then A occurs, if  $\omega \in B$ , then B occurs. Summarizing, occurrence of  $A \cup B$  means that A or B occurs. At least one of them must occur. That means either A and B or both events occur. We emphasize that "OR" is not an exclusive choice but a concessive one. Union of events can be expressed by the word OR.

• Intersection (or production) of events

First recall that intersection of two or more sets contains all the common elements of the sets. Let A and B be events, that is  $A \subset \Omega$  and  $B \subset \Omega$ . Now  $A \cap B \subset \Omega$  holds, as well.  $A \cap B$  occurs, if  $\omega \in A \cap B$  holds, consequently  $\omega \in A$  and  $\omega \in B$ . If  $\omega \in A$ , then A occurs, if  $\omega \in B$  then B occurs. Summarizing, occurrence of  $A \cap B$  means that both A and B occur. Intersection of events can be expressed by the word AND.

Two events are called **mutually exclusive** if their intersection is the impossible event. That means if either of them holds the other one can not occur.

• **Difference** of two events

First recall that the difference of sets A and B contains all of elements of A which are not contained by B.

Let A and B be events, that is  $A \subset \Omega$  and  $B \subset \Omega$ . Now  $A \setminus B \subset \Omega$  hold, as well.  $A \setminus B$  occurs if  $\omega \in A \setminus B$  holds, consequently  $\omega \in A$  and  $\omega \notin B$ . If  $\omega \in A$ , then A occurs. If  $\omega \notin B$  then B does not occur. Summarizing, occurrence of  $A \setminus B$  means that A occurs but B does not.

• Complement of an event

Let A be an events, that is  $A \subset \Omega \cdot \overline{A} \subset \Omega$  holds, as well.  $\omega \in \overline{A}$  holds, if  $\omega \notin A$ . If  $\omega \notin A$ , then A does not occur. Consequently,  $\overline{A}$  can be expressed by the word NOT A.

Remarks

• Operations on events have all the properties of operations on set: union, intersection are commutative, associative, the union and intersection is distributive.

• Further often used equality is the following one:

 $A \setminus B = A \cap \overline{B}$ , and the de Morgan's equalities:

$$\overline{A \cup B} = \overline{A} \cap \overline{B}$$
, and for infinite many sets  $\bigcup_{i=1}^{\infty} A_i = \bigcap_{i=1}^{\infty} \overline{A_i}$   
 $\overline{A \cap B} = \overline{A} \cup \overline{B}$ , and for infinitely many sets  $\overline{\bigcap_{i=1}^{\infty} A_i} = \bigcup_{i=1}^{\infty} \overline{A_i}$ .

Actually we present some examples how to express complicated events by the help of simple ones and operations.

E1. Choose one from the students of the Pannon University. Let A be the event that the student is a students of economics, let B be the event that the student lives in a student hostel. In that case the sample space is the set of all the students of the university, one of its subset is the set of those students who are students of economics; another of its subset is formed by the students living in a student hostel. If the chosen student belongs to the subset mentioned first, then the event A occurs. Actually, for example, the following events can be described by A, B and operations:

The chosen student is student of economics but does not live in a student hostel:  $A \cap B = A \setminus B$ . He/she is not student of economics and he does not live in a student hostel:  $\overline{A} \cap \overline{B}$ .

He/she is not student of economics or does not live in a student hostel:  $\overline{A \cup B}$ .

He/she is student of economics or does not live in a student hostel:  $A \cup \overline{B}$ .

He/she is not student of economics and he/she lives in a student hostel or he is student of economics and does not live in a student hostel:  $(B \setminus A) \cup (A \setminus B)$ .

He/she is student of economics and he lives in a student hostel or he/she is not student of economics and he/she does not live in a student hostel:  $(A \cap B) \cup (\overline{A} \cap \overline{B})$ .

E2. In a machine two parts may fail: part x and part y. Let A be the event that part x fails, let B the event that part y fails.

If both parts fail, then  $A \cap B$  holds.

At least one of them fails:  $A \cup B$  holds.

Part x fails but part y does not:  $A \setminus B$  holds.

Either of them fails:  $(A \setminus B) \cup (B \setminus A)$  holds.

Neither of them fails:  $\overline{A} \cap \overline{B}$  holds.

At least of them does not fail:  $\overline{A} \cup \overline{B}$  holds.

We note that in this case the sample space can be defined as follows:  $\Omega = \{(f, f), (f, n)(n, f), (n, n)\}$ , and possible outcome (f, n) represents that part x fails and part y does not.

E3. Let us investigate the arrival time of a person to a meeting. Let us suppose that the arrival time is a point in [-5,15]. (-1 represents that he arrives 1 minute earlier than the

8

scheduled time, 5 represents that he arrives 5 minutes late). Let A be the event that he is late, B the event that the difference of the scheduled time of meeting and the arrival time is less than 2 minutes (briefly small difference). Now A=[-5,0), B=(-2,2). The event that he is late but small difference is  $A \cap B$ .

He is not late or not small difference is:  $\overline{A} \cup \overline{B}$ .

Both events or neither of them hold:  $(A \cap B) \cup (\overline{A} \cap \overline{B})$ .

both events of hermer of them hold.  $(A \cap B) \cup (A \cap B) \cup (A \cap B)$ 

He is late but not small difference is:  $A \cap \overline{B}$ .

He is not late or not small difference is:  $A \cup B$  .

## a.3. $\sigma$ algebra of events

<u>Definition</u> Let the set of all possible outcomes be fixed and denoted by  $\Omega$ . The set  $\mathcal{A}$  containing some of all the subsets of  $\Omega$  is called  $\sigma$  algebra, if the following properties hold:

- 1.  $\Omega \in \mathcal{A}$ .
- 2. If  $A \in \mathcal{A}$ , then  $\overline{A} \in \mathcal{A}$  holds, as well.

3. If 
$$A_i \in \mathcal{A}$$
,  $i = 1, 2, 3, ...,$  then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{A}$  holds as well.

**Remarks** 

- $\emptyset \in \mathcal{A} \text{ as } \emptyset = \overline{\Omega} \text{ and } \Omega \in \mathcal{A}.$
- Applying the properties of operations one can see that if  $A_i \in \mathcal{A}$ , then  $\bigcap_{i=1}^{\infty} A_i \in \mathcal{A}$ . As a

proof, take into consideration that if  $A_i \in \mathcal{A}$ , then  $\overline{A_i} \in \mathcal{A}$ , consequently.  $\bigcup_{i=1}^{\infty} \overline{A_i} \in \mathcal{A}_i$ , .

Therefore,  $\overline{\bigcup_{i=1}^{\infty}\overline{A_i}} = \overline{\bigcap_{i=1}^{\infty}A_i} = \bigcap_{i=1}^{\infty}A_i \in \mathcal{A}$ .

• If  $A \in \mathcal{A}$  and  $B \in \mathcal{A}$ , then  $A \setminus B \in \mathcal{A}$  holds as well. As a proof, take into consideration that  $A \setminus B = A \cap \overline{B}$ . If  $B \in \mathcal{A}$ , then  $\overline{B} \in \mathcal{A}$  holds as well, and  $A \cap \overline{B} \in \mathcal{A}$  is also satisfied.

Strictly, the elements of the  $\sigma$  algebra A are called events. The above properties express that if some sets are events, then their union, intersection, difference and complement are events, as well.

In probability theory we would like determine the probability of events characterizing by it the relative frequency of the occurrence during many experiments.

## b. Probability

#### The aim of this chapter

The aim of this chapter is getting acquainted with the basic properties of the probability. We present the relative frequency, introduce the axioms of probability and we derive the consequences of the axioms. Classical and geometrical probability are also introduced and applied for sampling problems.

#### Preliminary knowledge

The applied mathematical apparatus: sets and set operation. Combinatorial counting problems. Co-ordinate geometry. Basic knowledge in any computer program language.

#### Content

- b.1. Frequency, relative frequency
- b.2. Axioms of the probability
- b.3. Consequences of axioms
- b.4. Classical probability
- b.5. Geometrical probability

## b.1. Frequency, relative frequency

The aim of the probability theory is to characterize an event by a number which expresses its relative frequency. More precisely, the events which occur frequently during many experiments are characterized by a large number. The events which are rare are characterized by a small number. If one performs n experiments and count how many times the event A occurs, one gets the frequency of A denoted by  $k_A(n)$ . It is obvious, that  $0 \le k_A \le n$ . If we are interested in the proportion of occurrences of A and the number of trials, we have to divide  $k_A(n)$ .by n, that is take the relative frequency.  $\frac{k_A(n)}{n}$ . It is easy to see that  $0 \le \frac{k_A(n)}{n} \le 1$ .

Moreover,  $k_{\Omega}(n) = n$ , therefore  $\frac{k_{\Omega}(n)}{n} = 1$ . If A and B are events for which  $A \cap B = \emptyset$ , then

 $k_{A\cup B}(n) = k_A(n) + k_B(n)$ , consequently  $\frac{k_{A\cup B}(n)}{n} = \frac{k_A(n)}{n} + \frac{k_B(n)}{n}$ . The value of relative frequency depends on the actual series of experiments, hence it changes if we repeat the series of experiments. During the centuries, people recognized that the relative frequency has a kind

of stability. As if it had a limit. To present this phenomenon let us consider the following example.

Let the experiment be flipping a coin many times. Let A be the event that the result is head during one flip.

In Table b.1, one can see the frequency and relative frequency of event in the function of the number of experiments (n).

Result of the trial	Т	Т	Т	Н	Т	Т	Н	Т	Н	Н
$k_A(n)$	0	0	0	1	1	1	2	2	3	4
n	1	2	3	4	5	6	7	8	9	10
$\underline{k_A(n)}$	0	0	0	0.25	0.2	0.17	0.27	0.25	0.33	0.4
n										

Table b.1 Frequency and relative frequency of heads in the function of the number of experiences

Draw the graph of relative frequency  $\frac{k_A(n)}{n}$  in the function of n. We can see the graph in the following figures: Fig.b.1, Fig.b.2, Fig.b.3 show oscillations. On the top of all, if we performed the series of experiments once again, we presumably would get other results for relative frequencies. If we increase the number of experiments the graph changes. Although there are fluctuations at the beginning of the graph, later they disappear, the graph looks almost constant.





Fig.b.2 Relative frequency of heads in the function of the number of experiences (n=1000)

The mentioned phenomenon becomes more and more expressive if we increase the number of experiments, as Fig. b.3 shows, as well.



Fig.b.3 Relative frequency of heads in the function of the number of experiences (n=10000)

If we look at Fig.b.3 thoroughly, we can realize that for large values of experiments, the relative frequency is almost constant function. Although fluctuations in the number of heads exist, they are small as compared to the number of experiences. This phenomenon was drafted during the centuries by the statement "relative frequency has a kind of stability". This phenomenon is expressed mathematically by the "law of large numbers".

#### b.2. Axioms of probability

If we would like to characterize the relative frequency by the probability, the probability should have the same properties as the relative frequency. Therefore, we require the properties for probability presented previously for the relative frequency.

<u>Definition</u> Let  $\mathcal{A}$  be a  $\sigma$  algebra. The function  $P: \mathcal{A} \to R$  is called **probability measure** if the following three requirements (axioms) hold:

I)  $0 \leq P(A)$ .

II)  $P(\Omega) = 1$ .

III) If 
$$A_i \in \mathcal{A}$$
,  $i = 1, 2, 3, ...$  for which  $A_i \cap A_j = \emptyset$   $i \neq j$ , then  $P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$ .

Remarks

• The above axioms I), II) and III) are called as Kolmogorov' axioms of probability. They were published in 1933.

• Probability measure maps the  $\sigma$  algebra of events to the set of real numbers. The elements of  $\mathcal{A}$  (events) have probability. As P maps to R, P(A) is a real number. The number P(A) is called the **probability of the event A**.

• We define probability by its property. It means that every function is probability measure that satisfies I), II) and III).

• Property I), II) and III) correspond to the properties of relative frequency. The property  $P(A) \le 1$  is not requirement; it can be proved from the axioms. Additive property is presented for two events in case of relative frequency, but it is required for countable infinitely many events in axiom III) in case of probability.

• Property I) expresses that the probability of any event is a nonnegative number.

• Property II) expresses that the probability of the sure event equals 1.

• Property III) expresses additive property of the probability for countable infinitely many mutually exclusive events.

• As  $\mathcal{A}$  is a  $\sigma$  algebra, the property III) is well defined. If  $A_i \in \mathcal{A}$ , i = 1, 2, 3, ... hold, then

 $\left(\bigcup_{i=1}^{\infty} A_i\right) \in \mathcal{A}$  is also satisfied, consequently it has probability.

If a function P satisfies axiom I), II) and III), it satisfies many other properties, as well. These properties are called as consequences of axioms. These properties serve to express probabilities of "composed" events by the help of probabilities of "simple" events.

## b3. Consequences of the axioms

We list the consequences of the axioms and we present their proofs. During this we do not use any heuristic evidences, we insist on strict mathematical inferences.

C1.  $\mathbf{P}(\emptyset) = \mathbf{0}$ .

 $\emptyset = \emptyset \cup \emptyset \cup \emptyset \cup \ldots$  and  $\emptyset \cap \emptyset = \emptyset$ . That means that the impossible event can be written as the union of infinitely many pair-wise mutually exclusive events. Consequently, axiom III) can

be applied and 
$$P(\emptyset) = \sum_{i=1}^{\infty} P(\emptyset)$$
. Recalling that  $\sum_{i=1}^{\infty} x_i = \lim_{n \to \infty} \sum_{i=1}^{n} x_i$ , we can conclude that

 $P(\emptyset) = \sum_{i=1}^{\infty} P(\emptyset) = \lim_{n \to \infty} n \cdot P(\emptyset).$  If  $0 < P(\emptyset)$  holds, then the limit is infinite, which is a

contradiction, as  $P(\emptyset)$  is a real number. If  $P(\emptyset) = 0$ , then  $n \cdot P(\emptyset) = 0$  also holds for any value of n, therefore the limit is 0. In that case  $0 = P(\emptyset) = \sum_{i=1}^{\infty} P(\emptyset) = 0$  holds, as well. Finally,  $P(\emptyset)$  can not be possible asymptotic properties of  $P(\emptyset) = 0$ . The possible of  $P(\emptyset) = 0$  holds are not be possible of  $P(\emptyset) = 0$ .

 $P(\emptyset)$  can not be negative, remember axiom I). Hence  $P(\emptyset) = 0$  must be satisfied.

C2. (finite additive property) If 
$$A_i \in \mathcal{A}$$
,  $i = 1, 2, ..., n$  and  $A_i \cap A_j = \emptyset$ ,  $i \neq j$ , then

$$P(A_1 \cup ... \cup A_n) = \sum_{i=1}^n P(A_i) = P(A_1) + ... + P(A_n).$$

We trace this property to axiom III). Let  $A_{n+1} = \emptyset$ ,  $A_{n+2} = \emptyset$ ,.... Now we have infinitely many events and  $A_i \cap A_j = \emptyset$ ,  $i = 1, 2, ..., j = 1, 2, ..., i \neq j$ . If  $i \leq n$  and  $j \leq n$ , this is our assumption, if n < i or n < j holds, then  $A_i = \emptyset$  or  $A_j = \emptyset$ , consequently their intersection is

the impossible event. Now axiom III) can be  

$$P(\bigcup_{i=1}^{n} A_{i}) = P(\bigcup_{i=1}^{\infty} A_{i}) = \sum_{i=1}^{\infty} P(A_{i}) = \sum_{i=1}^{n} P(A_{i}) + P(\emptyset) + P(\emptyset) + \dots$$
As  $P(\emptyset) = 0$ , we get  $P(\bigcup_{i=1}^{n} A_{i}) = \sum_{i=1}^{n} P(A_{i})$  and the proof is completed.

Let  $A \in \mathcal{A}$  and  $B \in \mathcal{A}$ . If  $A \cap B = \emptyset$ , then  $P(A \cup B) = P(A) + P(B)$ . C3.

This is the previous property for n = 2 with notation  $A_1 = A$  and  $A_2 = B$ . We emphasize it because the additive property is frequently used in this form.

C4. Let 
$$A \in \mathcal{A}$$
.  $P(\overline{A}) = 1 - P(A)$ 

.. .

This connection is really very simple and it is frequently applied in the real world.

It can be proved as follows:  $\Omega = A \cup A$ , and  $A \cap A = \emptyset$ . Applying C3 we can see, that  $P(\Omega) = P(A) + P(A)$ . Taking into consideration axiom II)  $P(\Omega) = 1$ , we get 1 = P(A) + P(A). Arranging the equality, it is easy to get C4. We mention that  $\mathcal{A}$  is  $\sigma$  algebra, consequently if  $A \in \mathcal{A}$  then  $A \in \mathcal{A}$ , which means that A has also probability.

#### C5. Let $A \in \mathcal{A}$ and $B \in \mathcal{A}$ . If $B \subset A$ , then $P(A \setminus B) = P(A) - P(B)$ .

This formula expresses the probability of the difference of A and B by the help of the probability A and B.

Take into consideration that  $B \subset A$  implies the equality  $A = (A \setminus B) \cup B$ , moreover  $(A \setminus B) \cap B = \emptyset$ . Consequently C3 can be applied and results in  $P(A) = P(A \setminus B) + P(B)$ . Arranging the formula we get C5.

C6. Let  $A \in \mathcal{A}$  and  $B \in \mathcal{A}$ . If  $B \subset A$ , then  $P(B) \leq P(A)$ 

Recall C5, and take into consideration axiom These I). formulas imply  $0 \le P(A \setminus B) = P(A) - P(B)$ . Non-negativity of P(A) - P(B) means C6.

C7. Let  $B \in \mathcal{A}$ .  $P(B) \leq 1$ .

This inequality is straightforward consequence of C6 with  $A = \Omega$ .

The formula expresses that the probability of any event is less than or equal to 1. This property coincides with the property of relative frequency  $\frac{k_A(n)}{n} \le 1$ .

C8. Let  $A \in \mathcal{A}$  and  $B \in \mathcal{A}$ .  $|\mathbf{P}(A \setminus B) = \mathbf{P}(A) - \mathbf{P}(A \cap B)|$ .

It is obvious that  $A = (A \setminus B) \cup (A \cap B)$  and  $(A \setminus B) \cap (A \cap B) = \emptyset$ .

Using C3 they imply  $P(A) = P(A \setminus B) + P(A \cap B)$ . Subtracting  $P(A \cap B)$  from both sides we get C8.

We emphasize that in this formula there is no extra condition for the event A and B, but C5 contains condition  $B \subset A$ . Consequently C8 is a more general statement than C6. We mention that if  $B \subset A$ , then  $A \cap B = B$ , therefore C6 coincides with C8.

C9. Let  $A \in \mathcal{A}$  and  $B \in \mathcal{A}$ .  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ .

This formula expresses the probability of the union by the help of the probability of the events and the probability of their intersection.

To prove it, take into consideration the identity  $A \cup B = (A \setminus B) \cup B$ . Now  $(A \setminus B) \cap B = \emptyset$ . Applying C3 we get  $P(A \cup B) = P(A \setminus B) + P((B))$ . Now C8 implies the identity  $P(A \cup B) = P(A) - P(A \cap B) + P(B)$  and the proof is completed.

and

applied

We note that C9 does not require any assumption on the events A and B. C3 holds for mutually exclusive events. If  $A \cap B = \emptyset$ , then  $P(A \cap B) = 0$  and  $P(A \cup B) = P(A) + P(B) - P(A \cap B) = P(A) + P(B)$  coinciding with C3.

We emphasize that probability is not additive function. It is only in case of mutually exclusive events.

## C10. Let $A \in \mathcal{A}$ and $B \in \mathcal{A}$ . $P(A \cup B) \leq P(A) + P(B)$ .

This formula is straightforward consequence of C9 taking into account that  $0 \le P(A \cap B)$ . If we do not subtract the nonnegative quantity  $P(A \cap B)$  from P(A) + P(B), we increase it, consequently C10 holds. We note that C10 is not an equality, it serves an inequality for the probability of union.

C11. Let  $A \in \mathcal{A}$ ,  $B \in \mathcal{A}$  and  $C \in \mathcal{A}$ . Now,

 $P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C).$ This formula is generalization of C9 for three events.

It can be proved as follows. Let  $X = A \cup B$  and Y = C. Now  $A \cup B \cup C = X \cup Y$ . Applying three times C9, first for X and Y, secondly for  $A \cup B$  thirdly for  $A \cap C$  and  $B \cap C$  we get  $P(A \cup B \cup C) = P(X \cup Y) = P(X) + P(Y) - P(X \cap Y) = P(A \cup B) + P(C) - P((A \cup B) \cap C)) = P(A) + P(B) - P(A \cap B) + P(C) - P((A \cap C) \cup (B \cap C))) = P(A) + P(B) + P(C) - P(A \cap B) - -(P(A \cap C) + P(B \cap C) - P(A \cap C \cap B \cap C))) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) + P(B \cap C) - P(A \cap C \cap B \cap C)) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C))$ .

We note that if  $A \cap B = B \cap C = A \cap C = \emptyset$ , then  $A \cap B \cap C = \emptyset$ , and  $P(A \cap B) = P(A \cap C) = P(B \cap C) = P(A \cap C \cap B \cap C) = 0$ . Hence in this case C11 is simplified to  $P(A \cup B \cup C) = P(A) + P(B) + P(C)$  coinciding with C2.

C12. Let 
$$A_i \in \mathcal{A}$$
,  $i = 1, 2, \dots, n$ 

$$P\left(\bigcup_{i=1}^{n} A_{i}\right) = \sum_{i=1}^{n} P(A_{i}) - \sum_{1 \le i < j \le n} P(A_{i} \cap A_{j}) + \sum_{1 \le i < j < k \le n} P(A_{i} \cap A_{j} \cap A_{k}) - \dots + (-1)^{n+1} P(A_{1} \cap \dots \cap A_{n})$$

The formula can be proved by mathematical induction following the steps of the proof of C11 but actually we omit it.

It states that the probability of the union can be determined by the help of the probability of the events, the probability of the intersections of two, three,..., and all the events.

The relevance of the consequences is the following: if we check that the axioms are satisfied then we can use the formulas C1-C12, as well. By the help of them we are able to express the probability of "composite" events if we determine the probability of "simple" events.

Actually we present examples how to apply C1-C12, if we know the probability of some events. Further examples will be listed in the next subsection as well.

E1. In a factory two types of products are manufactured: Type I and Type II. Choosing one product, let A be the event that it is of Type I. According to quality, the products are ranged into two groups: standard and substandard groups. Let B be the event that the chosen product is of standard quality. If we suppose that P(A) = 0.7, P(B) = 0.9 and  $P(A \cap B) = 0.65$ , give the probability of the following events:

The chosen product is of Type II.: P(A) = 1 - P(A) = 0.3. (apply C4)

The chosen product is of substandard quality: P(B) = 1 - P(B) = 0.1.(apply C4)

The chosen product is of Type I and it is of substandard quality:  $P(A \cap \overline{B}) = P(A \setminus B) = P(A) - P(A \cap B) = 0.7 - 0.65 = 0.05$ . (apply C8)

The chosen product is of Type II and it is of standard quality:  $P(B \cap \overline{A}) = P(B \setminus A) = P(B) - P(A \cap B) = 0.9 - 0.65 = 0.25$ . (apply C8)

The chosen product is of Type I or it is of standard quality:  $P(A \cup B) = P(A) + P(B) - P(A \cap B) = 0.7 + 0.9 - 0.65 = 0.95$ . (apply C10)

The chosen product is of Type II or it is of substandard quality:

 $P(\overline{A} \cup \overline{B}) = P(\overline{A \cap B}) = 1 - P(A \cap B) = 1 - 0.65 = 0.35$  (apply the de Morgan's equality and C4)

The chosen product is of Type II and it is of substandard quality:  $P(\overline{A} \cap \overline{B}) = P(\overline{A \cup B}) = 1 - P(A \cup B) = 1 - 0.95 = 0.05$ . (apply the de Morgan equality and C4)

The chosen product is of Type I and of standard quality or it is of Type II and of substandard quality.

 $P((A \cap B) \cup (\overline{A} \cap \overline{B})) = P(A \cap B) + P(\overline{A} \cap \overline{B}) - P((A \cap B) \cap (\overline{A} \cap \overline{B})) = 0.65 + 0.05 - 0 = 0.7.$ (apply C10, and C1 as  $(A \cap B) \cap (\overline{A} \cap \overline{B}) = \emptyset$ ).

The chosen product is of Type I and of substandard quality or it is of Type II and of standard quality.

 $P((A \cap \overline{B}) \cup (\overline{A} \cap B)) = P(A \cap \overline{B}) + P(\overline{A} \cap B) - P((A \cap \overline{B}) \cap (\overline{A} \cap B)) = P(A \setminus B) + P(B \setminus A) = P(A) - P(A \cap B) + P(B) - P(A \cap B) = 0.7 - 0.65 + 0.9 - 0.65 = 0.3.$  (apply C10, C8 and C1 taking into account that  $(A \cap \overline{B}) \cap (\overline{A} \cap B) = \emptyset$ .)

E2. Choose a person from the population of a town. Let A be the event that the chosen person is unemployed, let B be the event that the chosen person can speak English fluently. If P(A) = 0.09, P(B) = 0.25 and  $P(A \cap B) = 0.02$ , then determine the probability of the following events:

The chosen person is not unemployed: P(A) = 0.91. (apply C4)

The chosen person can not speak English fluently and he is unemployed:

 $P(B \cap A) = P(A \setminus B) = P(A) - P(A \cap B) = 0.09 - 0.02 = 0.07$ . (apply C8)

The chosen person can speak fluently English and he is not unemployed:

 $P(B \cap A) = P(B) - P(B \cap A) = 0.25 - 0.02 = 0.23$ . (apply C8)

The chosen person can speak fluently English or he is not unemployed:  $P(\overline{B} \cup A) = P(\overline{B}) + P(A) - P(\overline{B} \cap A) = 1 - 0.25 + 0.09 - 0.07 = 0.77$  (apply C10 and C8)

The chosen person can not speak fluently English or he is unemployed:  $P(\overline{A} \cup B) = P(\overline{A}) + P(B) - P(\overline{A} \cap B) = 1 - 0.09 + 0.25 - 0.23 = 0.93$  (apply C10 and C8)

The chosen person is not unemployed or can not speak fluently English:

 $P(\overline{A} \cup \overline{B}) = P(\overline{A} \cap B) = 1 - P(A \cap B) = 1 - 0.02 = 0.98$  (apply the de Morgan's equality and C4)

The chosen person is not unemployed and can not speak fluently English:

 $P(A \cap B) = P(A \cup B) = 1 - P(A \cup B) = 1 - (P(A) + P(B) - P(A \cap B)) = 0$ 

1 - (0.09 + 0.25 - 0.02) = 0.68 (apply the de Morgan's equality C4 and C10)

E3. Game two types of races. Let A be the event that you win on the race of first type, let B be the event that you win on the race of second type. Suppose P(A) = 0.01, P(B)=0.03,  $P(A \cap B) = 0.002$ . Determine the probability of the following events:

You win on the race at least one of types:

 $P(A \cup B) = P(A) + P(B) - P(A \cap B) = 0.01 + 0.03 - 0.002 = 0.038$  (apply C10)

You win on neither of them:  $P(A \cap B) = P(A \cup B) = 1 - (P(A) + P(B) - P(A \cap B)) = 1 - 0.038 = 0.962$  (apply C4 and C10) You do not win on at least one of them:  $P(\overline{A} \cup \overline{B}) = P(A \cap B) = 1 - P(A \cap B) = 1 - 0.002 = 0.998$  (apply the de Morgan's equality and C4) You win on the first type race but do not win on the second type race:  $P(A \cap B) = P(A) - P(A \cap B) = 0.01 - 0.002 = 0.008$ . (apply C8) You win on the first type race or do not win on the second type race:  $P(A \cup B) = P(A) + P(B) - P(A \cap B) = 0.01 + (1 - 0.03) - (0.01 - 0.002) = 0.978.$  (Apply C10. C4 and C8) You win on both of them or you win on neither of them:  $P((A \cap B) \cup (\overline{A} \cap \overline{B})) = P(A \cap B) + P(\overline{A} \cap \overline{B}) - P(A \cap B \cap \overline{A} \cap \overline{B}) =$ 0.002+0.962-0=0.964. (apply C10 and de Morgan's equality) You win on one of them but not on the other one:  $P((A \setminus B) \cup (B \setminus A)) = P((A \setminus B) + P(B \setminus A) - P((A \setminus B) \cap (B \setminus A)) =$  $P(A) - P(A \cap B) + P(B) - P(A \cap B) = 0.01 - 0.002 + 0.03 - 0.002 = 0.036$  (apply C10)

#### b.4. Classical probability

In this subsection we present the often used classical probability. We prove that it satisfies axioms I), II) and III.).

<u>Definition</u> Let  $\Omega$  be a finite, non empty set, let  $|\Omega| = n$ . Let  $\mathcal{A} = 2^{\Omega}$ , the set of all the subsets of  $\Omega$ . The **classical probability** is defined as follows:  $P(A) := \frac{|A|}{|\Omega|}$ .

<u>Theorem</u> Classical probability satisfies axioms I), II) and III).

<u>Proof</u> First we note that  $\mathcal{A}$  is  $\sigma$  algebra, consequently P maps the elements of a  $\sigma$  algebra to the set of real numbers. Since  $0 \le |A|$  and  $|\Omega| = n$ ,  $P(A) := \frac{|A|}{|\Omega|} \ge 0$  is satisfied, as well.

$$\mathbf{P}(\Omega) := \frac{|\Omega|}{|\Omega|} = 1.$$

Finally, if  $A_i \subset \Omega$ , i = 1, 2, ... with  $A_i \cap A_j = \emptyset$ ,  $i \neq j$ , then  $A_i = \emptyset$  except from finite indices i, as  $\Omega$  has only finite different subsets. If  $A_i \neq \emptyset$  i = 1, 2, ..., k, and  $A_i \cap A_j = \emptyset$   $i \neq j$ , then

$$\begin{vmatrix} \sum_{i=1}^{k} A_i \\ = \sum_{i=1}^{k} |A_i|, \quad \text{therefore} \quad \frac{\left| \bigcup_{i=1}^{k} A_i \right|}{|\Omega|} = \frac{\sum_{i=1}^{k} |A_i|}{|\Omega|}. \quad \text{We can conclude}$$

$$k \quad \left| \bigcup_{i=1}^{k} A_i \right| = \sum_{i=1}^{k} |A_i|, \quad \text{we can conclude}$$

that  $P(\bigcup_{i=1}^{k} A_i) = \frac{|\bigcup_{i=1}^{n} A_i|}{|\Omega|} = \frac{|\sum_{i=1}^{n} A_i|}{|\Omega|} = \sum_{i=1}^{n} P(A_i)$ . If we supplement the events  $A_i$  by empty sets,

neither union nor the sum of the elements of the sets change. This means that axiom III) holds, as well.

Remarks

Probability theory and mathematical statistics- Probability

• In the case of classical probability  $P(\{\omega\}) = \frac{|\{\omega\}|}{|\Omega|} = \frac{1}{n}$ , for any  $\omega \in \Omega$ . This formula

expresses that all outcomes have the same probability. Conversely, if  $P(\{\omega\}) = x$ , for any  $\omega \in \Omega$ ,

then 
$$1 = P(\Omega) = P(\bigcup_{i=1}^{n} \omega_i = n \cdot x$$
, which implies  $x = \frac{1}{n}$ . Furthermore,

 $P(A) = P(\bigcup_{\omega \in A} \omega) = \sum_{\omega \in A} P(\{\omega\}) = \sum_{\omega \in A} \frac{1}{n} = \frac{|A|}{|\Omega|}.$  Consequently, if all the outcomes are equally

probable, we can use the classical probability.

• In many cases, the number of elements of  $\Omega$  and A can be determined by combinatorial methods.

#### **Examples**

E1. Roll once a fair die. Compute the probability that the result is odd, even, prime, can be divided by 3, prime and odd, prime or odd, prime but not odd.

A fair die is one for which each face appears with equal likelihood. The assumption "fair" contains the information that each outcome has the same chance, consequently we can apply classical probability. We usually suppose that the die is fair. If we do not assume it, we will emphasize it.

We note that these latest computations are unnecessary in this very simple example but can be very useful in complicated examples.

E2. Roll twice a fair die. Compute the probability of the following events: there is no six between the rolls, there is at least one six between the rolls, there is one six between the rolls, the sum of the rolls is 5, the difference of the rolls is 4, both rolls are different.

 $\Omega = \{(i, j): 1 \le i \le 6, 1 \le j \le 6, i, jint egers\}$ . The outcome (i,j) can be interpreted as the result of the first roll and the result of the second roll. For example (1,1) denotes the outcome, when the first roll is 1, and the second roll is also 1. (3,1) denotes the outcome that the first roll is 3, the second one is 1. (1,3) means that the first roll is 1, and the second roll is 3, which differs from (3,1). If the die is fair, then (i,j) has the same probability as another pair, whatever are the values of i and j (integers between 1 and 6). Consequently, each outcome has equal probability.  $|\Omega| = 6 \cdot 6$ .

A=there is no "six" among the rolls = 
$$\{(1,1), (1,2), \dots, (1,5), (2,1), \dots, (2,5), \dots, (5,1), (5,2), \dots, (5,5)\}$$

$$|\mathbf{A}| = 5 \cdot 5 = 25, \ \mathbf{P}(\mathbf{A}) = \frac{25}{36}$$

B= there is at least one "six" between the rolls

$$= \{(1,6), (2,6), (3,6), (4,6), (5,6), (6,1), (6,2), (6,3), (6,4), (6,5), (6,6)\}. |B| = 11, P(B) = \frac{11}{36}.$$

Another way for solving this exercise if we realize that B = A. Therefore,  $P(B) = 1 - P(A) = 1 - \frac{25}{36} = \frac{11}{36}$ .

C= there is one "six" between the rolls

$$\{(1,6), (2,6), (3,6), (4,6), (5,6), (6,1), (6,2), (6,3), (6,4), (6,5)\}$$
.  $|C| = 10, P(C) = \frac{10}{36} = 0.278$ .  
D=the sum of the rolls is  $5 = \{(1,4), (2,3), (3,2), \{4,1\}\}$ .  $|D| = 4, P(D) = \frac{4}{36} = \frac{1}{9} = 0.111$ .

E=the difference between the two rolls is  $4 = \{(1,5), (2,6), (6,2), (5,1)\}$ . |E| = 4,  $P(E) = \frac{4}{36} = 0.111$ .

F=the results of the rolls are different = {(1,2), (2,1),...,(6,5), (5,6)}. |F| = 30,  $P(F) = \frac{30}{36} = 0.833$ .

Roughly spoken, the key of the solution is that we are able to list all the elements of the events and we can count them on the finger.

Of course, if the number of possible outcomes is large, this way is impracticable.

E3. Roll a fair die repeatedly five times. Compute the probability of the following events: there is no "six" among the rolls, there is at least one "six" among the rolls, the there is one "six" among the rolls, all the rolls are different, all the rolls are different and there is at least one "six" among the rolls, there is at least one "six" or all the rolls are different, there is at least one "six" and there are equal rolls.

 $\Omega = \{(i_1, i_2, i_3, i_4, i_5): 1 \le i_j \le 6, \text{ integers, } j = 1, 2, 3, 4, 5\}. \text{ Now } i_1 \text{ denotes the result of the first roll, } i_j \text{ denotes the result of the jth roll. If the die is fair, then all the outcomes are equally likely. } |\Omega| = 6 \cdot 6 \cdot 6 \cdot 6 = 6^5 = 7776.$ 

A=there is no ", six" among the rolls =  $\{(i_1, i_2, i_3, i_4, i_5): 1 \le i_j \le 5, \text{ int egers, } j = 1, 2, 3, 4, 5\}$ .

$$|\mathbf{A}| = 5^5 = 3125. \ \mathbf{P}(\mathbf{A}) = \frac{3125}{7776} = 0.402.$$

B=there is at least one "six" among the rolls =  $\overline{A}$ . P(B) = 1 - P(A) = 1 - 0.402 = 0.598. C=there is exactly one "six" among the rolls = {(1,1,1,1,6), .(1,1,1,2,6), ..., (6,5,5,5,5)}.

$$|C| = {5 \choose 1} \cdot 1 \cdot 5 \cdot 5 \cdot 5 \cdot 5 = 3125. P(C) = \frac{3125}{7776} = 0.402$$

D=all the rolls are different = {(1,2,3,4,5), (1,2,3,4,6),...,(6,5,4,3,2)}. |D| =  $6 \cdot 5 \cdot 4 \cdot 3 \cdot 2 = 720$ , P(D) =  $\frac{720}{7776} = 0.093$ .

E= all the rolls are different and there is at least one "six" among the rolls =  $D \cap \overline{A} = D \setminus A$ . P(E) = P(D) – P(A  $\cap$  D). As we need the value of P(D  $\cap$  A), we have to compute it now. The set D  $\cap$  A contains all the elements of  $\Omega$  in which there is no "six" and the rolls are different.

$$|A \cap D| = 5 \cdot 4 \cdot 3 \cdot 2 \cdot 1 = 120,$$
  $P(A \cap D) = \frac{120}{7776} = 0.015.$  Finally,

$$P(E) = P(D) - P(A \cap D) = 0.093 - 0.015 = 0.078.$$

F= there is at least one "six" or all the rolls are different =  $\overline{A} \cup D$ . Applying  $P(\overline{A} \cup D) = P(\overline{A}) + P(D) - P(\overline{A} \cap D)$  we get  $P(F) = P(\overline{A} \cup D) = 1 - P(A) + P(D) - (P(D) - P(D \cap A)) = 1 - 0.402 + 0.093 - 0.015 = 0.676$ . G=there is at least one "six" and there are equal rolls=  $\overline{A} \cap \overline{D} = \overline{A \cup D}$ .  $P(G) = P(\overline{A \cup D}) = 1 - P(A \cup D) = 1 - (P(A) + P(D) - P(A \cap D)) =$ = 1 - (0.402 + 0.093 - 0.015) = 1 - 0.480 = 0.502.

E4. Choose two numbers without replacement from a box containing the integer numbers 1,2,3,4,5,6,7,8,9. Compute the probability that both of them is odd, both of them is even, the sum of them is at least 15, one of them is less then 4 and the other is greater then 7, the difference of the numbers is 3.

If we take into consideration the order of drawn numbers, then the possible outcomes are  $(i_1, i_2)$   $i_1 \neq i_2$ ,  $1 \leq i_1 \leq 9$ ,  $1 \leq i_2 \leq 9$ ,  $i_1, i_2$  are integers.  $\Omega = \{(i_1, i_2): i_1 \neq i_2, 1 \leq i_1 \leq 9, 1 \leq i_2 \leq 9, \text{ int egers}\}$ .  $|\Omega| = 9 \cdot 8 = 72$ . If we draw each number being in the box with equal probability, all possible outcomes have the same chance. Consequently, classical probability can be applied. Now contract those outcomes which differ only in the order. For example, (1, 2) and (2, 1) can be contracted to  $\{1, 2\}$ .

Actually,  $\Omega^* = \{\{i_1, i_2\}: 1 \le i_1 < i_2 \le 9, \text{ integers}\}$ . As two possible outcomes were contracted, consequently each possible outcome (without order) has equal chance in this model, as well. Roughly spoken, one can decide whether he wants to take into consideration the order or no,

classical probability can be applied in both cases.  $\Omega^* = \begin{pmatrix} 9 \\ 2 \end{pmatrix} = \frac{9!}{2! \cdot 7!} = \frac{9 \cdot 8}{2} = 36$ .

Consider the event: both of them are odd:

If we take into consideration the order, then

 $A = \{((2,4), (2,6), (2,8), (4,2), (4,6), (4,8), (6,2), (6,4), (6,8), (8,2), (8,4), (8,6)\}$ 

$$|\mathbf{A}| = 4 \cdot 3 = 12$$
,  $\mathbf{P}(\mathbf{A}) = \frac{12}{72} = 0.167$ .

If we do not take into consideration the order, then

$$A^* = \{\{2,4\}, \{2,6\}, \{2,8\}, \{4,6\}, \{4,8\}, \{6,8\}\} \cdot |A^*| = \binom{4}{2} = 6, P(A^*) = \frac{6}{36} = 0.167.$$

Finally, we can realize that we get the same result in both cases. Both of them are even:

$$B = \{(1,3), (1,5), (1,7), (1,9), (3,1), \dots, (9,7)\}, |B| = 5 \cdot 4 = 20, P(B) = \frac{20}{72} = 0.278.$$
  
$$B^* = \{\{1,3\}, \{1,5\}, \dots, \{7,9\}\}, |B^*| = \binom{5}{2} = 10, P(B^*) = \frac{10}{36} = 0.278.$$

The sum of them is at least 15:

$$C = \{(6,9), (7,8), (7,9), (8,7), (8,9), (9,6), (9,7), (9,8)\}, |C| = 8, P(C) = \frac{8}{72} = 0.111.$$

$$C^* = \{\{6,9\}, \{7,8\}, \{7,9\}, \{8,9\}\}, |C^*| = 4, P(C^*) = \frac{4}{36} = 0.111.$$
One of them is less than 4 and the other one is greater than 7:  

$$D = \{(1,8), (8,1), (1,9), (9,1), (2,8), (8,2), ((2,9), (9,2), (3,8), (8,3), (3,9), (9,3)\}, |D| = 12 = 2 \cdot 3 \cdot 2,$$

$$P(D) = \frac{12}{72} = 0.167.$$

$$D^* = \{\{i_1, i_2\}: 1 \le i_1 \le 3, 8 \le i_2 \le 9, \text{ int egers}\}, |D^*| = 3 \cdot 2 = 6, P(D^*) = \frac{6}{36} = 0.167.$$
The difference of the numbers is 3:  

$$E = \{(1,4), (4,1), (2,5), (5,2), (3,6), (6,3), (4,7), (7,4), (5,8), (8,5), (9,6), (6,9)\}, |E| = 12,$$

$$P(E) = \frac{12}{72} = 0.167.$$

$$E^* = \{\{1,4\}, \{2,5\}, \{3,6\}, \{4,7\}, \{5,8\}, \{6,9\}\}, |E^*| = 6, P(E^*) = \frac{6}{36} = 0.167.$$

E5. Pick 4 cards without replacement from a pack of French cards containing 13 clubs  $(\bigstar)$ , diamonds  $(\bigstar)$ , hearts  $(\blacktriangledown)$  and spades  $(\bigstar)$ . Compute the probability that there is at least one of spades or there is at least one of hearts, there is no spade or there is no heart, there is at least one of spades but there is no heart, there are 2 spades, 1 hearts and 1 other, there are more hearts than spades.

If we do not take into consideration the order of the picked cards, then  

$$\Omega^* = \{\{ ace of hearts, 7 of diamonds, king of spades, 8 of spades, ...., \}, |\Omega^*| = {52 \\ 4} = 270725.$$

Actually the appropriate possible outcomes can not be listed and it is difficult to count them. The operations on the events and the consequences of axioms help us to answer the questions. Let X \* be the event that there is no spade, Y \* the event that there is no heart among the

picked cards. Now,  $|X^*| = {39 \choose 4} = 9139 = |Y^*|$ ,  $P(X^*) = P(Y^*) = \frac{9139}{270725} = 0.304$ .

A= there is at least one of spades or there is at least one of hearts:

 $A = X^* \cup Y^* = X^* \cap Y^*$ , consequently  $P(A) = 1 - P(X^* \cap Y^*)$ . We need the value of  $P(X^* \cap Y^*)$ .  $X^* \cap Y^*$  means that there is no spade and at the same time there is no heart,

therefore all of the picked cards are diamonds or clubs.  $|X * \cap Y *| = \begin{pmatrix} 26 \\ 4 \end{pmatrix} = 14950$ ,

$$P(X^* \cap Y^*) = \frac{14950}{270725} = 0.055, P(A) = 1 - 0.055 = 0.945.$$

B=there is no spade or there is no heart:

$$B = X * \cup Y *$$

 $P(B) = P(X * \cup Y*) = (P(X*) + P(Y*) - P(X* \cap Y*)) = 0.304 + 0.304 - 0.055 = 0.553.$ There is at least one of spades but there is no heart:  $C = \overline{X*} \cap Y* = Y* \setminus X*, \ P(C) = P(Y*) - P(X* \cap Y*) = 0.304 - 0.055 = 0.249.$ D = there are 2 spades, 1 hearts and 1 other card.  $|D| = {13 \choose 2} \cdot {13 \choose 1} {26 \choose 1} = 26364, \ P(D) = \frac{26364}{270725} = 0.097.$ 

E=there are more spade than hearts = there is at least one of spades and there is no heart or there are 2 spades and 0 or 1 hearts or there are 3 spades and 0 or 1 heart or each card is of spades. These events are mutually exclusive therefore their probabilities can be summed up.

Probability theory and mathematical statistics- Probability

$$P(E) = P(C) + \frac{\binom{13}{2} \cdot \binom{13}{\binom{26}{2}} + \binom{13}{\binom{12}{2}}\binom{26}{1}}{\binom{52}{4}} + \frac{\binom{13}{\binom{26}{1}}}{\binom{52}{4}} + \frac{\binom{13}{\binom{26}{1}} + \binom{13}{\binom{26}{1}}\binom{26}{\binom{12}{1}} + \frac{\binom{13}{\binom{26}{1}}}{\binom{52}{4}} + \frac{\binom{13}{\binom{4}{1}}}{\binom{52}{4}}.$$

The reader is kindly asked to compute it numerically.

## b.5. Geometrical probability

In this subsection we deal with geometrical probability. It is important to understand the concept of continuous random variable.

<u>Definition</u> Let  $\Omega$  be a subset of R, R<sup>2</sup>, R<sup>3</sup> or R<sup>n</sup>,  $4 \le n$ , and let  $\mu$  be the usual measure on the line, plane, space,... Let us assume that  $\mu(\Omega) \ne 0$ , and  $\mu(\Omega) \ne \infty$ . Let  $\mathcal{A}$  be those subsets of

Ω that have measure. Now **geometrical probability** is defined by  $P(A) := \frac{\mu(A)}{\mu(\Omega)}$ 

<u>Remarks</u>

- Axioms I) hold as  $0 \le \mu(A)$ , and  $0 \le \mu(\Omega)$ .
- Axiom II) is the consequence of the definition  $P(\Omega) := \frac{\mu(\Omega)}{\mu(\Omega)} = 1$ .
- Axiom III) follows from the measure-property of  $\mu$ . Measures hold that  $\mu(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mu(A_i)$  supposing  $A_i \cap A_j = \emptyset$ ,  $i \neq j$ . Therefore, under the same assumption

$$P(\bigcup_{i=1}^{\infty} A_i) = \frac{\mu(\bigcup_{i=1}^{\infty} A_i)}{\mu(\Omega)} = \frac{\sum_{i=1}^{\infty} \mu(A_i)}{\mu(\Omega)} = \sum_{i=1}^{\infty} \frac{\mu(A_i)}{\mu(\Omega)} = \sum_{i=1}^{\infty} P(A_i).$$

• Usual measure on R,  $R^2$ ,  $R^3$  is the length, area, volume, respectively. The concept of them can be generalized. For further knowledge on measures can be found in the book of Halmos.

• Definition  $P(A) = \frac{\mu(A)}{\mu(\Omega)}$  expresses that the probability of an event is proportional to its

measure. In the case of classical probability the "measure" is the number of the elements of  $\Omega$ . Actually the number of the elements of  $\Omega$  can be infinity.

• If  $\mu(\Omega) = 1$ , then  $P(A) = \mu(A)$ . The consequences of axioms are frequently used properties of measure. See for example C8 and C9.

• The proof of the fact that the set of those subsets of  $\Omega$  that have measure is a  $\sigma$  algebra requires many mathematical knowledge, we do not deal with it actually.

• Random numbers of computers are numbers chosen from interval [0,1] by geometrical probability approximately. That is the probability that the number is situated in a subset of [0,1] is proportional to the length of the subset. As the length of the interval [0,1] equals 1, probability coincides with the length of the set itself.

#### Examples

E1. Choose a point from the interval  $[0, \pi]$  by the geometrical probability. Compute the probability that the second digital of the point equals 4.

 $\Omega = [0, \pi]$ , lenght is abbreviated by  $\mu \cdot \mu(\Omega) = \pi$ .

**Probability theory and mathematical statistics– Probability** 

A= the second digital is 4 =  $[0.04, 0.05) \cup [0.14, 0.15) \cup ... \cup [3.14, \pi]$ .  $\mu(A) = 31 \cdot 0.01 + \pi - 3.14 = 0.3116$ ,  $P(A) = \frac{\mu(A)}{\pi} = 0.0992$ .

E2. Fire on a circle with radius R. The probability that the hit is situated in a subset of the circle is proportional to the area of the subset. Compute the probability that we have 10, 9 scores.

 $\Omega$  is the circle with radius R. area( $\Omega$ ) =  $\mu(\Omega)$  = R<sup>2</sup> ·  $\pi$ .Let A be the event that the hit is 10 scores. 10 scores means that the hit is inside the inner circle lined black, which is a circle with

radius  $\frac{R}{10}$ . Consequently,  $\mu(A) = \left(\frac{R}{10}\right)^2 \pi$ ,  $P(A) = \frac{\left(\frac{R}{10}\right)^2 \pi}{R^2 \pi} = \frac{1}{100}$ .



Fig.b.4 Events A and B

Let B be the event that the hit is 9 scores. It means that the hit is not in the inner part but in the following segment. As the hits are between concentric circles,  $\mu(B) = \left(\frac{2R}{10}\right)^2 \pi - \left(\frac{R}{10}\right)^2 \pi = \frac{3R^2}{100} \pi$ . Consequently, P(B) =  $\frac{3}{100}$ .

Compute the probability that the distance of the hit and the centre of the circle equals  $\frac{R}{2}$ . Let C be the event that the distance between the hit and centre of the circle equals  $\frac{R}{2}$ . The points whose distance from the centre equals  $\frac{R}{2}$  are situated on the curve of the circle of  $\frac{R}{2}$  radius drawn by red line in Fig.b.5.The area of the curve is zero, as it cab be covered by the section which is the difference of the open circle with radius  $\frac{R}{2} + \Delta R$ , and the circle with radius  $\frac{R}{2}$ , for any positive value of  $\Delta R$ .



Fig.b.5 Event 
$$C_{R/2}$$
 and event  $\left\{ \omega : \frac{R}{2} \le d(\omega, 0) < \frac{R}{2} + \Delta R \right\}$ 

Consequently,  $\mu(\mathbf{C}) \leq \left(\frac{\mathbf{R}}{2} + \Delta \mathbf{R}\right)^2 \cdot \pi - \left(\frac{\mathbf{R}}{2}\right)^2 \cdot \pi = \left(\mathbf{R} \cdot \Delta \mathbf{R} + (\Delta \mathbf{R})^2\right)\pi$ , which tends to zero if

 $\Delta R$  tends to zero. That implies  $\mu(C) = 0$ . Therefore,  $P(C) = \frac{\mu(C)}{R^2 \pi} = 0$ .

We draw the attention that despite of  $C \neq \emptyset$ , P(C) = 0 holds. Moreover, if we use the notation

 $C_x = \{Q: d(Q, O) = x\}, \text{ then } P(C_x) = 0, \text{ for any value of } 0 \le x \le R \text{ . Now } \Omega = \bigcup_{0 \le x \le R} C_x \text{ holds.}$ 

Moreover, if  $x \neq y$ , then  $C_x \cap C_y = \emptyset$ .  $P(\Omega) = 1$  but  $P(\Omega) \neq \sum P(C_x)$ . The reason of this

paradox phenomenon is that the set  $\{x: 0 \le x \le R\}$  is not finite and is not countable. This is a very important thing to understand the concept of continuous random variables.

E3. Choose two numbers independently of each other from the interval [-1,1] by geometrical probability. Compute the probability that the sum of the numbers is between 0.5 and 1.5.

To choose two numbers from the interval [-1,1] by geometrical probability independently of each others means to choose one point from Cartesian coordinate system, namely from the square [-1,1]x[-1,1] by geometrical probability. If the first number equals x, the second number equals y, then let the two dimensional point be denoted by Q(x, y). Roughly spoken, let the first number be put on the x axis, the second number be put on y axis. Now  $\Omega = [-1,1]x[-1,1]$ ,  $\mu(\Omega) = 4$ . Let A be the event that the sum of the numbers is between 0.5 and 1.5. We seek the points Q(x, y) for which 0.5 < x + y < 1.5.



Fig.b.6. The set of all possible outcomes  $\Omega$  and the set of appropriate points

These points are in the section between the red straight lines given by x + y = 0.5 and x + y = 1.5 presented in Fig.b.6.

$$\mu(A) = \frac{\left(\frac{3}{2}\right)^2}{2} - \frac{\left(\frac{1}{2}\right)^2}{2} = 1, \ P(A) = \frac{1}{4}.$$

Compute the probability that the sum of the numbers equals 1.

Let B be the event that the sum of numbers equals 1. The points of B are the points of the straight line given by x + y = 1 (see Fig.b.7)



Fig.b.7. The set of points given by the equation x + y = 1

 $\mu(B) = 0$ , consequently, P(B) = 0.

E4. Choose two numbers independently from each other by geometrical probability from the interval [0,1]. Compute the probability that the square of the second number is less than the first one or the square of the first one is greater than the second one.  $\Omega = [0,1]x[0,1], \ \mu(\Omega) = 1$ . We seek those points Q(x, y) for which  $y < x^2$  or  $x < y^2$ , that is  $\sqrt{x} < y$ . The appropriate points are bellow the curve given by  $y = x^2$ , furthermore above the



Fig.b.8. Those points for which  $y < x^2$  or  $x < y^2$  holds

If A is the set of appropriate points, then

$$\mu(A) = \int_{0}^{1} x^{2} dx + \int_{0}^{1} \left(1 - \sqrt{x}\right) dx = \left[\frac{x^{3}}{3}\right]_{0}^{1} + \left[x - \frac{\sqrt{x^{3}}}{\frac{3}{2}}\right]_{0}^{1} = \frac{1}{3} + 1 - \frac{2}{3} = \frac{2}{3} = 0.667 \text{ and}$$
$$P(A) = \frac{0.667}{1} = 0.667.$$

E5. Use the random number generator of your computer and generate N=1000, N=10000, N=100000, N=1000000 random numbers. Divide the interval [0,1] into 10 equal parts, and count the ratio of the random numbers situated in the sub-intervals  $\left(\frac{i}{10}, \frac{i+1}{10}\right]$ , i=0,1,2,...,9. Draw the figures!

Relative frequencies of random numbers being in the above intervals are shown in Figs.b.9. b.10. b11. and b.12. for the simulated random numbers N=1000, 100000, 1000000, 1000000, respectively. Pictures shows that increasing the number of simulations, the relative frequencies become more and more similar, the random numbers are situated more and more uniformly. If the probability of being in the interval is really  $\frac{1}{10}$ , then relative frequencies are closer and closer to this probability.



Figure b.9. Relative frequencies of random numbers in case of N=1000



Figure b.10 Relative frequencies of random numbers in case of N=10000



Figure b.11. Relative frequencies of random numbers in case of N=100000



Figure b.12. Relative frequencies of random numbers in case of N=1000000

E6. Approximate the probability of event A in E3) by relative frequency of the event A applying N=1000, 10000, 100000, 1000000 simulations. Give the difference between the approximate values and the exact probability.

First we mention that if a number is chosen from [0,1] by the geometrical probability, then its double is chosen from [0,2] by geometrical probability and the double and minus 1 is chosen from the interval [-1,1] by geometrical probability.

The relative frequencies of A and their differences from the exact probability 0.25 can be seen Table b.2. One can realize that if the number of simulations increases, the difference decreases.

	N=1000	N=10000	N=100000	N=1000000
Relative	0.2670	0.2584	0.2517	0.2502
frequency				
Difference	0.0170	0.0084	0.0017	0.0002

Table b.2. Relative frequencies of the event and their differences from the exact probability

The relative frequencies of the event that the sum is in  $\left(-2+\frac{i}{5},-2+\frac{i+1}{5}\right]$ , i=0,...,19 can be seen in Figs.b.13,b.14. One can see that the shapes of the graphs are getting similar to a roof.





Fig.b.13. The relative frequencies of the event that the sum is in  $\left(-2+\frac{i}{5},-2+\frac{i+1}{5}\right]$ , i = 0,...,19 for N=1000 and 10000



Fig.b.14. The relative frequencies of the event that the sum is in  $\left(-2+\frac{i}{5}, -2+\frac{i+1}{5}\right]$ , i = 0, ..., 19 for N=10000 and 100000

# c. Conditional probability and independence

#### The aim of this chapter

The aim of this chapter is to get acquainted with the concept of conditional probability and its properties. We present the possibilities for computing non-conditional probabilities applying conditional ones. We also define independence of events.

30

## Preliminary knowledge

Properties of probability.

## Content

- c.1. Conditional probability.
- c.2. Theorem of total probability and Bayes' theorem.
- c.3. Independence of events

31

## c.1. Conditional probability

In many practical cases we have some information. We would like to know the probability of an event and we know something. This "knowledge" has effect on the probability of the event; it may increase or decrease the probability of its occurrence.

What is the essence of the conditional probability? How can we express that we have some information?

Let  $\Omega$  be the set of possible outcomes,  $\mathcal{A}$  the set of events, let P be the probability. Let  $A, B \in \mathcal{A}$ . If we know that B occurs (this is our extra information), then the outcome which is the result of our experiment is the element of B. Our word is restricted to B. If A occurs, then the outcome is common element of A and B, therefore it is in  $A \cap B$ . The probability of the intersection should be compared to the "measure" of the condition, i.e. P(B). Naturally, 0 < P(B) has to be satisfied.

<u>Definition</u> The **conditional probability of event** A **given** B is defined as  $P(A | B) := \frac{P(A \cap B)}{P(B)}$ , if 0 < P(B).

Remarks

• Notice that definition of conditional probability implies the form  $P(A \cap B) = P(A | B) \cdot P(B)$ , called multiplicative formulae.

• The generalization of the above form is the following statement: if  $0 < P(A_1 \cap ... \cap A_{n-1} \cap A_n)$  holds, then

 $P(A_1 \cap A_2 \cap ... \cap A_n) = P(A_1) \cdot P(A_2 | A_1) \cdot P(A_3 | A_1 \cap A_2) \cdot ... \cdot P(A_n | A_1 \cap ... \cap A_{n-1}).$ It can be easily seen if we notice that  $P(A_1) \cdot P(A_2 | A_1) = P(A_1 \cap A_2)$ ,

 $P(A_3 | A_1 \cap A_2) \cdot P(A_1 \cap A_2) = P(A_1 \cap A_2 \cap A_3)$ , and finally,

$$P(A_{n} | A_{1} \cap ... \cap A_{n-1}) \cdot P(A_{1} \cap ... \cap A_{n-1}) = P(A_{1} \cap ... \cap A_{n-1} \cap A_{n}).$$

• If we apply classical probability, then

$$P(A | B) = \frac{P(A \cap B)}{P(B)} = \frac{\frac{|A \cap B|}{|\Omega|}}{\frac{|B|}{|\Omega|}} = \frac{|A \cap B|}{|B|}.$$
 Roughly spoken: there are some elements in B,

these are our "new (restricted) world". Some of them are in A, as well. The ratio of the number of the elements of A in our "new world" and the number of the elements of the "new world" is the conditional probability of A.

<u>Theorem</u> Let the event B be fixed with 0 < P(B). The conditional probability given B satisfies the axioms of probability I), II), III).

$$\frac{\text{Proof:}}{\text{I}} \quad 0 \le P(A \mid B), \text{ as } 0 \le P(A \cap B), \text{ and } 0 < P(B).$$

$$\text{II} \quad P(\Omega \mid B) = 1, \text{ as } P(\Omega \mid B) \coloneqq \frac{P(\Omega \cap B)}{P(B)} = \frac{P(B)}{P(B)} = 1.$$

$$\text{III} \quad \text{If } A_i \in \mathcal{A}, i = 1, 2, 3, \dots A_i \cap A_j = \emptyset, i \ne j, \text{ then } P(\bigcup_{i=1}^{\infty} A_i \mid B) = \sum_{i=1}^{\infty} P(A_i \mid B).$$

The proof can be performed by the following way: notice that if  $A_i \cap A_j = \emptyset$ , then  $(A_i \cap B) \cap (A_i \cap B) = \emptyset$  hold as well. Now

$$P(\bigcup_{i=1}^{\infty}A_{i} \mid B) = \frac{P\left(\left(\bigcup_{i=1}^{\infty}A_{i}\right) \cap B\right)}{P(B)} = \frac{P\left(\bigcup_{i=1}^{\infty}\left(A_{i} \cap B\right)\right)}{P(B)} = \frac{\sum_{i=1}^{\infty}P(A_{i} \cap B)}{P(B)} = \sum_{i=1}^{\infty}\frac{P(A_{i} \cap B)}{P(B)} = \sum_{i=1}^{\infty}P(A_{i} \mid B).$$

This theorem assures that we can conclude all of the consequences of axioms. We can state the following consequences corresponding to C1,..., C12 without any further proof.

- $P(\emptyset | B) = 0$ .
- If  $A_i \in \mathcal{A}, i = 1, 2, ..., n$  for which  $A_i \cap A_j = \emptyset$ ,  $i \neq j$ , then  $P(\bigcup_{i=1}^n A_i \mid B) = \sum_{i=1}^n P(A_i \mid B)$ .
- If  $C \subset A$ , then  $P(C | B) \leq P(A | B)$
- $P(A|B) \leq 1$ .
- $P(\overline{A}|B) = 1 P(A|B)$ .
- $P(A \setminus C \mid B) = P(A \mid B P(A \cap C \mid B))$ .
- $P(A \cup C | B) = P(A | B) + P(C | B) P(A \cap C | B)$ .
- $P(A \cup C | B) \le P(A | B) + P(C | B)).$
- $P(A \cup C \cup D | B) = P(A | B) + P(C | B) + P(D | B) -$

 $P(A \cap C \,|\, B) - P(D \cap C \,|\, B) - P(A \cap D \,|\, B) + P(A \cap C \cap D \,|\, B) \,.$ 

• 
$$P\left(\bigcup_{i=1}^{n} A_i \mid B\right) = \sum_{i=1}^{n} P(A_i \mid B) - \sum_{1 \le i < j \le n} P(A_i \cap A_j \mid B) +$$

These formulas help us to compute conditional probabilities of "composite" events using conditional probabilities of "simple" events.

#### Examples

E1. Roll twice a fair die. Given that there is at least one "six" among the results, compute the probability that the difference of the result equals 3.

Let A be the event that the difference is 3, B the event that there is at least one "six".

The first question is the conditional probability P(B|A). By definition,  $P(B|A) = \frac{P(A \cap B)}{P(A)}$ .

$$A \cap B = \{(6,3), (3,6)\}, P(A \cap B) = \frac{2}{36},$$
  

$$A = \{(1,6), (2,6), (3,6), (4,6), (5,6), (6,6), (6,1), (6,2), (6,3), (6,4), (6,5)\}, P(A) = \frac{11}{36}.$$

 $P(B|A) = \frac{P(A \cap B)}{P(A)} = \frac{36}{\frac{11}{36}} = \frac{2}{11}$ . Roughly spoken, our world is restricted to A, it contains 11

elements. Two of them have difference 3. If all possible elements are equally probable in the entire set  $\Omega$ , then all possible outcomes are equally probable in A, as well. Consequently, the conditional probability is  $\frac{2}{11}$ .

Given that the difference of the results is 3, compute the probability that there is at least one "six".

The second question is the conditional probability 
$$P(A | B)$$
. By definition,  
 $P(A | B) = \frac{P(A \cap B)}{P(B)}$ .  $B = \{(1,4), (4,1), (2,5), (5,2), (3,6), (6,3)\}, P(B) = \frac{6}{36}$ .  
Consequently,  $P(A | B) = \frac{P(A \cap B)}{P(B)} = \frac{\frac{2}{36}}{\frac{6}{36}} = \frac{1}{3}$ .

Roughly spoken, our world is restricted to the set B. Two elements are appropriate among them. If all possible elements are equally probable in the entire set  $\Omega$ , then all possible outcomes are equally probable in B, as well. Consequently the classical probability can be

applied, which concludes that the conditional probability equals  $\frac{2}{6} = \frac{1}{3}$ .

E2. Roll a fair die 0 times, repeatedly. Given that there is at least one "six", compute the probability that there is at least one "one".

Let A be the event that there is no "six" among the results, and B the event that there is no "one" among the results. The question is the conditional probability  $P(\overline{B} | \overline{A})$ .

$$P(\overline{B} \mid \overline{A}) = \frac{P(A \cap B)}{P(\overline{A})} = \frac{P(A \cup B)}{P(\overline{A})} = \frac{1 - P(A \cup B)}{1 - P(A)} = \frac{1 - (P(A) + P(B) - P(A \cap B))}{1 - P(A)}$$

Now we can see that we have to compute the values P(A), P(B) and  $P(A \cap B)$ .

$$P(A) = \frac{5^{10}}{6^{10}} = 0.161, \ P(B) = \frac{5^{10}}{6^{10}} = 0.161, \ P(A \cap B) = \frac{4^{10}}{6^{10}} = 0.017.$$

$$P(\overline{B} | \overline{A}) = \frac{1 - (P(A) + P(B) - P(A \cap B))}{1 - P(A)} = \frac{1 - (0.161 + 0.161 - 0.017)}{1 - 0.161} = \frac{0.695}{0.839} = 0.828.$$

E3. Choose two numbers independently in the interval [0,1] by geometrical probability. Given that the difference of the numbers is less than 0.3, compute the probability that the sum of the numbers is at least 1.5.

Let A be the event that the difference of the numbers is less than 0.3. The appropriate points in the square [0,1]x[0,1] are situated between the straight lines given by the equation x - y = 0.3 and y - x = 0.3. It is easy to see that  $P(A) = 1 - 0.7^2 = 0.51$ . A  $\cap$  B contains those points of A which are above the straight line given by x+y=1.5. This part is denoted by horizontal lines in Fig.c.1. The cross-points are  $Q_1(0.6, 0.9)$  and  $Q_2(0.9, 0.6)$ . The area of the appropriate points

is 
$$\mu(A) = \left(\sqrt{0.3^2 + 0.3^2}\right) \cdot \left(\sqrt{0.1^2 + 0.1^2}\right) + \frac{0.3^2}{2} = 0.06 + 0.045 = 0.105, \ P(A \cap B) = 0.105.$$



Fig.c.1. The points satisfying conditions  $1.5 \le x + y$  and |x - y| < 0.3

$$P(B | A) = \frac{P(A \cap B)}{P(A)} = \frac{0.105}{0.51} = 0.206$$

E4. Order the numbers of the set  $\{1,2,3,4,...,10\}$  and suppose that all arrangements are equally probable. Given that the number "1" is not on its proper place, compute the probability that the number 10 is on its proper place.

Let  $A_i$  the event that the number "i" is in its proper place. The question is the conditional probability  $P(A_{10} | \overline{A_1})$ . Now

$$P(A_{10} | \overline{A_1}) = \frac{P(A_{10} \cap \overline{A_1})}{P(\overline{A_1})} = \frac{P(A_{10} \setminus A_1)}{P(\overline{A_1})} = \frac{P(A_{10}) - P(A_{10} \cap A_1)}{1 - P(A_1)}.$$

We can see that we need the values  $P(A_1)$ ,  $P(A_{10})$  and  $P(A_{10} \cap A_1)$ .  $\Omega = \{(i_1, i_2, ..., i_{10}): 1 \le i_j \le 10, \text{ int egers}, j = 1, 2, ..., 10, i_j \ne i_k \text{ if } j \ne k\}, \text{ for example}$   $(1, 2, 3, 4, 5, 6, 7, 8, 9, 10), (5, 2, 3, 4, 7, 9, 10, 8, 1, 7) \text{ and so on. } |\Omega| = 10! = 3628800.$   $A_1 = \{(1, i_2, ..., i_{10}): 2 \le i_j \le 10, \text{ int egers}, j = 2, ..., 10, i_j \ne i_k \text{ if } j \ne k\}, |A_1| = 9!, P(A_1) = \frac{9!}{10!} = 0.1.$ Similarly,  $P(A_{10}) = \frac{9!}{10!} = 0.1.$  $A_1 \cap A_{10} = \{(1, i_2, ..., 10): 1 \le i_j \le 10, \text{ int egers}, j = 2, ..., 9, i_j \ne i_k \text{ if } j \ne k\}, |A_1 \cap A_{10}| = 8!$  as numbers 1 and 10 have to be on their proper places,  $P(A_1 \cap A_{10}) = \frac{8!}{10!} = \frac{1}{10!} = 0.011.$ 

Therefore, 
$$P(A_{10} | \overline{A_1}) = \frac{P(A_{10}) - P(A_{10} \cap A_1)}{1 - P(A_1)} = \frac{\frac{1}{10} - \frac{1}{10 \cdot 9}}{\frac{9}{10}} = \frac{\frac{8}{10 \cdot 9}}{\frac{9}{10}} = \frac{8}{81} = 0.099.$$

E5. Order the numbers of the set  $\{1,2,3,4,...,10\}$  and suppose that all arrangements are equally probable. Given that the number "1" is not on its proper place, compute the probability that the number "10" or the number "5" is on its proper place.

Let  $A_i$  the event that the number "i" is on its proper place. The question is the conditional probability  $P(A_{10} \cup A_5 | \overline{A_1})$ . Recall the properties of the conditional probability, namely  $P(A_{10} \cup A_5 | \overline{A_1}) = P(A_{10} | \overline{A_1}) + P(A_5 | \overline{A_1}) - P(A_{10} \cap A_5 | \overline{A_1})$ .

We can realize that the conditional probabilities  $P(A_{10} | \overline{A_1})$ ,  $P(A_5 | \overline{A_1})$  and  $P(A_{10} \cap A_5 | \overline{A_1})$  are needed.  $P(A_{10} | \overline{A_1})$  was computed in the previous example, and  $P(A_5 | \overline{A_1})$  can be computed in the same way.

$$P(A_{10} \cap A_5 | \overline{A_1}) = \frac{P(A_{10} \cap A_5 \cap A_1)}{P(\overline{A_1})} = \frac{P(A_{10} \cap A_5) - P(A_{10} \cap A_5 \cap A_1)}{1 - P(A_1)}.$$
  
$$A_{10} \cap A_5 \cap A_1 = \begin{cases} (1, i_2, i_3, i_4, 5, i_6, i_7, i_8, i_9, 10) : 2 \le i_j \le 4, 6 \le i_j \le 9, \\ \text{int egers, } j = 2, 3, 4, 6, 7, 8, 9, i_j \ne i_k \text{ if } j \ne k \end{cases}$$

 $|A_{10} \cap A_5 \cap A_1| = 7!$  as numbers "1", "10" and "5" are on their proper places.

Consequently,  $P(A_{10} \cap A_5 \cap A_1) = \frac{7!}{10!} = \frac{1}{10 \cdot 9 \cdot 8} = 0.001$ , and
$$P(A_{10} \cap A_5 | \overline{A_1}) = \frac{P(A_{10} \cap A_5) - P(A_{10} \cap A_5 \cap A_1)}{1 - P(A_1)} = \frac{\frac{1}{10 \cdot 9} - \frac{1}{10 \cdot 9 \cdot 8}}{1 - \frac{1}{10}} = \frac{\frac{7}{10 \cdot 9 \cdot 8}}{\frac{9}{10}} = \frac{7}{10}$$
$$= \frac{7}{81 \cdot 8} = 0.011.$$

Now  

$$P(A_{10} \cup A_5 | \overline{A_1}) = P(A_{10} | \overline{A_1}) + P(A_5 | \overline{A_1}) - P(A_{10} \cap A_5 | \overline{A_1}) = \frac{8}{81} + \frac{8}{81} - \frac{7}{81 \cdot 8} = \frac{121}{81 \cdot 8} = 0.187.$$

E6. Pick 4 cards without replacement from a package containing 52 cards. Given that there is no hearts or there is no spades, compute the probability that there is no hearts and there is no spades.

Let A be the event that there is no hearts, B the event that there is a spade. The question is the conditional probability  $P(A \cap B | A \cup B)$ .

$$P(A \cap B | A \cup B) = \frac{P((A \cap B) \cap (A \cup B))}{P(A \cup B)} = \frac{P(A \cap B)}{P(A \cup B)}, \text{ as } (A \cap B) \subset (A \cup B).$$

We have to compute the probabilities  $P(A \cap B)$  and  $P(A \cup B)$ . This later one requires P(A), P(B) and  $P(A \cap B)$ . As the sampling is performed without replacement we do not have to take into consideration the order of the cards.  $\Omega = \{\{i_1, i_2, i_3, i_4\}: i_j \text{ are the cards from the package, } i_j = 1,2,3,4 \text{ are different if } j \neq k\}$ .

$$|\Omega| = \binom{52}{4}, |A| = |B| = \binom{39}{4}, |A \cap B| = \binom{26}{4},$$
$$P(A) = \frac{\binom{39}{4}}{\binom{52}{4}} = P(B) = 0.304, P(A \cap B) = \frac{\binom{26}{4}}{\binom{52}{4}} = 0.055$$

 $P(A \cup B) = P(A) + P(B) - P(A \cap B) = 0.553.$  $P(A \cap B | A \cup B) = \frac{P(A \cap B)}{P(A \cup B)} = \frac{0.055}{0.553} = 0.099.$ 

E7. Pick 4 cards without replacement from a package containing 52 cards. Compute the probability that the first card is heart, the second card and the third is diamond and the fourth one is spade.

Let A be the event that the first card is heart, B be the event that the second one is diamond, C be the event that the third card is diamond and D be the event that the last one is spade. The question is  $P(A \cap B \cap C \cap D)$ . Applying the generalized form of the multiplicative rule, we can write that  $P(A \cap B \cap C \cap D) = P(A) \cdot P(B|A) \cdot P(C|A \cap B) \cdot P(D|A \cap B \cap C)$ . Notice that conditional probabilities P(B|A),  $P(C|A \cap B)$ ,  $P(D|A \cap B \cap C)$  can be computed by the following argumentations. If we know that the first card is heart, then the package contains 51 cards and 13 are diamond of them. The third and last ones can be any cards, consequently  $P(B|A) = \frac{13}{51}$ . If we know that the first card is heart and the second one is diamond, then the package contains 50 cards at the third draw and 12 are diamonds of them. The last one can be any card, consequently  $P(C|A \cap B) = \frac{12}{50}$ .

Finally, if we know that the first card is heart, the second and third ones are diamonds, then the package contains 49 cards at the last picking and 13 spades are among them. Consequently,

$$P(D | A \cap B \cap C) = \frac{13}{49}. \text{ As } P(A) = \frac{13}{52}, P(A \cap B \cap C \cap D) = \frac{13}{52} \cdot \frac{13}{51} \cdot \frac{12}{50} \cdot \frac{13}{49} = 0.004$$

We present the following "simple" solution as well. As the question is connected to the order of pickings, we have to take into consideration the order of picked cards.

 $\Omega = \{ (i_1, i_2, i_3, i_4) : i_i \text{ are the cards from the package, } i_i j = 1, 2, 3, 4 \text{ are different if } j \neq k \}.$ 

 $|\Omega| = 52 \cdot 51 \cdot 50 \cdot 49$ . If the first draw is heart, consequently we have 13 possibilities at the first draw. If the second card is diamond, we have 13 possibilities at the second picking. If the third card is diamond again, we have only 12 possibilities at the third picking, as the previous draw eliminates one of diamond cards. Finally, if the last card is spade, we have 13 possibilities at the last picking. Consequently,  $|A \cap B \cap C \cap D| = 13 \cdot 13 \cdot 12 \cdot 13$ ,

 $P(A \cap B \cap C \cap D) = \frac{13 \cdot 13 \cdot 12 \cdot 13}{52 \cdot 51 \cdot 50 \cdot 49}$ , which is exactly the same as we have got by applying the multiplicative rule.

# c.2. Theorem of total probability, Bayes' theorem

In the examples of the previous section the conditional probabilities were computed from unconditional ones. The last example was solved by two methods. One of them has applied conditional probabilities for determining unconditional one. Law of total probability applies conditional probabilities for computing unconditional (total) probabilities. To do this, we need only a partition of the sample space  $\Omega$ .

Suppose that  $\Omega$ ,  $\mathcal{A}$ , and P are given.

<u>Definition</u> The set of events  $B_1, B_2, ..., B_n \in \mathcal{A}$  is called **partition** of  $\Omega$ , if  $\Omega = \bigcup_{i=1}^{n} B_i$  and  $B_i \cap B_i = \emptyset$ ,  $i \neq j$ ,  $1 \le i \le n$ ,  $1 \le j \le n$ .

We note that a partition cut the set of possible outcomes into some mutually exclusive events. Every possible outcome belongs to an event and any of them can not belong to two events.

<u>Theorem</u> (Law of total probability) Let  $B_1, B_2, ..., B_n \in \mathcal{A}$  be a partition of  $\Omega$ , and assume  $0 < P(B_i)$ , i = 1, 2, ..., n. Then for any event  $A \in \mathcal{A}$  the following equality holds

$$P(A) = \sum_{i=1}^{n} P(A | B_i) P(B_i).$$

<u>Proof:</u> As  $0 < P(B_i)$ , conditional probabilities are well defined.

$$P(A) = P(A \cap \Omega) = P(A \cap \left(\bigcup_{i=1}^{n} B_{i}\right)) = P\left(\bigcup_{i=1}^{n} (A \cap B_{i})\right).$$

Notice that if  $B_i \cap B_j = \emptyset$ , then  $(A \cap B_i) \cap (A \cap B_j) = \emptyset$ . Therefore the unioned events are mutually exclusive and the probability of the union is the sum of the probabilities.

$$P\left(\bigcup_{i=1}^{n} (A \cap B_{i})\right) = \sum_{i=1}^{n} P(A \cap B_{i})$$

Recalling the multiplicative rule  $P(A \cap B_i) = P(A | B_i) \cdot P(B_i)$  we get

$$P(A) = \sum_{i=1}^{n} P(A \mid B_i) P(B_i)$$

An inverse question can be asked by the following way: if we know that A occurs, compute the probability that  $B_i$  occurs. The answer can be given by the Bayes' theorem as follows:

37

$$\begin{split} & \underline{\text{Theorem}} \text{ (Bayes' theorem) Let } B_1, B_2, \dots, B_n \in \mathcal{A} \text{ be a partition of } \Omega \text{ , and assume } 0 < P(B_i) \text{ , } \\ & i = 1, 2, \dots, n. \quad \text{Then for any event} \quad A \in \mathcal{A} \quad \text{with } 0 < P(A) \text{ , the following holds:} \\ & P(B_i \mid A) = \frac{P(A \mid B_i) \cdot P(B_i)}{P(A)} = \frac{P(A \mid B_i) \cdot P(B_i)}{\sum_{i=1}^n P(A \mid B_i) P(B_i)} \text{ , } i = 1, 2, \dots, n \text{ .} \end{split}$$

$$\underline{Proof} \ P(B_i | A) = \frac{P(B_i \cap A)}{P(A)} = \frac{P(A | B_i) \cdot P(B_i)}{P(A)} = \frac{P(A | B_i) \cdot P(B_i)}{\sum_{i=1}^{n} P(A | B_i) P(B_i)}$$

**Remarks** 

• Notice that the unconditional probability is the weighted sum of the conditional probabilities.

• Law of total probability is worth applying when it is easy to know conditional probabilities.

• Construction of the partition is sometimes easy, in other cases it can be difficult. The main view is to be able to compute conditional probabilities.

• The theorem can be proved for countable infinite sets  $B_i$ , i = 1, 2, ..., as well.

• Bayes' theorem can be interpreted as the probability of "reasons". If A occurs, what is the probability that its "reason" is  $B_i$ , i = 1, 2, 3, ...

### Examples

E1. In a factory, there are three shifts. 45% of all products are manufactured by the morning shift, 35% of all products are manufactured by the afternoon shift, 20% are manufactured by the evening shift. A product manufactured by the morning shift is substandard with probability 0.04, a product manufactured by the afternoon shift is substandard with probability 0.06, and a product manufactured by the evening shift is substandard with probability 0.08. Choose a product from the entire set of products. Compute the probability that the chosen product is substandard.

Let  $B_1$  be the event that the chosen product was produced by the morning shift, let  $B_2$  be the event that the chosen product was produced by the afternoon shift and let  $B_3$  be the event that the chosen product was produced by the evening shift.  $B_1$ ,  $B_2$ ,  $B_3$  is a partition of the entire set of all products. Let S be the event that the chosen product is substandard. Now,  $P(S|B_1) = 0.04$ ,  $P(S|B_2) = 0.06$ ,  $P(S|B_3) = 0.08$ . Furthermore,

 $P(B_1) = 0.45, P(B_2) = 0.35, P(B_3) = 0.2.$  Applying the law of total theorem we get  $P(S) = P(S | B_1) \cdot P(B_1) + P(S | B_2) \cdot P(B_2) + P(S | B_3) \cdot P(B_3) =$ 

 $0.04 \cdot 0.45 + 0.06 \cdot 0.35 + 0.08 \cdot 0.2 = 0.055.$ 

If the chosen product is substandard, compute the probability that it was produced by the morning shift. If the chosen product is substandard, which shift produced it most probable?  $P(S \mid P_{i}) = P(P_{i}) = 0.04 \cdot 0.45$ 

$$P(B_{1} | S) = \frac{P(S | B_{1}) \cdot P(B_{1})}{P(S)} = \frac{0.04 \cdot 0.45}{0.055} = 0.327.$$

$$P(B_{2} | S) = \frac{P(S | B_{2}) \cdot P(B_{2})}{P(S)} = \frac{0.06 \cdot 0.35}{0.055} = 0.382.$$

$$P(B_{3} | S) = \frac{P(S | B_{3}) \cdot P(B_{3})}{P(S)} = \frac{0.08 \cdot 0.2}{0.055} = 0.291.$$

If the chosen product is substandard, the second shift is the most probable, as a "reason".

38

This example draws the attention to the differences between the conditional probabilities  $P(S|B_1)$  and  $P(B_1|S)$ ,  $P(S|B_2)$  and  $P(B_2|S)$ ,  $P(S|B_3)$  and  $P(B_3|S)$ . Although the maximal value among  $P(S|B_1)$ ,  $P(S|B_2)$  and  $P(S|B_3)$  is the first conditional probability, the maximal value among  $P(B_1|S)$ ,  $P(B_2|S)$  and  $P(B_3|S)$  is the second one.  $P(S|B_1)$  is the ratio of the substandard products among the products produced by the morning shift,  $P(B_1|S)$  is the ratio of the products produced by morning shift among all substandard products. These ratios have to be strictly distinguished.

E2. People are divided into three groups on the basis of their qualification: people with superlative, intermediate and elementary degree. We investigate the adults. 25% of all adults have elementary, 40% of all adults have intermediate and the rest of people have superlative degree. A person having elementary degree is unemployed with probability 0.18, a person having intermediate degree is unemployed with probability 0.12 and a person having superlative degree is unemployed with probability 0.05. Choose a person among the adults. Compute the probability that he is unemployed.

Let  $B_1$  be the event that the chosen person has elementary degree,  $B_2$  be the event that the chosen person has intermediate degree,  $B_3$  be the event that the chosen people has superlative degree.  $B_1, B_2, B_3$  is a partition of the entire set of  $\Omega$ . Let E be the event that the chosen person is unemployed.  $P(B_1) = 0.25$ ,  $P(B_2) = 0.4$  and  $P(B_3) = 0.35$ , furthermore  $P(E | B_1) = 0.18$ ,  $P(E | B_2) = 0.12$ ,  $P(E | B_3) = 0.05$ . Applying the law of total probability we get  $P(E) = P(E | B_1) \cdot P(B_1) + P(E | B_2) \cdot P(B_2) + P(E | B_3) \cdot P(B_3) = 0.18 \cdot 0.25 + 0.12 \cdot 0.4 + 0.05 \cdot 0.35 = 0.1105$ .

If the chosen person is not unemployed compute the probability that he has elementary/intermediate/ superlative degree.

$$P(B_{1} | \overline{E}) = \frac{P(E | B_{1}) \cdot P(B_{1})}{P(\overline{E})} = \frac{(1 - P(E | B_{1})) \cdot P(B_{1})}{1 - P(E)} = \frac{0.82 \cdot 0.25}{1 - 0.1105} = 0.230.$$

$$P(B_{2} | \overline{E}) = \frac{P(\overline{E} | B_{2}) \cdot P(B_{2})}{P(\overline{E})} = \frac{(1 - P(E | B_{2})) \cdot P(B_{2})}{1 - P(E)} = \frac{0.88 \cdot 0.4}{1 - 0.1105} = 0.396.$$

$$P(B_{3} | \overline{E}) = \frac{P(\overline{E} | B_{3}) \cdot P(B_{3})}{P(\overline{E})} = \frac{(1 - P(E | B_{3})) \cdot P(B_{3})}{1 - P(E)} = \frac{0.95 \cdot 0.35}{1 - 0.1105} = 0.374.$$

We draw the attention that  $P(\overline{E}|B_1) = 1 - P(E|B_1)$  according to the properties of conditional probability.

E3. Pick two cards without replacement from a package of cards containing 52 cards. Compute the probability that the second card is heart.

If we knew that the first card is heart or not, the conditional probabilities of the event "second draw is heart" could be easily computed. Consequently the unconditional probability can be also computed by the help of the conditional probabilities.

Let  $B_1$  be the event that the first card is heart and  $B_2 = \overline{B_1}$ . Now  $B_1$  and  $B_2$  form a partition of the entire set of  $\Omega$ . Let A be the event that the second draw is heart. Now,  $P(A | B_1) = \frac{12}{51}$ ,

 $P(A | B_2) = \frac{13}{51}$ , furthermore  $P(B_1) = \frac{13}{52}$ ,  $P(B_2) = \frac{39}{52}$ . Applying the law of total probability we get

$$P(A) = P(A | B_1) \cdot P(B_1) + P(A | B_2) \cdot P(B_2) = \frac{12}{51} \cdot \frac{13}{52} + \frac{13}{51} \cdot \frac{39}{52} = \frac{13 \cdot (12 + 39)}{51 \cdot 52} = \frac{13}{52} = 0.25.$$

Given that the second draw is heart compute the probability that the first one is not heart.  $13 \ 3$ 

$$P(B_2 | A) = \frac{P(A | B_2) \cdot P(B_2)}{P(A)} = \frac{\frac{1}{51 \cdot 4}}{0.25} = \frac{39}{51}$$

Given that the second draw is not heart compute the probability that the first one is heart.

$$P(B_1 | \overline{A}) = \frac{P(\overline{A} | B_1) \cdot P(B_1)}{P(\overline{A})} = \frac{\frac{39}{51} \cdot \frac{1}{4}}{\frac{3}{4}} = \frac{13}{51}, \text{ taking into account that } P(\overline{A} | B_1) = 1 - P(A | B_1).$$

### c3. Independence of events

Conditional probability of an event may differ from the unconditional one. It may be greater, smaller than the unconditional probability, and in some cases they can be equal, as well. Let us consider the following very simple examples.

Roll two fair dies. Let A be the event that the sum of the rolls is 7, let B be the event that the difference of the rolls is at least 4, let be C the event that the difference of the rolls is 0, finally

let D be the event that the first roll is 1. Now  $P(A) = \frac{6}{36}$ ,  $P(B) = \frac{6}{36}$ ,  $P(C) = \frac{6}{36}$ ,  $P(D) = \frac{6}{36}$ .

One can easily see that  $P(B | A) = \frac{P(B \cap A)}{P(A)} = \frac{\frac{2}{36}}{\frac{6}{36}} = \frac{1}{3} > P(B)$ ,

$$P(C | A) = \frac{P(C \cap A)}{P(A)} = \frac{P(\emptyset)}{\frac{1}{6}} = 0 < P(C), \ P(D | A) = \frac{P(D \cap A)}{P(A)} = \frac{\frac{1}{36}}{\frac{1}{6}} = P(D).$$
 This latter case is

the case when the information contained in A does not change the chance of D. It can be computed that  $P(A | D) = \frac{P(A \cap D)}{P(D)} = \frac{1}{6} = P(A)$  also holds, which means that the information in D does not change the chance of A. Relation is symmetric. Similarly,

$$P(A | B) = \frac{P(B \cap A)}{P(B)} = \frac{1}{3} > P(A) \text{ and } P(A | C) = \frac{P(A \cap C)}{P(C)} = 0 < P(A).$$

<u>Definition</u> The events  $A, B \in \mathcal{A}$  are called **independent** if  $P(A \cap B) = P(A) \cdot P(B)$ .

Actually we present that this definition is generalization of the previous concept.

<u>Theorem</u> Let A and B be events for which 0 < P(A) and 0 < P(B). A and B are independent if and only if P(A | B) = P(A) and/or P(B | A) = P(B).

<u>Proof</u> Recalling the definition of conditional probability, we can write that  $P(A | B) = \frac{P(A \cap B)}{P(B)}$  and  $P(B | A) = \frac{P(B \cap A)}{P(A)}$ . If A and B are independent, then, by definition,  $P(A \cap B) = P(A) \cdot P(B)$ . Dividing by P(A) and P(B) we get the equalities

$$\frac{P(A \cap B)}{P(A)} = P(B) \text{ and } \frac{P(A \cap B)}{P(B)} = P(A), \text{ respectively. Conversely, } \frac{P(A \cap B)}{P(A)} = P(B) \text{ implies}$$

 $P(A \cap B) = P(A) \cdot P(B)$ , and so does  $\frac{\Gamma(A \cap D)}{P(B)} = P(A)$ .

<u>Remarks</u>

- Definition of independence is symmetric.
- Definition of independence is given even in the case of 0 = P(A) or P(B) = 0.
- If 0 = P(A) or P(B) = 0, then A and B are independent. Take into consideration that

$$\begin{split} P(A \cap B) \leq P(A), \quad P(A \cap B) \leq P(B), \quad \text{consequently} \quad P(A \cap B) \leq \min(P(A), P(B)) = 0. \\ \text{Therefore, } P(A \cap B) = 0 = P(A) \cdot P(B). \end{split}$$

• Independent events are strongly different from mutually exclusive events. If A and B are mutually exclusive, then  $A \cap B = \emptyset$ ,  $P(A \cap B) = 0$ .  $P(A) \cdot P(B) = 0$  implies P(A) = 0 or P(B) = 0. If A and B are mutually exclusive and  $P(A) \neq 0 \neq P(B)$  hold, then A and B can not be independent. Roughly spoken, if A and B are mutually exclusive and any of them occurs, the other one can not occur. Occurrence of A is a very important piece of information with respect to B.

• In the example presented at the beginning of the subsection the events A and D are independent but the events A and B are not. So are A and C.

• Independence of A and B means that the "weight" of A in the entire set equals the "weight" of A in B.

#### Examples

E1. Roll 5 times a fair die repeatedly. Let A be the event that all rolls are different let B the event that there is no "six" among the rolls. Are the event A and B independent?

Applying our knowledge on sampling with replacement it is easy to see that  

$$P(A) = \frac{6 \cdot 5 \cdot 4 \cdot 3 \cdot 2}{6^5} = 0.093, \quad P(B) = \frac{5^5}{6^5} = 0.42, \quad P(A \cap B) = \frac{5 \cdot 4 \cdot 3 \cdot 2 \cdot 1}{6^5} = 0.015.$$
 As  

$$P(A \cap B) \neq P(A) \cdot P(B), A \text{ and } B \text{ are not independent. If we know that there is no "six"}$$

 $P(A \cap B) \neq P(A) \cdot P(B)$ , A and B are not independent. If we know that there is no six among the rolls then we can "feel" that the chance that all the rolls are different has been decreased. We have only five numbers to roll instead of six ones.

E2. There are N balls in a box (urn), M of them are white N-M are red. Pick n balls from the urn with replacement. Let A be the event that the first one is red, let B the event that the last one is white. Are the event A and B independent?

Recalling the results in connection with sampling with replacement,

$$P(A) = \frac{(N - M) \cdot N^{n-1}}{N^n} = \frac{N - M}{N} = 1 - \frac{M}{N}, \ P(B) = \frac{N^{n-1} \cdot M}{N^n} = \frac{M}{N},$$
$$P(A \cap B) = \frac{(N - M) \cdot N^{n-2} \cdot M}{N^n} = \frac{(N - M) \cdot M}{N^2} = \left(1 - \frac{M}{N}\right) \cdot \frac{M}{N}. \ As \ P(A \cap B) = P(A) \cdot P(B), \ A$$

and B are independent.

Roughly spoken, the result of the first picking does not effect on the result of the last picking, it does not increase and does not decrease the chance of picking white ball.

E3. There are N balls in an urn, M of them are white N-M are red. Pick 2 balls from the urn without replacement. Let A be the event that the first one is red, let B the event that the second one is white. Are the event A and B independent?

Recalling the results in connection with sampling without replacement, we can write  $P(A \cap B) = \frac{(N-M) \cdot M}{N \cdot (N-1)}$ ,  $P(A) = \frac{(N-M) \cdot (N-1)}{N \cdot (N-1)} = \frac{(N-M)}{N}$ . P(B) can be computed by the

help of theorem of total probability as follows:  

$$P(B) = P(B | A) \cdot P(A) + P(B | \overline{A}) \cdot P(\overline{A}) = \frac{M}{N-1} \cdot \frac{N-M}{N} + \frac{M-1}{N-1} \cdot \frac{M}{N} = \frac{M \cdot (N-M+M-1)}{(N-1) \cdot N} =$$

 $\frac{M}{N}$ . As  $P(A \cap B) \neq P(A) \cdot P(B)$ , A and B are not independent.

Roughly spoken, if we know that the first draw is red, the chance of the second one being white has been increased. The reason is that the relative number of white balls in the urn has increased.

E4. People are grouped into three groups on the basis of their qualification: people with superlative, intermediate and elementary degree. We investigate the adults. 25% of all adults have elementary, 40% of all adults have intermediate and the rest of people have superlative degree. A person having elementary degree is unemployed with probability 0.18, a person having intermediate degree is unemployed with probability 0.12 and a person having superior degree is unemployed with probability 0.05. Choose a person among the adults. Are the event A="the chosen person is unemployed" and B<sub>1</sub> = "the chosen person has superlative degree" independent?

Recalling the law of total probability we get P(A) = 0.1105, but  $P(A|B_1) = 0.05$ . As  $P(A|B_1) \neq P(E)$ , A and  $B_1$  are not independent. If somebody has superlative degree, the probability of the event that he is unemployed has decreased. The ratio of the unemployed people in the population is higher than the ratio of the unemployed people having superlative degree.

E5. Roll 3 times a fair die. Let A be the event that the sum of the rolls is at least 17, let B be the event that all the rolls are the same. Are A and B independent?

Taking into account the condition, the sum of the rolls can be 17 and 18. If the sum is 17 then we roll two "six"s and one "five". if the sum is 18, then we have three "six"-s.  $P(A) = \frac{3 \cdot 1 \cdot 1 \cdot 1}{6^3} + \frac{1}{6^3} = \frac{4}{6^3}$ . There are four elements in A. One of them satisfies that all of the

rolls are the same, consequently  $P(B|A) = \frac{1}{4}$ . Finally,  $P(B) = \frac{6 \cdot 1 \cdot 1}{6^3} = \frac{1}{36}$ . Now we can see

that  $P(B | A) \neq P(B)$ , therefore A and B are not independent.

<u>Theorem</u> If the events A and B are independent, then A and  $\overline{B}$ , furthermore  $\overline{A}$  and  $\overline{B}$  are independent, as well.

$$\begin{split} P(A \cap \overline{B}) &= P(A \setminus B) = P(A) - P(A \cap B) = P(A) - P(A) \cdot P(B) = P(A)(1 - P(B)) = P(A) \cdot P(\overline{B}) \,. \\ P(\overline{A} \cap \overline{B}) &= P(\overline{A \cup B}) = 1 - P(A \cup B) = 1 - (P(A) + P(B) - P(A \cap B)) = \\ 1 - (P(A) + P(B) - P(A) \cdot P(B)) = (1 - P(A))(1 - P(B)). \end{split}$$

Now let us consider independency of more than two events.

<u>Definition</u> The events  $A_i$  i  $\in I$  are called **pair wise independent** if any two of them are independent, that is  $P(A_i \cap A_k) = P(A_i) \cdot P(A_k)$  j,  $k \in I$ ,  $j \neq k$ .

 $\underline{\text{Definition}} \text{ The events } A_i \ i \in I \text{ are called } \textbf{independent}, \text{ if for any finite set of different indices} \\ \overline{\{i_1, i_2, ..., i_n\}} \text{ the equality } P(A_{i1} \cap A_{i2} \cap ... \cap A_{in}) = P(A_{i1}) \cdot P(A_{i2}) \cdot ... \cdot P(A_{in}).$ 

### **Remarks**

• If the number of elements of the set of indices equals 2, the above property expresses the pair wise independence.

• Pair wise independence of events does not imply independence of the events. We construct the following example in which pair wise independence holds but

$$\begin{split} P(A \cap B \cap C) \neq P(A) \cdot P(B) \cdot P(C). \quad \text{Let} \quad \Omega = \{1,2,3,4\}, \quad P(\{i\}) = \frac{1}{4}, \quad i = 1,2,3,4. \quad \text{Let} \\ A = \{1,2\}, B = \{1,3\}, C = \{1,4\}. \text{ Now } P(A) = P(B) = P(C) = \frac{2}{4} = 0.5, \\ A \cap B = B \cap C = A \cap C = \{1\}, \ P(A \cap B) = P(B \cap C) = P(A \cap C) = P(\{1\}) = \frac{1}{4} = 0.25. \\ \text{Consequently, } P(A \cap B) = P(A) \cdot P(B), \ P(A \cap C) = P(A) \cdot P(C), \ P(B \cap C) = P(B) \cdot P(C). \text{ It means that } A, \quad B \quad \text{and} \quad C \quad \text{are pair wise independent. But} \\ P(A \cap B \cap C) = P(\{1\}) = 0.25 \neq P(A) \cdot P(B) \cdot P(C) = \frac{1}{8}. \end{split}$$

<u>Definition</u> Experiments are called **independent** if the events connected to them are independent. More detailed for two experiments: if  $\mathcal{A}_1$  is the set of events connected to an experiment,  $\mathcal{A}_2$  is the set of events connected to another experiment, then for any  $A \in \mathcal{A}_1$  and  $B \in \mathcal{A}_2$  the events A and B are independent. The experiments characterized by the set of events  $\mathcal{A}_i$ ,  $i \in I$  are independent if for any  $A_i \in \mathcal{A}_i$  the events  $A_i$  are independent.

#### Remarks

• Sampling with replacement can be considered as a sequence of independent experiments. If the first draw is the first experiment, the second draw is the second experiment and so on, the events connected to different draws are independent.

• If we do sampling without replacement, then the consecutive draws are not independent experiments, as E3) in the previous subsection illustrates.

### **Examples**

E6. Fill two lotteries (90/5) independently. Compute the probability that at least one of them is bull's-eye.

Let A be the event that the first lottery is bull's-eye, let B the event that the second one is bull's-eye. The question is  $P(A \cup B)$ .  $P(A) = \frac{1}{\begin{pmatrix} 90 \\ 5 \end{pmatrix}}$ ,  $P(B) = \frac{1}{\begin{pmatrix} 90 \\ 5 \end{pmatrix}}$ ,

$$P(A \cap B) = P(A) \cdot P(B) = \frac{1}{\binom{90}{5}} \cdot \frac{1}{\binom{90}{5}} \cdot Applying \ P(A \cup B) = P(A) + P(B) - P(A \cap B) \text{ we get}$$
$$P(A \cup B) = \frac{2}{\binom{90}{5}} - \frac{1}{\binom{90}{5}} \cdot \frac{1}{\binom{90}{5}} = 4.6 \cdot 10^{-8}.$$

E7. Fill 10 million lotteries independently. Compute the probability that at least one of them is bull's-eye. Let  $A_i$  be the event that the ith experiment is bull's-eye. The question is  $P(A_1 \cup ... \cup A_{10^7})$ .

Instead of it, let us first consider its compliment.  $P(\overline{A_1 \cup ... \cup A_{10^7}}) = P(\overline{A_1} \cap \overline{A_2} \cap ... \cap \overline{A_{10^7}})$ . As the experiments are independent, the probability of the intersection of the events connected to them is the product of the probabilities. Therefore

43

$$P(\overline{A_1} \cap \overline{A_2} \cap \dots \cap \overline{A_{10^7}}) = P(\overline{A_1}) \cdot \dots \cdot P(\overline{A_{10^7}}) = \left(1 - \frac{1}{\binom{90}{5}}\right)^{10^7} = 0.796.$$

Consequently,  $P(A_1 \cup ... \cup A_{10^7}) = 1 - 0.796 = 0.204$ .

E8. How many lotteries are filled independently, if the probability that there is at least one bull's-eye among them equals 0.5?

Let  $A_i$  i=1,2,...,n be the event that the ith experiment is bull's-eye. The question is the value of n if  $P(A_1 \cup ... \cup A_n) = 0.5$ . Following the argumentation of the previous example E7 ٦n

1

$$P(\overline{A_1 \cup ... \cup A_n}) = P(\overline{A_1} \cap \overline{A_2} \cap ... \cap \overline{A_n}) = \left(1 - \frac{1}{\binom{90}{5}}\right) = 1 - 0.5 = 0.5.$$

Take the logarithm of both sides, we get

$$n \cdot \log(1 - \frac{1}{\binom{90}{5}}) = \log 0.5$$
,  $n = \frac{\log 0.5}{\log(1 - \frac{1}{\binom{90}{5}})} = 30463322$ , which is much more than the half of

possible fillings. But if you fill 30 million lotteries the probability that there are same fillings is almost 1. If you fill them independently, it may happen that the first one and the second one contain the same numbers crossed.

### The aim of this chapter

This chapter aims being acquainted with the concept of random variables as random valued functions. We introduce the concept of distribution, cumulative distribution function and probability density function. We present how to use cumulative distribution function to express probabilities. We introduce the concept of independent random variables.

### Preliminary knowledge

Properties of probability. Analysis, taking derivative and integrate.

### Content

- d.1. Random variables as random valued functions.
- d.2. Cumulative distribution function.
- d.3. Continuous random variable.
- d.4. Independent random variables.

# d.1. Random variables as random valued functions

In this section we introduce the concept of random variables as random valued functions.

We suppose that  $\Omega$ ,  $\mathcal{A}$  and P are given.

First we introduce a simple definition and later, after presenting lots of examples, we make it mathematically exact.

<u>Definition</u> The function  $\xi: \Omega \to R$  is called **random variable**.

#### **Remarks**

• Random variables map the set of possible outcomes to the set of real numbers. The values of random variables are numbers. If we know the result of the experiment, we know the actual value of the random variable. Before we perform the experiment, we do not know the actual outcome; hence we do not know the value of the function. "Randomness" is hidden in the outcome.

• Although we do not know the value of the function, we know the possible outcomes and the values assigned to them. These values are called as the image of the function in analysis. We will call them possible values of the random variable.

• If we know the possible values of the function, we can presumably compute the probabilities belonging to these possible values. That is we can compute the probability that the function takes this value. Additional refinement is needed to be able to do this in all cases.

• As the elements of  $\Omega$  are not real numbers in some cases, the function  $\xi$  may not be drawn in a usual Cartesian frame.

### **Examples**

E1. Flip a coin. If the result is head we gain 10 HUF, if the result is tail we pay 5 HUF. Let  $\xi$  be the money we get/pay during a game.

 $\Omega = \{H, T\}, A = 2^{\Omega}, P$  is the classical probability.  $\xi: \Omega \to R, \xi(H) = 10, \xi(T) = -5$ . Possible values of  $\xi$  are 10 and -5, and  $P(\xi = 10) = P(\{H\}) = 0.5, P(\xi = -5) = P(\{T\}) = 0.5$ . Before performing the experiment we do not know the value of our gain, but we can state that it can be 10 or -5 and both values are taken with probability 0.5.

E2. Roll a fair die. We gain the square of the result. Let  $\xi$  be the gain playing one game.

 $\Omega = \{1,2,3,4,5,6\}, \quad \mathcal{A} = 2^{\Omega}, \text{ P is the classical probability. } \xi: \Omega \to \mathbb{R}, \quad \xi(i) = i^2 \cdot \xi(1) = 1^2 = 1, \\ \xi(2) = 2^2 = 4, \quad \xi(3) = 3^2 = 9, \quad \xi(4) = 4^2 = 16, \quad \xi(5) = 5^2 = 25, \quad \xi(6) = 6^2 = 36. \text{ Moreover,} \\ \mathbb{P}(\xi = i^2) = \mathbb{P}(\{i\}) = \frac{1}{6}. \text{ Summarizing, possible values of } \xi \text{ are } 1,4,9,16,25,36, \text{ and the} \\ \text{probabilities belonging to them are } \frac{1}{6}. \text{ Before we roll the die we do not know how much} \\ \text{money we gain, but we can state that it may be } 1,4,9,16,25 \text{ or } 36, \text{ and all of them have} \\ \text{probability } \frac{1}{6}. \end{cases}$ 

E3. Roll a fair die twice. Let  $\xi$  be the sum of the rolls.

 $\Omega = \{(1,1), (1,2), \dots, (6,6)\}, \ \mathcal{A} = 2^{\Omega}, \ P \text{ is the classical probability}. \ \xi : \Omega \to \mathbb{R}, \ \xi((i,j)) = i + j.$ For example,  $\xi((1,1)) = 2, \ \xi((2,5)) = 7, \ \xi((6,6)) = 12.$  Possible values of  $\xi$  are 2,3,4,5,6,7,8,9,10,11,12.

$$\begin{split} \mathsf{P}(\xi=2) &= \mathsf{P}(\{(1,1)\}) = \frac{1}{36}, \\ \mathsf{P}(\xi=3) &= \mathsf{P}(\{(1,2),(2,1)\}) = \frac{2}{36}, \mathsf{P}(\xi=4) = \mathsf{P}(\{(1,3),(3,1),(2,2)\}) = \frac{3}{36}, \\ \mathsf{P}(\xi=5) &= \mathsf{P}(\{(1,4),(2,3),(3,2),(4,1)\}) = \frac{4}{36}, \mathsf{P}(\xi=6) = \mathsf{P}(\{(1,5),(2,4),(3,3),(4,2),(5,1)\}) = \frac{5}{36}, \\ \mathsf{P}(\xi=7) &= \mathsf{P}(\{(1,6),(2,5),(3,4),(4,3),(5,2),(6,1)\}) = \frac{6}{36}, \\ \mathsf{P}(\xi=8) &= \mathsf{P}(\{(2,6,(3,5),(4,4),(5,3),(6,2)\}) = \frac{5}{36}, \mathsf{P}(\xi=9) = \mathsf{P}(\{(3,6),(4,5),(5,4),(6,3)\}) = \frac{4}{36}, \\ \mathsf{P}(\xi=10) &= \mathsf{P}(\{(4,6),(5,5),(6,4)\}) = \frac{3}{36}, \mathsf{P}(\xi=11) = \mathsf{P}(\{(5,6),(6,5)\}) = \frac{2}{36}, \\ \mathsf{P}(\xi=12) &= \mathsf{P}(\{(6,6)\}) = \frac{1}{36}. \end{split}$$

We mention that the sets  $B_i = \{\omega; \xi(\omega) = i\}$  i = 2, 3, ..., 12 are mutually exclusive and the union of them is  $\Omega$ . They form a partition. Consequently, the sum of the probabilities belonging to the possible values equals 1.

E4. Choose two numbers without replacement from the set  $\{0,1,2,3,4\}$ . Let  $\xi$  be the minimum of the chosen numbers.

Actually, 
$$\Omega = \{\{i_1, i_2\}: 0 \le i_1 < i_2 \le 4, \text{ int egers}\}, \xi: \Omega \to \mathbb{R}, \xi(\{i_1, i_2\}) = \min\{i_1, i_2\}, |\Omega| = \binom{5}{2} = 10. \xi(\{0, 4\}) = 0, \xi(\{2, 3\}) = 2 \text{ and so on. Possible values of } \xi \text{ are } 0, 1, 2, 3 \text{ and}$$

$$P(\xi = 0) = P(\{0,1\}, \{0,2\}, \{0,3\}, \{0,4\}) = \frac{4}{10}, \qquad P(\xi = 1) = P(\{1,2\}, \{1,3\}, \{1,4\}) = \frac{3}{10},$$
$$P(\xi = 2) = P(\{2,3\}, \{2,4\}) = \frac{2}{10}, P(\xi = 3) = P(\{3,4\}) = \frac{1}{10}.$$

E5. Pick two numbers with replacement from the set  $\{0,1,2,3,4\}$ . Let  $\xi$  be the minimum of the picked numbers.

Actually, 
$$\Omega = \{(i_1, i_2): 0 \le i_1, i_2 \le 4, \text{ int egers}\}, \xi: \Omega \to \mathbb{R}, \xi((i_1, i_2)) = \min\{i_1, i_2\}, |\Omega| = 5 \cdot 5 = 25. \xi((0,4)) = 0, \xi((3,3)) = 3 \text{ and so on. Possible values of } \xi \text{ are } 0,1,2,3,4 \text{ and}$$
  
 $P(\xi = 0) = P(\{(0,0), (0,1), (0,2), (0,3), (0,4), (1,0), (2,0), (3,0), (4,0)\}) = \frac{9}{25},$   
 $P(\xi = 1) = P((1,1), (1,2), (1,3), (1,4), (4,1), (4,2), (4,3)) = \frac{7}{25},$   
 $P(\xi = 2) = P((2,2), (2,3), (2,4), (3,2), (4,2)) = \frac{5}{25}, P(\xi = 3) = P((3,3), (3,4), (4,3)) = \frac{3}{25},$   
 $P(\xi = 4) = P((4,4)) = \frac{1}{25}.$ 

E6. Choose two numbers with replacement of the set  $\{0,1,2,3,4\}$ . Let  $\xi$  be their difference.

Actually, the elements of the sample space are as in the previous example, but the mappings differ.  $\xi((1,1)) = 0$ ,  $\xi((4,1)) = 3$ , and so on. Possible values of  $\xi$  are 0,1,2,3,4 and

$$P(\xi = 0) = P(\{(0,0), (1,1)(2,2), (3,3), (4,4)\}) = \frac{5}{25},$$

$$P(\xi = 1) = P(\{(0,1), (1,0)(2,1), (1,2), (3,2), (2,3), (3,4), (4,3)\}) = \frac{8}{25},$$

$$P(\xi = 2) = P(\{(0,2), (2,0)(3,1), (1,3), (4,2), (2,4)\}) = \frac{6}{25},$$

$$P(\xi = 3) = P(\{(0,3), (3,0), (1,4), (4,1)\}) = \frac{4}{25}, P(\xi = 4) = P(\{(0,4), (4,0)\}) = \frac{2}{25}.$$

E7. Fire into a circle with radius R and suppose that the probability that the hit is situated in a subset of the circle is proportional to the area of the subset. Let  $\xi$  be the distance of the hit from the centre of the circle.

Actually,  $\Omega$  is the circle and A are those subsets of the circle which have area. If Q is a point of the circle, then  $\xi(Q) = d(O, Q)$ . Possible values of  $\xi$  are the points of the interval

 $\begin{bmatrix} 0, R \end{bmatrix}. P(\xi = 0) = P(\{O\}) = \frac{\mu(O)}{R^2 \pi} = 0. P(\xi = R) = \frac{\mu_R}{R^2 \pi}, \text{ where } \mu_R \text{ is the area of the border}$ curve of the circle with radius R, which equals 0.  $P(\xi = R) = 0.$  If 0 < x < R, then  $P(\xi = x) = \frac{\mu_x}{R^2 \pi}$ , where  $\mu_x$  is the area of the border curve of the circle with radius x, which equals 0, as well. Consequently, all possible values have probability 0.

E8. Choose two numbers independently from the interval [0,1] by geometrical probability. Let  $\xi$  be their difference.

Now,  $\Omega = [0,1]x[0,1]$ , which is a square.  $\mu(\Omega) = 1$ . The possible values of  $\xi$  are the points of [0,1]. Actually,  $P(\xi=0) = \frac{\mu(\{Q(x,y): x=y\} \cap \Omega)}{1}$ . The area of the line given by the equation x = y in the square equals 0, consequently,  $P(\xi=0)=0$ .  $P(\xi=1) = \frac{\mu(\{(1,0), (0,1)\})}{1} = 0$ . Generally, If 0 < u < 2, then  $P(\xi=u) = \frac{t(\{Q(x,y): |x-y|=u\} \cap \Omega)}{1}$ . The set  $\{Q(x,y): |x-y|=u\}$  consists of the points of the lines given by x-y=u and y-x=u, and the area of the two lines equals 0. Therefore  $P(\xi=u)=0$ .

#### Remarks

• Common feature of E1, E2,...,E6 is that the set of the possible values are finite.

• Common feature of E1, E2,...,E6 is that if  $x_i$  is a possible value of  $\xi$ , then  $P(\xi = x_i) \neq 0$ .

• If the possible values of  $\xi$  are denoted by  $x_1, \dots, x_n$ , then the sets  $B_i = \{\omega; \xi(\omega) = x_i\}$  form a partition of  $\Omega$ . Consequently,  $\sum_{i=1}^{n} P(\xi = x_i) = \sum_{i=1}^{n} P(B_i) = P(\Omega) = 1.$ 

• Common feature of E7, E8 is that the set of possible values is uncountable infinite and if x is a possible value then  $P(\xi = x) = 0$ . Nevertheless,  $P(\bigcup \{\omega : \xi(\omega) = x\}) = 1$ . If  $B_x = \{\omega : \xi(\omega) = x\}$ , and  $B_y = \{\omega : \xi(\omega) = y\}$ , then  $B_x \cap B_y = \emptyset$ , if  $x \neq y$ . If the set of possible values were countable, then  $P(\bigcup_{i=1}^{\infty} \{\omega : \xi(\omega) = x_i\}) = \sum_{i=1}^{\infty} P(\{\omega : \xi(\omega) = x_i\}) = 0$  would hold.

• In the case of E7, E8, instead of  $P(\xi = x)$  the probabilities  $P(\xi < x)$  are worth investigating, if the set  $\{\omega: \xi(\omega) < x\}$  has probability, i.e.  $\{\omega: \xi(\omega) < x\} \in \mathcal{A}$ . This requirement is included in the mathematically correct definition of random variables.

<u>Definition</u> The function  $\xi: \Omega \to \mathbb{R}$  is called **random variable**, if for any  $x \in \mathbb{R}$  $\{\omega: \xi(\omega) < x\} \in \mathcal{A}$ .

<u>Definition</u> The function  $\xi: \Omega \to \mathbb{R}$  is called **discrete random variable**, if the set Im( $\xi$ ) is finite or countable infinite. Those values in Im $\xi$  for which  $P(\xi = x) \neq 0$ , are called possible values.

<u>Definition</u> **Distribution of the discrete random variable**  $\xi$  is the set of the possible values together with the probabilities belonging to them. We denote is by  $\xi \sim \begin{pmatrix} x_1, x_2, \dots, x_n \\ p_1, p_2, \dots, p_n \end{pmatrix}$  or in the infinite case  $\xi \sim \begin{pmatrix} x_1, x_2, \dots, p_n \\ p_1, p_2, \dots \end{pmatrix}$  with  $p_i = P(\xi = x_i)$ .

**Remarks** 

• Definition of a discrete random variable can be more general as well. In many cases  $\xi$  is called discrete random variable, if there is countable subset C of Imf, for which

 $\sum_{x\in C} P(\xi=x) = 1$  . This means that the set Imf may be uncountable, but the values out of C

have probability zero together, that is  $P(\bigcup_{x \notin C} \{\omega : \xi(\omega) = x\}) = 0$ .

• If 
$$\{\omega: \xi(\omega) < x\} \in \mathcal{A}$$
, then  $\{\omega: \xi(\omega) = x\} = \bigcap_{n=1}^{\infty} \{\omega: x \le \xi(\omega) < x + \frac{1}{n}\} =$ 

 $\bigcap_{n=1}^{\infty} \left( \left\{ \omega : \xi(\omega) < x + \frac{1}{n} \right\} \setminus \left\{ \omega : \xi(\omega) < x \right\} \right) \in \mathcal{A}, \text{ as } \mathcal{A} \text{ is } \sigma \text{ algebra. Consequently,}$ 

 $P(\{\omega: \xi(\omega) = x\})$  are well defined.

• In example E1.,...E6. in the previous subsection, the distributions of random variables  $\xi$  are given: namely:

In E1. 
$$\xi \sim \begin{pmatrix} 10, & -5 \\ 0.5, & 0.5 \end{pmatrix}$$
.  
In E2.  $\xi \sim \begin{pmatrix} 1 & 4 & 9 & 16 & 25 & 36 \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \end{pmatrix}$ .  
In E3.  $\xi = \begin{pmatrix} 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \frac{1}{36} & \frac{2}{36} & \frac{3}{36} & \frac{4}{36} & \frac{5}{36} & \frac{6}{36} & \frac{5}{36} & \frac{4}{36} & \frac{3}{36} & \frac{2}{36} & \frac{1}{36} \end{pmatrix}$ .  
In E4.  $\xi \sim \begin{pmatrix} 0 & 1 & 2 & 3 \\ 0.4 & 0.3 & 0.2 & 0.1 \end{pmatrix}$ .

In E5. 
$$\xi \sim \begin{pmatrix} 0 & 1 & 2 & 3 & 4 \\ 0.36 & 0.28 & 0.2 & 0.12 & 0.04 \end{pmatrix}$$
  
In E6.  $\xi \sim \begin{pmatrix} 0 & 1 & 2 & 3 & 4 \\ 0.2 & 0.32 & 0.24 & 0.16 & 0.08 \end{pmatrix}$ .

• The examples in E7. and E8. are not discrete random variables even in the generalized sense of definition.

# d.2. Cumulative distribution function

As the probabilities  $P(\xi = x)$  are not always appropriate for characterizing random variables, consequently, the probability  $P(\xi < x)$  is investigated. This probability depends on the value of x. If we consider this probability as the function of x, we get a real-real function. This function is called cumulative distribution function.

<u>Definition</u> Let  $\xi$  be a random variable. The **cumulative distribution function** of  $\xi$  is defined as  $F: R \to R$   $F_{\xi}(x) = P(\xi < x) = P(\{\omega: \xi(\omega) < x\}).$ 

Remarks

- If the random variable  $\xi$  is fixed, then notation from the index is omitted.
- As F is a real-real function, it can be represented in the usual Cartesian frame.

### **Examples**

Give the cumulative distribution functions of the random variables presented in subsection d.1.

E1. 
$$\xi \sim \begin{pmatrix} 10, & -5 \\ 0.5, & 0.5 \end{pmatrix}$$
.

It can be easily seen that if  $x \le -5$ , then  $P(\xi < x) = P(\emptyset) = 0$ .

If  $-5 < x \le 10$ , then  $P(\xi < x) = P(\xi = -5) = P(\{T\}) = 0.5$ .

If 10 < x, then  $P(\xi < x) = P(\Omega) = 1$ .

Summarizing  $F(x) = P(\xi < x) = \begin{cases} 0 & \text{if } x \le -5 \\ 0.5 & \text{if } -5 < x \le 10 \\ 1 & \text{if } 10 < x \end{cases}$ 

The graph of this function can be seen in Fig. d.1.



Figure d.1. The cumulative distribution function of the random variable  $\xi \sim \begin{pmatrix} 10, -5\\ 0.5, 0.5 \end{pmatrix}$ 

$$E2. \quad \xi \sim \begin{pmatrix} 1 & 4 & 9 & 16 & 25 & 36 \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \\ \frac{1}{6} & \text{if } 1 < x \le 4 \\ \frac{2}{6} & \text{if } 4 < x \le 9 \\ \frac{3}{6} & \text{if } 9 < x \le 16 \\ \frac{4}{6} & \text{if } 16 < x \le 25 \\ \frac{5}{6} & \text{if } 25 < x \le 36 \\ 1 & \text{if } 36 < x \end{pmatrix}$$

$$E6. \ \xi \sim \begin{pmatrix} 0 & 1 & 2 & 3 & 4 \\ 0.2 & 0.32 & 0.24 & 0.16 & 0.08 \end{pmatrix}$$

$$F(x) = \begin{cases} 0 & \text{if } x \le 0 \\ 0.2 & \text{if } 0 < x \le 1 \\ 0.52 & \text{if } 1 < x \le 2 \\ 0.76 & \text{if } 2 < x \le 3 \\ 0.92 & \text{if } 3 < x \le 4 \\ 1 & \text{if } 4 < x \end{cases}$$

$$E7. \text{ If } 0 < x \le R,$$

then  $F(x) = P(\xi < x) = P(\{Q \in \Omega : d(O, Q) < x\}) = \frac{\mu(x)}{R^2 \pi} = \frac{x^2 \pi}{R^2 \pi} = \frac{x^2}{R^2}$ , where  $\mu(x)$  is the area of the circle with radius x. Of course, if  $x \le 0$ , then  $P(\xi < x) = P(\emptyset) = 0$ , and if R < x, then  $P(\xi < x) = P(\Omega) = 1$ . Summarizing,

$$F(x) = \begin{cases} 0 & \text{if } x \le 0 \\ \frac{x^2}{R^2} & \text{if } 0 < x \le R \\ 1 & \text{if } R < x \end{cases}$$

which can be seen in Fig.d.2.



Figure d.2. Cumulative distribution function of the random variable presented in E7

E8. 
$$F(u) = P(\xi < u) = P(\langle Q(x, y) : |x - y| < u \rangle)$$
 if  $0 < u < 1$ .

Recall that  $\left|x-y\right| < u \; \text{ means, that } \; x-u < y \; \text{ if } \; y < x \; \text{, and } \; y < x+u \; \text{ if } \; x < y \; \text{.}$ 

Those points for which |x - y| < u are situated between the straight lines given by the equations y - x = u and x - y = u. The area of the appropriate points can be computed by subtracting the area of the two triangles from the area of the square. The area of a triangle is  $\frac{(1-u)^2}{2}$ . Consequently,  $P(\xi < u) = 1 - (1-u)^2$  if  $0 < u \le 1$ . It is obvious that if  $u \le 0$ , then  $P(|x - y| < u) = P(\emptyset) = 0$ , and if 1 < u, then  $P(|x - y| < u) = P(\Omega) = 1$ .



Figure d.3. Appropriate points for the |x - y| < u with u = 0.35

Summarizing, F(u) = 
$$\begin{cases} 0 & \text{if } u \le 0 \\ 1 - (1 - u)^2 & \text{if } 0 < u \le 1 \\ 1 & \text{if } 1 < u \end{cases}$$

The graph of the cumulative distribution function cumulative can be seen in Fig. d.4.



Figure d.4. Cumulative distribution function of the random variable presented in E8

The graphs of the cumulative distribution functions presented have common features and differences, as well. The most conspicuous difference is in continuity, namely the cumulative distribution functions of E1, E2, have discontinuity in jumps, while the

cumulative distribution functions of E7. and E8. are continuous. The common features are that they are all increasing functions with values between 0 and 1.

Let us first consider the property of cumulative distribution functions. First we note that  $0 \le F(x) \le 1$  for any  $x \in R$ , as F(x) is a probability.

<u>Theorem</u> Let  $\xi$  be a random variable and let  $F: R \rightarrow R$  be its cumulative distribution function. Then F satisfies the followings:

- A) F is a monotone increasing function that is in case of x < y,  $F(x) \le F(y)$ .
- B)  $\lim_{x \to \infty} F(x) = 0$  and  $\lim_{x \to \infty} F(x) = 1$ .
- C) F is a left hand side continuous function.

#### **Remarks**

• The proof of the previous properties can be executed on the basis of the properties of probabilities but we omit it.

• The above properties can be checked easily using the tools of analysis.

The above properties characterize cumulative distribution functions, namely

<u>Theorem</u> If the function  $F: R \to R$  satisfies the properties A) B) and C), then there exist  $\Omega$  sample space,  $\mathcal{A} \sigma$  algebra and P probability measure, furthermore random variable  $\xi$  cumulative distribution function of that is the function F.

Cumulative distribution functions are suitable for expressing the probability that the value of the random variable  $\xi$  is situated in a fix interval. We list these probabilities with explanation in the following theorem:

#### <u>Theorem</u>

a)  $P(\xi \in (-\infty, a)) = P(\xi < a) = F(a)$  by definition of cumulative distribution

function.

b) 
$$P(\xi \in [a, \infty)) = P(\xi \ge a) = 1 - F(a).$$

$$P(\xi \in [a,\infty)) = P(\xi \ge a) = P(\overline{\xi < a}) = P(\overline{\{\omega : \xi(\omega) < a\}}) = 1 - F(a).$$

c)  

$$P(\xi \in (-\infty, a]) = P(\xi \le a) = F(a) + P(\xi = a)$$

$$P(\xi \le a) = P(\{\omega : \xi(\omega) < a\} \cup \{\omega : \xi(\omega) = a\}) = P(\{\omega : \xi(\omega) < a\}) + P(\{\omega : \xi(\omega) = a\})$$

 $= F(a) + P(\xi = a).$ 

d)  

$$P(\xi \in (a, \infty)) = P(\xi > a) = 1 - F(a) - P(\xi = a).$$

$$P(\xi > a) = P(\{\omega : \xi(\omega) > a\}) = P(\{\omega : \xi(\omega) \ge a\}) - P(\{\omega : \xi(\omega) = a\}) = 1 - F(a) - P(\xi = a).$$

e) 
$$P(\xi \in [a,b)) = P(a \le \xi < b) = F(b) - F(a)$$

$$P(\xi \in [a,b)) = P(a \le \xi < b) = P(\{\omega : \xi(\omega) < b\}) - P(\{\omega : \xi(\omega) < a\} = F(b) - F(a)\}$$

Note that  $\{\omega: \xi(\omega) < a\} \subset \{\omega: \xi(\omega) < b\}$ , consequently the probability of the difference is the difference of probabilities.

f) 
$$P(\xi \in [a,b]) = P(a \le \xi \le b) = F(b) - F(a) + P(\xi = b)$$

$$\begin{split} P(a \leq \xi \leq b) &= P(\{\omega : a \leq \xi(\omega) < b\} \cup \{\omega : \xi(\omega) = b\}) = P(\{\omega : a \leq \xi(\omega) < b\}) + P(\{\omega : \xi(\omega) = b\}) \\ F(b) - F(a) + P(\xi = b). \quad \text{We note that} \quad \{\omega : a \leq \xi(\omega) < b\} \cap \{\omega : \xi(\omega) = b\} = \emptyset, \text{ consequently} \end{split}$$

the probability of the union equals the sum of the probabilities.

g) 
$$P(\xi \in (a,b)) = P(a < \xi < b) = F(b) - F(a) - P(\xi = a)$$

$$P(a < \xi < b) = P(\{\omega : a \le \xi(\omega) < b\} \setminus \{\omega : \xi(\omega) = a\}) = F(b) - F(a) - P(\{\omega : \xi(\omega) = a\}).$$

h)  

$$P(\xi \in (a, b]) = P(a < \xi \le b) = F(b) - F(a) - P(\xi = a) + P(\xi = b) - F(a) = P(\{\omega : a < \xi(\omega) < b\} \cup \{\omega : \xi(\omega) = b\}) = P(\{\omega : a < \xi(\omega) < b\} \cup \{\omega : \xi(\omega) = b\}) = F(b) - F(a) - F(b) - F$$

$$P(\left\{\omega: a < \xi(\omega) < b\right\}) + P(\left\{\omega: \xi(\omega) = b\right\}) = F(b) - F(a) - P(\xi = a) + P(\xi = b).$$

i) 
$$P(\xi = a) = \lim_{\Delta a \to 0^+} F(a + \Delta a) - F(a).$$

$$\begin{split} P(\xi = a) &= P(\bigcap_{n=1}^{\infty} \left\{ \omega : a \leq \xi(\omega) < a + \frac{1}{n} \right\}) = \lim_{n \to \infty} P(\left\{ \omega : a \leq \xi(\omega) < a + \frac{1}{n} \right\}) = \lim_{n \to \infty} \left( F(a + \frac{1}{n}) - F(a) \right) \\ &= \lim_{n \to \infty} \left( F(a + \frac{1}{n}) \right) - F(a) \,. \end{split}$$

Remarks

- $\lim_{n \to \infty} \left( F(a + \frac{1}{n}) \right) F(a)$  is the value of the jump of the cumulative distribution function at "a".
- If F is continuous at "a", then  $\lim_{\Delta a \to 0^+} F(a + \Delta a) = F(a)$ , consequently  $P(\xi = a) = 0$ .
- If F is continuous on R, then P(ξ=x)=0 for any x∈R. Examples for this case were presented in E7 and E8. Further examples can be given by the help of geometrical probability.

Examples

E9. Let the lifetime of a machine be a random variable which has cumulative

distribution function F(x) = 
$$\begin{cases} 0, & \text{if } x \le 0 \\ \frac{e^{x} - e^{-x}}{e^{x} + e^{-x}}, & \text{if } 0 < x \end{cases}$$

Prove that F(x) is cumulative distribution function.

To prove that F(x) is a cumulative distribution function it is sufficient and necessary to check the properties A., B. and C.

A) For checking the monotone increasing property, take its derivative.

$$F'(x) = \frac{\left(e^{x} - (-e^{-x})\right) \cdot \left(e^{x} + e^{-x}\right) - \left(e^{x} - e^{-x}\right) \cdot \left(e^{x} + (-1) \cdot e^{-x}\right)}{\left(e^{x} + e^{-x}\right)^{2}} = \frac{4}{\left(e^{x} + e^{-x}\right)^{2}} > 0 \quad \text{if} \quad 0 < x ,$$

consequently the function F is monotone increasing for positive values. As at x=0 the function is continuous and it is constant for negative values, then it is increasing for all values of x.

B) 
$$\lim_{x \to -\infty} F(x) = \lim_{x \to -\infty} 0 = 0$$
 and  $\lim_{x \to \infty} F(x) = 1$ .  $\lim_{x \to \infty} \frac{e^x - e^{-x}}{e^x + e^{-x}} = \lim_{x \to \infty} \frac{1 - e^{-2x}}{1 + e^{-2x}} = 1$ .

C) 
$$\lim_{x \to 0^+} \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{0}{1} = 0 = \lim_{x \to 0^-} 0$$
, consequently F is continuous at  $x = 0$ , and it is

continuous at any point x. Therefore F is left hand side continuous.

Compute the probability that the lifetime of the machine is less than 1 unit.

$$P(\xi < 1) = F(1) = \frac{e^1 - e^{-1}}{e^1 + e^{-1}} = 0.762$$

Compute the probability that the lifetime of the machine is between 1 and 2 unit.

$$P(1 \le \xi < 2) = F(2) - F(1) = \frac{e^2 - e^{-2}}{e^2 + e^{-2}} - \frac{e^1 - e^{-1}}{e^1 + e^{-1}} = 0.964 - 0.762 = 0.202$$

Compute the probability that the lifetime is between 2 and 3 unit.

$$P(2 \le \xi < 3) = F(3) - F(2) = \frac{e^3 - e^{-3}}{e^3 + e^{-3}} - \frac{e^2 - e^{-2}}{e^2 + e^{-2}} = 0.995 - 0.964 = 0.031$$

Compute the probability that the lifetime is at least 3 unit.

$$P(3 \le \xi) = 1 - F(3) = 1 - \frac{e^3 - e^{-3}}{e^3 + e^{-3}} = 0.005.$$

Compute the probability that the lifetime of the machine equals 3.

 $P(\xi = x) = 0$ , as the cumulative distribution function of the lifetime is continuous at x = 3. At least how much time is the lifetime of the machine with probability 0.9?

$$x = ? P(\xi \ge x) = 0.9 \cdot 1 - F(x) = 0.9 \Longrightarrow F(x) = 0.1$$

 $\frac{e^{x} - e^{-x}}{e^{x} + e^{-x}} = 0.1$ . Substitute  $e^{x} = y$ , we have to find the solution of the following equation:

$$\frac{y - \frac{1}{y}}{y + \frac{1}{y}} = 0.1. \qquad \frac{y^2 - 1}{y^2 + 1} = 0.1 \Rightarrow 0.9y^2 = 1.1. \qquad \text{Consequently}, \qquad y^2 = \frac{1.1}{0.9} = 1.222,$$

$$y = \pm \sqrt{1.222} = \pm 1.105$$
. As  $y = e^x$ ,  $0 < y$  holds.  $e^x = 1.105$  implies  $x = \ln 1.105 = 0.100$ .

Finally, at most how much time is the lifetime of the machine with probability 0.9?

$$x = ?$$
  $P(\xi \le x) = 0.9$ .  $P(\xi \le x) = P(\xi < x) + P(\xi = x) = F(x) = 0.9$ . Substitute  $e^x = y$ , we

have to find the solution of the following equation:  $\frac{y-\frac{1}{y}}{y+\frac{1}{y}} = 0.9$ . Following the above steps

we get 
$$y = \sqrt{\frac{1.9}{0.2}}$$
, and  $x = \ln \sqrt{\frac{1.9}{0.2}} = 1.126$ 

<u>Definition</u>: Random variables  $\xi$  and  $\eta$  are called **identically distributed** if  $F_{\xi}(x) = F_{\eta}(x)$ for any value  $x \in \mathbb{R}$ .

Example

E10. 
$$\Omega_1 = \{H, T\}, \quad \mathcal{A}_1 = 2^{\Omega}, \quad P \quad \text{classical probability}, \quad \xi(H) = -1, \\ \xi(T) = 1.$$

 $\Omega_2 = \{1,2,3,4,5,6\}, \ \mathcal{A}_2 = 2^{\Omega}, \ P \ classical probability, \ \eta(i) = -1 \ if \ i \ is \ odd, \ \eta(i) = 1 \ if \ i \ is \ even.$  Now,  $\xi$  and  $\eta$  are identically distributed random variables, as

$$F_{\xi}(x) = F_{\eta}(x) = \begin{cases} 0 & \text{if } x \le -1 \\ 0.5 & \text{if } -1 < x \le 1 \\ 1 & \text{if } 1 \le x \end{cases}$$

We draw the attention that the distribution functions may be equal even if the mappings are different.

<u>Theorem</u> If  $\xi$  and  $\eta$  are discrete and identically distributed then they have common possible values and  $P(\xi = x_i) = P(\eta = x_i)$ , i = 1, 2, 3, ...

<u>Proof</u> If the random variables have common distribution functions, then the jumps of the cumulative distribution functions are at the same places. This concludes in common possible

values. Furthermore, the values of the jumps equal, as well. Recalling that the jump equals the probability belonging to the possible value, this means that the random variables take the possible value with the same probability. Consequently, they have the same distribution.

# d.3. Continuous random variable

Actually we turn our attention to those random variables which have continuous cumulative distribution function.

<u>Definition</u> The random variable  $\xi$  is called **continuous random variable** if its cumulative distribution function is the integral function of a piecewise continuous function, that is there exists a  $f: R \rightarrow R$  piecewise continuous (continuous except from finite points) for which

 $F(x) = \int f(t) dt$  . The function f is called **probability density function** of  $\xi$  .

Remarks

• The integral is Riemann integral.

• It is well-known fact in analysis that the integral function is continuous at any point, and at the points where f is continuous F is differentiable and F'(x) = f(x).

• If f is changed at a point, its integral function does not change. Consequently the probability density function of a random variable is not unique. Consequently, we can define it at some points arbitrarily. It is the typically case at the endpoints of intervals when f has discontinuity.

• The denomination "probability density function" can be argued by the followings:

 $\frac{P(a \le \xi < a + \Delta a)}{\Delta a}$  expresses the probability that  $\xi$  is situated in the neighbourhood of point "a" related to the length of the interval. It is a kind of density of being at the neighbourhood

"a" related to the length of the interval. It is a kind of density of being at the neighbourhood of "a". As

$$\begin{split} P(a \le \xi < a + \Delta a) &= F(a + \Delta a) - F(a), \quad \frac{P(a \le \xi < a + \Delta a)}{\Delta a} = \frac{F(a + \Delta a) - F(a)}{\Delta a}. \\ If \quad 0 \le \Delta a \to 0, \quad \text{then} \quad \lim_{\Delta a \to 0^+} \frac{P(a \le \xi < a + \Delta a)}{\Delta a} = \lim_{\Delta a \to 0^+} \frac{F(a + \Delta a) - F(a)}{\Delta a} = F'(a) = f(a), \end{split}$$

supposing that the limit exists.

•  $F(a + \Delta a) - F(a) \approx F'(a) \cdot \Delta a = f(a) \cdot \Delta a$ , therefore where the probability density function has large values, there the random variable takes its values with large probability, if

the length of the interval is fixed. If the probability density function is zero in the interval [a, b], then the random variable takes its values in [a, b] with probability zero.

• If the cumulative distribution function is a piecewise continuous function, then at the points of jumps the derivatives do not exist. On the open intervals, when the cumulative distribution function is constant, the derivative takes value zero, consequently there is no sense to take the derivative of the cumulative distribution function.

• We note that there exist random variables which are not either discrete either continuous. They can be "mixing" of discrete and continuous random variables, their cumulative distribution function is strictly monotone increasing continuous function in some intervals and have jumps at some points. These random variables are out of the frame of this booklet.

### **Examples**

E1. In the example given in E7 in subsection d.1., the probability density function is the following:

$$f(x) = F'(x) = \begin{cases} \frac{2x}{R^2} & \text{if } 0 < x < R\\ 0 & \text{otherwise} \end{cases}$$

We note that at x = 0 the function F is differentiable, and the derivative equals 0.At x = R the function F is not differentiable. The graph of the probability density function for R = 1 can be seen in Fig. d.5.



Figure d.5. Probability density function of the random variable given in E7.

E2. Probability density function of E8. in subsection d.1. is

$$f(u) = F'(u) = \begin{cases} 2 - 2u & \text{if } 0 \le u \le 1\\ 0 & \text{otherwise} \end{cases}$$

The graph of f(u) can be seen in Fig.d.6.



Figure d.6. Probability density function of the random variable given in E8.

E3. Probability density function of E9. in the previous subsection

$$f(x) = F'(x) = \begin{cases} \frac{4}{\left(e^x + e^{-x}\right)^2}, & \text{if } x < 0\\ 0 & \text{otherwise} \end{cases}$$

This function can be seen in Fig.d.7.



Figure d.7. Probability density function of the random variable given in E9.

The above probability density function takes large values in the interval [0,1] and small values in [2,3] and indeed,  $P(0 \le \xi < 1) = 0.723 > P(2 \le \xi < 3)$ .

Now let us investigate general properties of density functions.

<u>Theorem</u> If  $\xi$  is continuous random variable, with probability density function f, then

D)  $0 \le f(x)$  except from "some" points and

E) 
$$\int_{-\infty}^{\infty} f(x) dx = 1$$
.

<u>Proof</u> F is a monotone increasing function, consequently, its derivative is nonnegative, when the derivative exists. If we choose the values of f negative when the derivative does not exist, these points can belong to the set of exceptions. Usually we choose the values of f at these points zero. On the other hand, by the definition of improper integral

$$\int_{-\infty}^{\infty} f(x) dx = \lim_{x \to \infty} F(x) - \lim_{x \to -\infty} F(x) = 1 - 0.$$

The properties D) and E) characterize the probability density functions, namely

<u>Theorem</u> If the function  $f: \mathbb{R} \to \mathbb{R}$  satisfies the properties D) and E) then there exist  $\Omega$  sample space,  $\mathcal{A} \sigma$  algebra and P probability measure, furthermore a continuous random variable  $\xi$  probability density function of that is the function f.

#### **Remarks**

 $\sim$ 

• If the random variables  $\xi$  and  $\eta$  have the same probability density functions, then they have the same cumulative distribution functions as well, therefore they are identically distributed.

• If the random variables  $\xi$  and  $\eta$  have the same cumulative distribution functions, then there derivatives also equal at the points when the derivatives exist. At the points when the derivatives do not exist we can define the probability density functions arbitrary, but only some points have this property. Consequently, if the continuous random variables  $\xi$ and  $\eta$  are identically distributed, then they essentially have the same probability density functions.

• If we would like to express the probability that the continuous random variable  $\xi$  takes its values in an interval, we can write the followings:

$$\begin{split} \hline P(\xi < x) &= P(\xi \le x) = F(x), \\ \hline P(\xi \ge x) &= P(\xi > x) = 1 - F(x), \\ \hline P(a \le \xi < b) &= P(a \le \xi \le b) = P(a < \xi < b) = P(a < \xi \le b) = F(b) - F(a). \end{split}$$

The reason for this is the fact that the cumulative distribution function of a continuous random variable is continuous at any points, consequently it takes any value with probability 0. Hence we do not have to take into consideration the endpoints of the interval.

Now, we can express the probability taking values in an interval by the help of probability density function.

<u>Theorem</u> If the continuous random variable  $\xi$  has probability density function f, then  $P(a \le \xi \le b) = \int_{a}^{b} f(t)dt.$ 

<u>Proof</u> Applying the formula concerning the cumulative distribution function and the properties of integrals we get

$$P(a \le \xi \le b) = F(b) - F(a) = \int_{-\infty}^{b} f(t)dt - \int_{-\infty}^{a} f(t)dt = \int_{a}^{b} f(t)dt.$$

Remarks

• As the integral of a nonnegative function equals the area under the function, the above formula states that the probability of taking values in the interval [a,b] equals the area under the probability density function in [a,b]. For example, in the case of the random variable given by the probability density function  $f(x) = \begin{cases} 0.5 \sin x & \text{if } 0 \le x \le \pi \\ 0 & \text{otherwise} \end{cases}$ , the probability of taking values between  $\frac{\pi}{6}$  and  $\frac{5\pi}{6}$  can be seen in Fig.d.8. It is the area between the two red lines.



Figure d.8. Probability expressed by the area between the two read lines

Example

E4. Let the error of a measurement be a random variable  $\xi$  with probability

density function  $f(x) = \begin{cases} 0.5 \cdot e^x & \text{if } x < 0\\ 0.5 \cdot e^{-x} & \text{if } 0 \le x \end{cases}$ .

The graph of this function can be seen in Fig.d.9.



Figure d.9. Probability density function given by f

Prove that f is probability distribution function.

To do this, check the properties D) and E). As exponential functions take only positive values, the inequality 0 < f(x) holds. Moreover,

$$\int_{-\infty}^{\infty} f(x) dx = \int_{-\infty}^{0} 0.5e^{x} dx + \int_{0}^{\infty} 0.5e^{-x} dx = 0.5 \left[e^{x}\right]_{-\infty}^{0} + 0.5 \left[-e^{-x}\right]_{0}^{\infty} = 0.5 \left(1 - \lim_{x \to -\infty} e^{x}\right) + 0.5 \left(\lim_{x \to \infty} -e^{-x} - (-1)\right) = 0.5 + 0.5 = 1.$$

Determine the cumulative distribution function of  $\xi$ .

$$F(x) = \int_{-\infty}^{x} f(t) dt = \begin{cases} 0.5 \cdot e^{x} & ha \ x \le 0\\ 1 - 0.5 \cdot e^{-x} & ha \ 0 < x \end{cases}$$

Detailed computations are the following:

If 
$$x \le 0$$
, then  $\int_{-\infty}^{x} f(t) dt = \int_{-\infty}^{x} 0.5e^{t} dt = [0.5 \cdot e^{t}]_{-\infty}^{x} = 0.5e^{x} - \lim_{x \to -\infty} 0.5e^{x} = 0.5 \cdot e^{x} - 0 = 0.5e^{x}$ .

If 0 < x, then

$$\int_{-\infty}^{x} f(t)dt = \int_{-\infty}^{0} 0.5e^{t}dt + \int_{0}^{x} 0.5 \cdot e^{-t}dt = \left[0.5 \cdot e^{t}\right]_{-\infty}^{0} + \left[0.5(-e^{-x})\right]_{0}^{x} = 0.5 + (-0.5e^{-x} - (-0.5))$$
  
$$1 - 0.5 \cdot e^{-x}.$$

Compute the probability that the error of the measurement is less than -2.

 $P(\xi < -2) = F(-2) = 0.5e^{-2} = 0.068.$ 

Compute the probability that the error of the measurement is less than 1.

 $P(\xi < 1) = F(1) = 1 - 0.5 \cdot e^{-1} = 0.816.$ 

Compute the probability that the error of the measurement is between -1 and 3.

$$P(-1 < \xi < 3) = F(3) - F(-1) = 1 - 0.5 \cdot e^{-3} - 0.5 \cdot e^{-1} = 0.975 - 0.184 = 0.791.$$

Compute the probability that the error of the measurement is more than 1.5.

$$P(1.5 < \xi) = 1 - F(1.5) = 1 - (1 - 0.5 \cdot e^{-1.5}) = 0.112.$$

Now we ask the inverse question: at most how much is the error with probability 0.9?

We want to find the value x for which  $P(\xi \le x) = 0.9$ .

Taking into account that  $P(\xi \le x) = P(\xi < x) = F(x)$ , we seek the value x for which F(x) = 0.9. Namely, we would like to determine the cross point of the function F and line y = 0.9, as shown in Fig.d.10.



Figure d.10.Cumulative distribution function of  $\xi$  and the level 0.9

F(0) = 0.5, consequently x is positive. For positive x values  $F(x) = 1 - 0.5 \cdot e^{-x}$ . Consequently,  $1 - 0.5e^{-x} = 0.9$ . This implies  $0.5 \cdot e^{-x} = 0.1$ ,  $e^{-x} = 0.2$ ,  $x = -\ln 0.2 = 1.61$ . Give an interval symmetric to 0 in which the value of the error is situated with probability 0.9. Now we have to determine the value x for which  $P(-x < \xi < x) = 0.9$ . This means that F(x) - F(-x) = 0.9. Substituting the formula concerning F(x) we get  $1 - 0.5 \cdot e^{-x} - 0.5e^{-x} = 1 - e^{-x} = 0.9$ . This equality implies  $e^{-x} = 0.1$ ,  $x = -\ln 0.1 = 2.3$ . In Fig.d.11, the area between the two red lines equals 0.9.



d.11. Probability expressed by the area between the two read lines

At least how much is the error of the measurement with probability 0.99? Now we would like to determine the value x for which  $P(x \le \xi) = 0.99$ .  $P(x \le \xi) = 1 - F(x)$ , therefore F(x) = 0.1. As F(0) = 0.5, x is negative. Now we can write the equality  $0.5e^x = 0.01$ ,  $x = ln \frac{0.01}{0.5} = -3.91$ . As Fig.d.12. shows, the area under the density function from the red line to infinity equals 0.99.



d.12. Probability expressed by the area upper the read line

# d.4. Independent random variables

In this subsection we define independence of random variables.

<u>Definition</u> Random variables  $\xi$  and  $\eta$  are called **independent**, if for any values of  $x \in R$ and  $y \in R$  the events  $\{\xi < x\}$  and  $\{\eta < y\}$  are independent, that is  $P(\xi < x \cap \eta < y) = P(\xi < x) \cdot P(\eta < y)$ . For more than two variables, the random variables  $\xi_i$ , i = 1, 2, ..., are called **independent**, if for any value of j and any indices  $i_1, i_2, ..., i_j \in \{1, 2, 3, ...\}$  and any value of  $x_{i_k} = 1, 2, ..., j$  $P(\xi_{i_1} < x_{i_1} \cap ... \cap \xi_{i_j} < x_{i_j}) = P(\xi_{i_1} < x_{i_1}) \cdot P(\xi_{i_2} < x_{i_2}) \cdot ... \cdot P(\xi_{i_j} < x_{i_j})$ .

The independence of random variables are defined by the independence of events connected to them.

The following theorem can be stated:

Theorem If 
$$\xi$$
 and  $\eta$  are discrete random variables, distribution of them are  $\xi \sim \begin{pmatrix} x_1 & x_2 & \cdots \\ p_1 & p_2 & \cdots \end{pmatrix}$  and  $\eta \sim \begin{pmatrix} y_1 & y_2 & \cdots \\ q_1 & q_2 & \cdots \end{pmatrix}$ , then  $\xi$  and  $\eta$  are independent if and only if for any  $i = 1, 2, \ldots$  and  $j = 1, 2, \ldots$  the equality  $P(\xi = x_i \cap \eta = y_j) = P(\xi = x_i) \cdot P(\eta = y_j) = p_i \cdot q_j$  holds.

<u>Theorem Let</u>  $\xi$  and  $\eta$  be continuous random variables with probability density function f(x) and g(y), respectively.  $\xi$  and  $\eta$  are independent if and only if for any  $x \in \mathbb{R}$  and  $y \in \mathbb{R}$  where the  $P(\xi < x \cap \eta < y)$  is differentiable, there the following equality holds:  $\frac{\partial^2 P(\xi < x, \eta < y)}{\partial x \partial y} = f(x) \cdot g(y).$ 

Examples

E1. Flip twice a coin repeatedly. Let  $\xi$  be the number of heads, let  $\eta$  be the the number of difference between head and tails. Now.  $\Omega = \{(H, H), (H, T), (T, H), (T, T)\} \cdot \xi((H, H)) = 2, \quad \xi((T, T)) = 0, \xi((H, T)) = 1, \quad \xi((T, H)) = 1.$  $\xi \sim \begin{pmatrix} 0 & 1 & 2 \\ 0.25 & 0.5 & 0.25 \end{pmatrix}$ . Moreover,  $\eta((H, H)) = 2 = \eta((T, T))$ , Therefore, and  $\eta((H,T)) = 0 = \eta((T,H)).$  $\eta \sim \begin{pmatrix} 0 & 2 \\ 0.5 & 0.5 \end{pmatrix}$ .  $P(\xi = 0 \cap \eta = 0) = P(\emptyset) = 0 \neq P(\xi = 0) \cdot P(\eta = 0) = 0.125$ ., consequently  $\xi$ 

and  $\boldsymbol{\eta}$  are not independent.

E2. Choose one point Q from the circle with radius 1 by geometrical probability. Put the circle into the Cartezian frame and let the centre be the point O(0,0). Let  $\xi$  be the distance of the point Q from the centre O(0,0) of the circle, and  $\eta$  be the angle of

the vector 
$$\overrightarrow{OQ}$$
. Now,  $0 \le \xi \le 1$ ,  $0 \le \eta \le 2\pi$ .  $P(\xi < x) = \frac{x^2 \cdot \pi}{\pi} = x^2$ , if  $0 \le x \le 1$ .



Figure d.13. Appropriate points for  $\{\xi < x\}$  and for  $\{\eta < y\}$ 

$$P(\eta < y) = \frac{\frac{y \cdot \pi}{2\pi}}{\pi} = \frac{y}{2\pi}, \ 0 \le y \le 2\pi.$$
  
Furthermore,  $P(\xi < x \cap \eta < y) = \frac{x^2 \cdot \pi \cdot \frac{y}{2\pi}}{\pi} = \frac{\frac{x^2 \cdot y}{2\pi}}{\pi}, \text{ if } 0 \le x \le 1, \ 0 \le y \le 2\pi.$ 



Figure d.14. Appropriate points for  $\{\xi < x\} \cap \{\eta < y\}$ 

These together imply that  $P(\xi < x \cap \eta < y) = P(\xi < x) \cdot P(\eta < y)$ , if  $0 \le x \le 1$ ,  $0 \le y \le 2\pi$ . For the values out of  $[0,1]x[0,2\pi]$  one can easily check the equality, consequently  $\xi$  and  $\eta$  are independent.

# e. Numerical characteristics of random variables

### The aim of this chapter

In the previous chapter random variables were characterized by functions, such as cumulative distribution function or probability density function. This chapter aims with being acquainted with the numerical characteristics of random variables. These numbers contain less information than cumulative distribution functions but they are easier to be interpreted. We introduce expectation, dispersion, mode and median. Beside the definitions, main properties are also presented.

### Preliminary knowledge

Random variables, computing series and integrals. Improper integral.

# Content

- e.1. Expectation.
- e.2. Dispersion and variance.

e.3. Mode.

e.4. Median.

# e.1. Expectation

Cumulative distribution function of a random variable contains all of information about the random variable but it is not easy to know and handle it. This information can be condensed more or less into some numbers. Although we lose information during this concentration, these number carry important information about the random variable, consequently they are worth dealing with.

First of all we present a motivational example. Let us imagine the following gamble: we throw a die once and we gain the square of the result (points on the surface). How much money is worth paying for a gamble, if after many rounds we would like get more money than we have paid. About some values one can easily decide: for example 1 is worth paying but 40 is not. Other values, for example 13, are not obvious. Let us follow a heuristic train of though. Let the price of a round be denoted by x, and let the number of rounds be n. Now, the frequency of "one", "two", "three", "four", "five", "six" are  $k_1$ ,  $k_2$ ,...,  $k_6$ , respectively. The money we get together equals

 $1^2 \cdot k_1 + 2^2 \cdot k_2 + 3^2 \cdot k_3 + 4^2 \cdot k_4 + 5^2 \cdot k_5 + 6^2 \cdot k_6.$ 

The money we pay for gambling is  $n \cdot x$ . We get more money than we pay if the following inequality holds:  $n \cdot x < 1^2 \cdot k_1 + 2^2 \cdot k_2 + 3^2 \cdot k_3 + 4^2 \cdot k_4 + 5^2 \cdot k_5 + 6^2 \cdot k_6$ . Dividing by x, we get  $x < 1^2 \cdot \frac{k_1}{n} + 2^2 \cdot \frac{k_2}{n} + 3^2 \cdot \frac{k_3}{n} + 4^2 \cdot \frac{k_4}{n} + 5^2 \cdot \frac{k_5}{n} + 6^2 \cdot \frac{k_6}{n}$ .  $\frac{k_i}{n}$  i=1,2,...,6 express the relative frequencies of result "i". If they were about the probabilities of the result "i", then  $\frac{k_i}{n} \approx \frac{1}{6}$  and the left hand side of the previous inequality ends in  $1^2 \cdot \frac{1}{6} + 2^2 \cdot \frac{1}{6} + 3^2 \cdot \frac{1}{6} + 5^2 \cdot \frac{1}{6} + 6^2 \cdot \frac{1}{6} = \frac{91}{6} = 15\frac{1}{6}$ . Therefore, if  $x < 15\frac{1}{6}$  then the money we get after many rounds is more than we paid for them, in the opposite case it is less than we paid. Heuristic is  $\frac{k_i}{n} \approx \frac{1}{6}$ , it has not been proved yet in this booklet, it will be done in the chapter h.

How the value  $\frac{91}{6}$  can be interpreted? If we define the random variable  $\xi$  as the gain during one round, then  $\xi$  is discrete random variable with the following distribution:  $\xi \sim \left( \frac{1}{6} \quad \frac{4}{6} \quad \frac{9}{16} \quad \frac{16}{25} \quad \frac{25}{6} \quad \frac{36}{6} \right)$ . The right hand side of the inequality is the weighted sum of the possible values of  $\xi$  and the weights are the probabilities belonging to the possible values. This motivates the following definition:

<u>Definition</u> Let  $\xi$  be discrete random variable with finite possible values. Let the distribution

of 
$$\xi \sim \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ p_1 & p_2 & \dots & p_n \end{pmatrix}$$
. Then the **expectation** of  $\xi$  is defined as  $E(\xi) = \sum_{i=1}^n x_i \cdot p_i$ .

Let  $\xi$  be discrete random variable with infinite possible values. Let  $\xi = \begin{pmatrix} x_1 & x_2 & . & . \\ p_1 & p_2 & . & . \end{pmatrix}$ .

Then the **expectation** of  $\xi$  is defined as  $E(\xi) = \sum_{i=1}^{\infty} x_i \cdot p_i$ , if the series is absolute

convergent, that is  $\sum_{i=1}^{\infty} |x_i| \cdot p_i < \infty$ .

Let  $\xi$  be continuous random variable with probability density function f. Then the **expectation** of  $\xi$  is defined as  $E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx$  supposing that the improper integral is absolute convergent, that is  $\int_{-\infty}^{\infty} |x| \cdot f(x) dx < \infty$ .

**Remarks** 

- If the discrete random variable has only finite values, then its expectation exists.
- If  $\sum_{i=1}^{\infty} |x_i| \cdot p_i = \infty$  or  $\int_{-\infty}^{\infty} |x| \cdot f(x) dx < \infty$ , then, by definition, the expectation does not

exist.

• 
$$\sum_{i=1}^{\infty} |x_i| \cdot p_i < \infty$$
 implies  $\sum_{i=1}^{\infty} x_i \cdot p_i < \infty$ . Similarly,  $\int_{-\infty}^{\infty} |x| \cdot f(x) dx < \infty$  implies

 $\int_{-\infty}^{\infty} x \cdot |f(x)| dx < \infty.$ 

- Expectation of a random variable is finite, if it exists.
- $\sum_{i=1}^{\infty} x_i \cdot p_i$  can be convergent even if it is not absolute convergent. But in this case if

the series is rearranged, the sum can change. Therefore the value of the sum may depend on the order of the members, which is undesirable. This can not happen, if the series is absolute convergent.
• Expectation may be out of the set of possible values. For example, if the random variable takes values -1 and 1 with probability 0.5 and 0.5, then expectation is  $-1 \cdot 0.5 + 1 \cdot 0.5 = 0$ .

## **Examples**

E1. We gamble. We roll a die twice repeatedly and we gain the difference of the results. Compute the expectation of the gain.

Let  $\xi$  be the difference of the results. The distribution of  $\xi$  can be given as follows:

$$\xi \sim \left( \begin{array}{ccccc} 0 & 1 & 2 & 3 & 4 & 5 \\ \frac{6}{36} & \frac{10}{36} & \frac{8}{36} & \frac{6}{36} & \frac{4}{36} & \frac{2}{36} \end{array} \right).$$
  
Now  $E(\xi) = \sum_{i=1}^{6} x_i p_i = 0 \cdot \frac{6}{36} + 1 \cdot \frac{10}{36} + 2 \cdot \frac{8}{36} + 3 \cdot \frac{6}{36} + 4 \cdot \frac{4}{36} + 5 \cdot \frac{2}{36} = 1.24$ 

E2. We gamble. We roll a die n times repeatedly and we gain the maximum of the results. Compute the expectation of the gain.

Let  $\xi$  be the maximum of the results. The distribution of  $\xi$  can be given as follows:

Possible values are 1,2,3,4,5,6. and 
$$P(\xi = 1) = \left(\frac{1}{6}\right)^n$$
,  $P(\xi = 2) = \left(\frac{2}{6}\right)^n - \left(\frac{1}{6}\right)^n$ ,  
 $P(\xi = 3) = \left(\frac{3}{6}\right)^n - \left(\frac{2}{6}\right)^n$ ,  
 $P(\xi = 4) = \left(\frac{4}{6}\right)^n - \left(\frac{3}{6}\right)^n$ ,  $P(\xi = 5) = \left(\frac{5}{6}\right)^n - \left(\frac{4}{6}\right)^n$ ,  $P(\xi = 6) = 1 - \left(\frac{5}{6}\right)^n$   
 $E(\xi) = \sum_{i=1}^6 x_i \cdot p_i = 1 \cdot \left(\frac{1}{6}\right)^n + 2 \cdot \left(\left(\frac{2}{6}\right)^n - \left(\frac{1}{6}\right)^n\right) + 3 \cdot \left(\left(\frac{3}{6}\right)^n - \left(\frac{2}{6}\right)^n\right) + 4 \cdot \left(\left(\frac{4}{6}\right)^n - \left(\frac{3}{6}\right)^n\right) + 5 \cdot \left(\left(\frac{5}{6}\right)^n - \left(\frac{4}{6}\right)^n\right) = 6 - \left(\left(\frac{5}{6}\right)^n + \left(\frac{4}{6}\right)^n + \left(\frac{3}{6}\right)^n + \left(\frac{2}{6}\right)^n + \left(\frac{1}{6}\right)^n\right).$ 

E3. Flip a coin repeatedly. The gain is  $10^n$  if head appears first at the nth game. Compute the expectation of the gain.

Let  $\xi$  be the gain. Now the possible values of  $\xi$  are 10, 100, 1000,...and  $P(\xi = 10^{n}) = \left(\frac{1}{2}\right)^{n}. \quad E(\xi) = \sum_{i=1}^{\infty} x_{i} \cdot p_{i} = \sum_{i=1}^{\infty} 10^{i} \cdot \left(\frac{1}{2}\right)^{i} = \sum_{i=1}^{\infty} 5^{i} = \infty, \quad \text{consequently} \quad \text{the}$ 

expectation does not exist.

.1

E4. Flip a coin repeatedly. The gain is  $10^n$  if head appears first at the nth game supposing  $n \le m$  and  $10^m$ , if the we do not get head until the nth game. (The bank is able to pay maximum a given sum, which is reasonable assumption.) Compute the expectation of the gain.

Let 
$$\xi$$
 be the gain. Now the possible values of  $\xi$  are 10, 100, 1000,....,  $10^{m}$ .  
 $P(\xi = 10^{n}) = \left(\frac{1}{2}\right)^{n}$ , if  $n < m$  and  $P(\xi = 10^{m}) = \left(\frac{1}{2}\right)^{m-1}$ .  
 $E(\xi) = \sum_{i=1}^{m} x_{i} \cdot p_{i} = \sum_{i=1}^{m-1} 10^{i} \cdot \left(\frac{1}{2}\right)^{i} + 10^{m} \cdot \left(\frac{1}{2}\right)^{m-1} = \sum_{i=1}^{m-1} 5^{i} + 10 \cdot 5^{m-1} = 5 \cdot \frac{5^{m-1} - 1}{4} + 10 \cdot 5^{m-1} = 11.25 \cdot 5^{m-1} - 1.25$ , consequently the expectation exists.

E5. We compare the expectation of a random variable and average of the result of many experiences. We make computer simulations, we generate random numbers in the interval [0,1] by geometrical probability. Let the random number be denoted by  $\xi$ . Let  $\eta = [6 \cdot \xi] + 1.$ Now the possible values of η are 1.2.3.4.5.6.7 and  $P(\eta = 1) = P([6 \cdot \xi] = 0) = P(0 \le \xi < \frac{1}{6}) = \frac{1}{6}, \quad P(\eta = 2) = P([6 \cdot \xi] = 1) = P(\frac{1}{6} \le \xi < \frac{2}{6}) = \frac{1}{6}, \quad \dots,$  $P(\eta = 6) = P([6 \cdot \xi] = 5) = P(\frac{5}{6} \le \xi < 1) = \frac{1}{6}$ , finally,  $P(\eta = 7) = P([6\xi] = 6) = P(\xi = 1) = 0$ .

Therefore, distribution of  $\eta$  equals the distribution of the random variable which is equal to the number of points on the surface of a fair die. If we take the square of this random variable, we get our motivation example presented at the beginning of this subsection.

Now repeating the process many times, and taking the average of the numbers  $1, 4, \dots, 36$ , we get the following results in Table e.1. Recall that the expectation of the gain equals 15.1667. The larger the number of simulations, the smaller the difference between the average and the expectation.

Numbers of	100	1000	10000	100000	100000	10000000
simulations						
Average	13.94	15.130	15.0723	15.1779	15.1702	15.1646
Difference	1.2267	0.0367	0.0944	0.0112	0.0035	0.0021

Table e.1. Averages and their differences from the expectation in case of simulation

numbers  $n = 100, ..., 10^7$ 

E6. Recall the example presented in E7. in subsection d.1. Compute the expectation of the distance between the chosen point and the centre of the circle.

10 100 1000

Let  $\xi$  be the distance. The probability density function of  $\xi$ , as presented in subsection d.3.

is the following: 
$$f(x) = \begin{cases} \frac{2x}{R} & 0 \le x \le R\\ 0 & \text{otherwise} \end{cases}$$

Now 
$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{R} \frac{x \cdot 2x}{R} dx = \left[\frac{2x^{2}}{3R}\right]_{0}^{R} = \frac{2}{3}R$$
.

E7. Recall the example presented in E8. in subsection d.1. Compute the expectation of the distance between the chosen points.

The probability density function of  $\xi$  as presented in subsection d.3. is the following:

$$f(x) = \begin{cases} 2(1-x) & \text{if } x \le 0 \le 1\\ 0 & \text{otherwise} \end{cases}.$$
  
$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{1} x \cdot 2(1-x) dx = \left[ x^{2} - \frac{2x^{3}}{3} \right]_{0}^{1} = 1 - \frac{2}{3} = \frac{1}{3}.$$

E8. Compute the approximate value of the above expectation. Generate two random numbers in [0,1] by geometrical probability, compute their difference and take the average of all differences. Repeating this process many times, we get the following results:

Numbers of	100	1000	10000	100000	100000	1000000
simulations						
Average	0.3507	0.3325	0.3323	0.3328	0.3331	0.3333
Difference	0.0174	0.0008	0.0010	0.0005	0.0002	0.00007

 Table e.2. Differences of the approximate and the exact expectation in case of different numbers of simulations

E9. Choose two numbers in the interval [0,1] by geometrical probability independently. Let  $\xi$  be the sum of them. Now one can prove that the probability density function is

 $f(x) = \begin{cases} x & \text{if } 0 \le x \le 1\\ 2 - x & \text{if } 1 \le x \le 2\\ 0 & \text{otherwise} \end{cases}$ 

Now

$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{1} x \cdot x \, dx + \int_{0}^{1} x \cdot (2 - x) dx = \left[\frac{x^{3}}{3}\right]_{0}^{1} + \left[x^{2} - \frac{x^{3}}{3}\right]_{1}^{2} = \frac{1}{3} + 4 - \frac{8}{3} - 1 + \frac{1}{3} = 1$$

Solving this problem is also possible by simulation. Generating two random numbers, summing them up and averaging the sums one can see the following:

Numbers of	100	1000	10000	100000	100000	1000000
simulations						
Average	0.9761	1.0026	0.99995	1.0001	0.9999	1
Difference	0.0239	0.0026	0.00005	0.0001	0.0001	0.00001

Table e.3. Differences of the approximate and the exact expectation in case of different numbers of simulations

## Properties of the expectation

Now we list some important properties of the expectation. If it is easy to do, we give some explanation, as well. Let  $\xi$  and  $\eta$  be random variables, suppose that  $E(\xi)$  and  $E(\eta)$  exist. Let  $a, b, c \in \mathbb{R}$ .

1. If  $\xi$  and  $\eta$  are identically distributed, then  $E(\xi) = E(\eta)$ . If  $\xi$  and  $\eta$  are discrete, then they have common possible values and  $P(\xi = x_i) = P(\eta = x_i)$ , consequently the weighted sums are equal, as well. If  $\xi$  and  $\eta$  continuous random variable, they have common probability density function, consequently the improper integrals are equal.

2. If  $\xi = c$  or  $P(\xi = c) = 1$ , then  $E(\xi) = c \cdot 1 = 1$ .

3. If  $0 \le \xi$ , then  $0 \le E(\xi)$  holds. If  $\xi$  is discrete, then all possible values of  $\xi$  is nonnegative, therefore so is the weighted sum, as well. If  $\xi$  is continuous random variable, then  $0 \le \xi$  implies that its probability density function is zero for negative x values.

Consequently, 
$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{\infty} x \cdot f(x) dx$$
, which must be nonnegative.

4.  $E(\xi + \eta) = E(\xi) + E(\eta)$ . Additive property is difficult to prove using elementary analysis, but is follows from the general properties of integral.

5.  $E(a \cdot \xi + b) = a \cdot E(\xi) + b$ . If  $\xi$  is discrete, then the possible values of  $a \cdot \xi + b$  are ,,a" times more and b than the possible values of  $\xi$ , therefore so is their weighted sum. If  $\xi$  is continuous, then  $F_{a\xi+b}(x) = P(a\xi+b< x) = P(\xi < \frac{x-b}{a}) = F(\frac{x-b}{a})$  supposing 0 < a. Taking the derivative  $f_{a\xi+b}(x) = \frac{1}{a} \cdot f(\frac{x-b}{a})$ ,

$$E(a\xi+b) = \int_{-\infty}^{\infty} x \cdot f_{a\xi+b}(x) dx = \int_{-\infty}^{\infty} x \cdot f_{a\xi+b}(x) dx = \int_{-\infty}^{\infty} x \cdot \frac{1}{a} \cdot f(\frac{x-b}{a}) dx = \int_{-\infty}^{\infty} (ay+b) \cdot f(y) dy = \int_{-\infty}^{\infty} x \cdot \frac{1}{a} \cdot \frac{$$

 $a \int_{-\infty} y \cdot f(y) dy + b \cdot \int_{-\infty} f(y) dy = aE(\xi) + b$ . Similar argumentation can be given for negative

value of "a" as well. If a = 0 holds, then  $E(a \cdot \xi + b) = b = aE(\xi) + b$ .

6. If  $a \le \xi \le b$ , then  $a \le E(\xi) \le b$ . As  $a \le \xi$ ,  $0 \le \xi - a$ , holds, therefore  $0 \le E(\xi - a) = E(\xi) - a$ , which implies  $a \le E(\xi)$ . Similar argumentation can be given for the upper bound.

7. If  $\xi \le \eta$ , that is  $\xi(\omega) \le \eta(\omega)$  for any  $\omega \in \Omega$ , then  $E(\xi) \le E(\eta)$ . Take into consideration that  $\xi \le \eta$  implies  $0 \le \eta - \xi$ , consequently  $0 \le E(\eta - \xi) = E(\eta) - E(\xi) \Longrightarrow E(\xi) \le E(\eta)$ . We draw the attention that it is not enough that the possible values of  $\xi$  are less than the possible values of  $\eta$ . For example,

$$\xi \sim \begin{pmatrix} 1 & 4 \\ 0.1 & 0.9 \end{pmatrix}$$
,  $\eta \sim \begin{pmatrix} 2 & 5 \\ 0.8 & 0.2 \end{pmatrix}$ . Now  $E(\xi) = 1 \cdot 0.1 + 4 \cdot 0.9 = 3.7$ ,

 $E(\eta) = 2 \cdot 0.8 + 5 \cdot 0.2 = 3.6$ , that is  $E(\eta) < E(\xi)$ .

8. Let  $\xi_i$  i=1,2,...,n be independent identically distributed random variables with expectation  $E(\xi_i) = m$ . Then  $E(\sum_{i=1}^n \xi_i) = nm$ . This is the straightforward consequence of

the above properties, namely  $E(\sum_{i=1}^{n} \xi_i) = \sum_{i=1}^{n} E(\xi_i) = n \cdot m$ .

9. Let  $\xi_i$  i=1,2,...,n be independent identically distributed random variables with

expectation 
$$E(\xi_i) = m$$
. Then  $E\left(\frac{\sum_{i=1}^n \xi_i}{n}\right) = m$ . Take into consideration that  $\frac{\sum_{i=1}^n \xi_i}{n} = \frac{1}{n} \sum_{i=1}^n \xi_i$ .

10. If  $\xi$  and  $\eta$  are independent random variables and  $E(\xi \cdot \eta)$  exists, then  $E(\xi \cdot \eta) = E(\xi) \cdot E(\eta)$ .

11. If 
$$\xi$$
 is discrete random variable with distribution  $\xi \sim \begin{pmatrix} x_1 & x_2 & \cdots \\ p_1 & p_2 & \cdots \end{pmatrix}$ ,  $g: I \to R$ 

for which  $\{x_1, x_2, ...\} \subset I$ , furthermore  $\sum_{i=1}^{\infty} |g(x_i)| p_i < \infty$ , then  $E(g(\xi)) = \sum_{i=1}^{\infty} g(x_i) p_i$ . Take

into consideration that  $g(\xi): \Omega \rightarrow R$  and their possible values are  $g(x_i)$ , and

$$P(g(\xi)) = g(x_i) = \sum_{j:g(x_j) = g(x_i)} p_j = q_i.$$
 This implies the equality

$$E(g(\xi)) = \sum_{i=1}^{\infty} g(x_i) p_i$$
 .Especially, if  $g(x) = x^2$ , then  $E(\xi^2) = \sum_{i=1}^{\infty} x_i^2 \cdot p_i$ 

12. If  $\xi$  is continuous random variable with probability density function f,  $g: I \subset R$  for

which 
$$\operatorname{Im}(\xi) \subset I$$
 and  $\int_{-\infty}^{\infty} |g(x)| f(x) dx < \infty$ , then  $E(g(\xi) = \int_{-\infty}^{\infty} |g(x)| f(x) dx$ . Especially, if  $g(x) = x^2$ , then  $E(g(\xi)) = E(\xi^2) = \int_{-\infty}^{\infty} x^2 f(x) dx$ 

**Examples** 

E9. The latest property is able to provide possibility for computing integral by computer simulation. If the expectation is an integral, and expectation is about the average of many values of the random variables, we can compute the average and it can be used for approximation of the integral. For example, if we want compute the integral  $\int_{0}^{1} \sin x dx$ , then it can be interpreted as an expectation. Namely, let  $\xi$  be a random variable with probability density function  $f(x) = \begin{cases} 1 & \text{if } 0 \le x \le 1 \\ 0 & \text{otherwise} \end{cases}$ , and  $E(\sin \xi) = \int_{-\infty}^{\infty} \sin x \cdot f(x) dx = \int_{0}^{1} \sin x dx$ . If  $\xi$  is a random number chosen by geometrical probability, then  $F(x) = P(\xi < x) = \begin{cases} 0 & \text{if } x \le 0 \\ x & \text{if } 0 < x \le 1, \\ 1 & \text{if } 1 < x \end{cases}$ 

and  $f(x) = F'(x) = \begin{cases} 1 & \text{if } 0 \le x \le 1 \\ 0 & \text{otherwise} \end{cases}$ .

Consequently, generating a random number, and substituting it into the function sinx, taking their average we get an approximate value for the integral. This is a simple algorithm. We draw the attention to the fact that expectation is about the average of many experiments has not been proved yet in this booklet. It will be done by the law of large numbers in chapter h. The following Table e.4. presents some results:

Numbers of	100	1000	10000	100000	100000	1000000
simulations						
Average	0.4643	0.4548	0.4588	0.4586	0.4596	0.4597
Difference	0.0046	0.0049	0.001	0.0011	0.0011	0.00002

Table e.4. Differences of the approximate and the exact value of the integral in case of different numbers of simulations

E10. Additive property of the expectation helps us to simplify computations. For example, consider the following example. Roll twice a die repeatedly. Let  $\eta$  be the sum of the results. Now. can check that one and  $E(\eta) = \sum_{i=1}^{11} x_i p_i = 2 \cdot \frac{1}{36} + 3 \cdot \frac{2}{36} + 4 \cdot \frac{3}{36} + 5 \cdot \frac{4}{36} + 6 \cdot \frac{5}{36} + 7 \cdot \frac{6}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 9 \cdot \frac{4}{36} + 6 \cdot \frac{5}{36} + 7 \cdot \frac{6}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 9 \cdot \frac{4}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 8 \cdot \frac{5}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 8 \cdot \frac{5}{36} + 8 \cdot \frac{5}{36} + 9 \cdot \frac{4}{36} + 8 \cdot \frac{5}{36} + \frac{5}{36} + \frac{5}{36} + \frac{5}{36} + \frac{5}{36} + \frac{5}{36} + \frac{5}{36}$  $10 \cdot \frac{3}{36} + 11 \cdot \frac{2}{36} + 12 \cdot \frac{1}{36} = 7$ . Another method is the following:  $\eta = \xi_1 + \xi_2$  where  $\xi_1$  is the result of the first throw and  $\xi_2$  is the result of the second throw. Now  $\xi_1$  and  $\xi_2$  are identically distributed random variables and  $\xi_1 \sim \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ \frac{1}{\epsilon} & \frac{1}{\epsilon} & \frac{1}{\epsilon} & \frac{1}{\epsilon} & \frac{1}{\epsilon} & \frac{1}{\epsilon} & \frac{1}{\epsilon} \\ \end{pmatrix}$ .  $E(\xi_1) = \sum_{i=1}^{o} x_i p_i = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = 3.5 = E(\xi_2),$ 

consequently,  $\eta = \xi_1 + \xi_2 = E(\xi_1 + \xi_2) = 2 \cdot 3.5 = 7$ .

# e.2. Dispersion and variance

Expectation is a kind of average. It is easy to construct two different random variables which have the same expectation. For example,  $\xi_1 \sim \begin{pmatrix} -1 & 1 \\ 0.5 & 0.5 \end{pmatrix}$  and  $\xi_2 \sim \begin{pmatrix} -2 & -1 & 0 & 1 & 2 \\ 0.1 & 0.3 & 0.225 & 0.25 & 0.125 \end{pmatrix}$ . They both have the same expectation, namely zero.

Measure of the average distance from the expectation can be important information, as well. As  $E(\xi - E(\xi)) = E(\xi) - E(E(\xi)) = 0$ , therefore it is not appropriate to characterize the distance from the average. The reason is that the negative and positive differences balance. This phenomenon disappears if we take  $E(|\xi - E(\xi)|)$ . But if we use the square instead of absolute value, the signs disappear again and, on the top of all the small differences become smaller, large differences become larger. Square punishes large differences but does not punish small ones. Consequently, it is worth investigating  $E((\xi - E(\xi))^2)$  instead of  $E(|\xi - E(\xi)|)$ , if it exists.

<u>Definition</u> Let  $\xi$  be a random variable with expectation  $E(\xi)$ . The variance of  $\xi$  is defined as  $D^2((\xi - E(\xi))^2)$ , if it exists.

<u>Definition</u> Let  $\xi$  be a random variable with expectation  $E(\xi)$ . The **dispersion** of  $\xi$  is defined as  $D(\xi) = \sqrt{D^2(\xi)}$ , if  $D^2(\xi)$  exists.

Remarks

- As  $0 \le (\xi E(\xi))^2$ , so is its expectation. Its square root is well-defined.
- By definition, dispersion of a random variable is nonnegative number. It is the square root of the average squared difference.
- It is easy to construct such random variable which has expectation but does not have dispersion. We will do it in this subsection, after proving the rule of its calculation.

<u>Theorem</u> If  $\xi$  is a random variable with expectation  $E(\xi)$  and  $E(\xi^2)$  exists, then  $D^2(\xi) = E(\xi^2) - (E(\xi))^2$ .

Proof Applying the properties of expectation

$$D^{2}(\xi) = E((\xi - E(\xi))^{2}) = E(\xi^{2} - 2\xi E(\xi) + (E(\xi))^{2}) = E(\xi^{2}) - 2E(\xi)E(\xi) + E((E(\xi))^{2})$$
$$= E(\xi^{2}) - 2(E(\xi))^{2} + (E(\xi))^{2} = E(\xi^{2}) - (E(\xi))^{2}.$$

**Remarks** 

• 
$$D^{2}(\xi) = \sum_{i=1}^{\infty} x_{i}^{2} p_{i} - \left(\sum_{i=1}^{\infty} x_{i} p_{i}\right)^{2}$$
, and  $D^{2}(\xi) = \int_{-\infty}^{\infty} x^{2} f(x) dx - \left(\int_{-\infty}^{\infty} x f(x) dx\right)^{2}$ .

• If  $\xi$  and  $\eta$  are identically distributed random variables, then  $D(\xi) = D(\eta)$ 

• In case of discrete random variable with infinitely many possible values,  

$$E(\xi^2) = \sum_{i=1}^{\infty} x_i^2 p_i$$
If the series is not (absolute) convergent, then 
$$\sum_{i=1}^{\infty} x_i^2 p_i = \infty$$
.

79

• In case of continuous random variables with probability density function f,  $E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2}f(x)dx . \text{ If the improper integral is not (absolute) convergent, then}$   $\int_{-\infty}^{\infty} x^{2}f(x)dx = \infty.$ • If  $E(\xi^{2})$  does not exist, neither does  $D^{2}(\xi) . \sum_{i=1}^{\infty} x_{i}^{2}p_{i} = \infty$  implies  $\sum_{i=1}^{\infty} (x_{i} - c)^{2}p_{i} = \infty \text{ and } \int_{-\infty}^{\infty} x^{2}f(x)dx = \infty \text{ implies } \int_{-\infty}^{\infty} (x - c)^{2}f(x)dx = \infty \text{ for any value of } c.$ • It can be proved that if  $E(\xi^{2})$  exists, so does  $E(\xi)$ . • Let  $\xi$  be a continuous random variable with probability density function  $f(x) = \begin{cases} 0 & \text{if } x \le 1 \\ \frac{2}{x^{3}} & \text{if } 1 < x \end{cases}$ Then the expectation of the random variable is  $E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x)dx = \int_{1}^{\infty} x \cdot \frac{2}{x^{3}}dx = 2 \cdot \int_{1}^{\infty} \frac{1}{x^{2}}dx = 2 \cdot \left[-\frac{1}{x}\right]_{1}^{\infty} = 2\left(\left(\lim_{x \to \infty} -\frac{1}{x}\right) - (-1)\right) = 2(0+1) = 2$ .  $E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2} \cdot f(x)dx = \int_{1}^{\infty} x^{2} \cdot \frac{2}{x^{3}}dx = 2 \cdot \int_{1}^{\infty} \frac{1}{x}dx = 2 \cdot \left[\ln x\right]_{1}^{\infty} = 2\left(\left(\lim_{x \to \infty} \ln x\right) - (-1)\right) = \infty.$ 

Consequently,  $E(\xi)$  exists, but  $D(\xi)$  does not.

### Example

E1. Roll a die twice repeatedly. Let  $\xi$  be the maximum of the results. Compute the dispersion of  $\xi$ . First we have to determine the distribution of  $\xi$ . It is easy to see that

$$\xi \sim \left(\frac{1}{36} \quad \frac{2}{36} \quad \frac{3}{36} \quad \frac{4}{56} \quad \frac{5}{9} \quad \frac{6}{11} \\ \frac{1}{36} \quad \frac{3}{36} \quad \frac{5}{36} \quad \frac{7}{36} \quad \frac{9}{36} \quad \frac{11}{36}\right).$$

$$E(\xi) = 1 \cdot \frac{1}{36} + 2 \cdot \frac{3}{36} + 3 \cdot \frac{5}{36} + 4 \cdot \frac{7}{36} + 5 \cdot \frac{9}{36} + 6 \cdot \frac{11}{36} = 4.472.$$

$$E(\xi^{2}) = 1^{2} \cdot \frac{1}{36} + 2^{2} \cdot \frac{3}{36} + 3^{2} \cdot \frac{5}{36} + 4^{2} \cdot \frac{7}{36} + 5^{2} \cdot \frac{9}{36} + 6^{2} \cdot \frac{11}{36} = \frac{791}{36} = 21.972.$$
Applying the above theorem,
$$D(\xi) = \sqrt{E(\xi^{2}) - (E(\xi))^{2}} = \sqrt{21.972 - 4.472^{2}} = \sqrt{1.973} = 1.405$$

E2. Choose two numbers from the interval [0,1] independently by geometrical probability. Let  $\xi$  be the difference between the two numbers. Compute the dispersion of

 $\xi$ . Recall from E8. in subsection d3 that the probability density function of  $\xi$  looks

$$f(x) = \begin{cases} 2 - 2x & \text{if } 0 \le x \le 1\\ 0 & \text{otherwise} \end{cases}$$

We need  $E(\xi)$  and  $E(\xi^2)$ .

$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{1} x \cdot (2 - 2x) dx = \left[ x^{2} - \frac{2x^{3}}{3} \right]_{0}^{1} = \frac{1}{3}.$$

$$E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2} \cdot f(x) dx = \int_{0}^{1} x^{2} \cdot (2 - 2x) dx = \left[ \frac{2x^{3}}{3} - \frac{2x^{4}}{4} \right]_{0}^{1} = \frac{1}{6}.$$

$$D(\xi) = \sqrt{\frac{1}{6} - \left(\frac{1}{3}\right)^{2}} = \sqrt{\frac{1}{18}} = 0.236.$$

Now we list the most important properties of the variance and dispersion. As variance and dispersion are in close connection, we deal with their properties together.

### Properties of the variance and dispersion

Let  $\xi$  and  $\eta$  be random variables with dispersion  $D(\xi)$  and  $D(\eta)$ , respectively, a, b, c are constant values.

1. If  $\xi = c$ , then  $D^2(\xi) = D(\xi) = 0$ . It is obvious, as  $E(\xi) = c$ ,  $(\xi - E(\xi))^2 = 0$ , and E(0) = 0.

2. If  $D(\xi) = 0$ , then  $P(\xi = c) = 1$ . Consequently, zero value for dispersion characterizes the constant random variable.

3. 
$$D^{2}(a\xi + b) = a^{2}D^{2}(\xi)$$
 and  $D(a\xi + b) = |a|D(\xi)$ .

Take into consideration that  $E(a\xi + b) = aE(\xi) + b$ ,

$$E((a\xi + b - (aE(\xi) + b))^2) = E(a^2(\xi - E(\xi))^2) = a^2 E((\xi - E(\xi))^2) = a^2 D^2(\xi).$$

 $D(a\xi + b) = \sqrt{a^2 D^2(\xi)} = |a| D(\xi).$ 

4. Let  $\xi$  be a random variable with dispersion  $D(\xi)$ . Now the value of  $g(c) = E((\xi - c)^2)$  is minimal, if  $c = E(\xi)$ . Take into consideration that  $g(c) = E((\xi - c)^2) = c^2 - 2cE(\xi) + (E(\xi))^2$  is a quadratic polynomial of c. Moreover, the coefficient of  $c^2$  is positive, therefore the function has minimum value. If we take its derivative,  $g'(c) = -2c + 2E(\xi)$ . It is zero if and only if  $c = E(\xi)$  which implies our statement.

5. If  $\xi$  is a random variable for which  $a \le \xi \le b$  holds, then its dispersion exists. If it is denoted by  $D(\xi)$ , then  $D(\xi) \le \frac{b-a}{2}$ . If  $\xi$  is discrete, then  $E(\xi^2) = \sum_{i=1}^{\infty} x_i^2 p_i \le \max\{a^2, b^2\} \cdot \sum_{i=1}^{\infty} p_i = \max\{a^2, b^2\} < \infty$ . If  $\xi$  is

continuous, then  $E(\xi^2) = \int_{-\infty}^{\infty} x^2 f(x) dx \le \max\{a^2, b^2\} \cdot \int_{-\infty}^{\infty} f(x) dx = \max\{a^2, b^2\} < \infty$ , which

proves the existence of dispersion. Applying the properties of expectation we can write for any value of  $x \in R$ ,

$$D^{2}(\xi) = E((\xi - E(\xi))^{2}) \le E((\xi - x)^{2}) \le (a - x)^{2} P(\xi < x) + (b - x)^{2} P(\xi \ge x) =$$
  
=  $(a - x)^{2} - (a - x)^{2} P(\xi \ge x) + (b - x)^{2} P(\xi \ge x) = (a - x)^{2} + (b - a)(b + a - 2x)P(\xi \ge x).$ 

Substituting  $x = \frac{a+b}{2}$ , b+a-2x=0,  $(a-x)^2 = \left(\frac{b-a}{2}\right)^2$ . We get that

$$D^{2}(\xi) \leq \frac{(b-a)^{2}}{4}$$
, therefore  $D(\xi) \leq \frac{b-a}{2}$ . We note that in case of  $\xi \sim \begin{pmatrix} a & b \\ 0.5 & 0.5 \end{pmatrix}$ 

 $D(\xi) = \frac{b-a}{2}$ . Consequently, the inequality can not be sharpened.

6. If  $\xi$  and  $\eta$  are independent, then  $D^2(\xi + \eta) = D^2(\xi) + D^2(\eta)$  and  $D(\xi + \eta) = \sqrt{D^2(\xi) + D^2(\eta)}$ .

 $D^{2}(\xi + \eta) = E((\xi + \eta - E(\xi) - E(\eta))^{2}) = E((\xi - E(\xi))^{2}) + E((\eta - E(\eta))^{2}) + 2 \cdot E((\xi - E(\xi) \cdot (\eta - E(\eta)))$ Recall that if  $\xi$  and  $\eta$  are independent then  $E(\xi \cdot \eta) = E(\xi)E(\eta)$ , therefore  $E((\xi - E(\xi) \cdot (\eta - E(\eta))) = E((\xi - E(\xi)) \cdot E((\eta - E(\eta))) = 0.$ 

We would like emphasize that the dispersions can not be summed, only the variances. Namely, it is important to remember, that  $D(\xi + \eta) \neq D(\xi) + D(\eta)$ . This fact has very important consequences when taking average of random variables.

7. Let  $\xi_i$  i=1,2,...,n be independent identically distributed random variables with

dispersion  $D(\xi_i) = \sigma$ . Then  $D^2(\sum_{i=1}^n \xi_i) = n \cdot \sigma^2$  and  $D(\sum_{i=1}^n \xi_i) = \sqrt{n} \cdot \sigma$ . This is the straightforward consequence of the above properties, namely  $D^2(\sum_{i=1}^n \xi_i) = \sum_{i=1}^n D^2 \xi_i) = n \cdot \sigma^2$ .

8. Let  $\xi_i$  i=1,2,...,n be independent identically distributed random variables with

dispersion  $D(\xi_i) = \sigma$ . Then  $D^2(\frac{\sum_{i=1}^n \xi_i}{n}) = \frac{\sigma^2}{n}$  and  $D(\frac{\sum_{i=1}^n \xi_i}{n}) = \frac{\sigma}{\sqrt{n}}$ . This is again the

straightforward consequence of properties 3 and 7.

# e.3. Mode

Expectation is the weighted average of the possible values and it may be out of the set of possible values. A very simple example is the random variable taking values 0 and 1 with probabilities 0.5. In that case the distribution of  $\xi$  is given by  $\xi \sim \begin{pmatrix} 0 & 1 \\ 0.5 & 0.5 \end{pmatrix}$ ,  $E(\xi) = 0.0.5 + 1.0.5 = 0.5$ , and 0.5 is not between the possible values of  $\xi$ . Mode is in the set of the possible values and the most probable value among them. Definition Let be discrete random variable with distribution ٤ ( ---------

$$\xi = \begin{pmatrix} x_1 & x_2 & \dots & x_n & \dots \\ p_1 & p_2 & \dots & p_n & \dots \end{pmatrix}.$$
 The **mode** of  $\xi$  is  $x_k$ , if  $p_i \le p_k$ ,  $i = 1, 2, 3, \dots$ .

<u>Definition</u> Let  $\xi$  be continuous random variable with probability density function f(x). **Mode** of  $\xi$  is x if f has its local maximum at x, and the maximum value is not zero.

### Remark

• Mode of a discrete random variable exists. If it has finite values then the maximum of a finite set exists. If it has infinitely many values, then only the probability 0 may have infinitely many probabilities in its neighbourhood. The remaining part of the probabilities is a finite set, it must have maximum value, and the index belonging to it marks the mode.

• Mode of a discrete random variable may not be unique. For example, consider

 $\xi \sim \begin{pmatrix} 0 & 1 \\ 0.5 & 0.5 \end{pmatrix}$ . Now both possible values have equal likelihood.

• Mode of a continuous random variable is more complicated case, as the probability density functions may be changed at any point and the distribution of the random variable does not change. Consequently we usually deal with the mode of such continuous random variables which have continuous probability function on finitely many subintervals. We consider the maximum of these functions in the inner parts of the subintervals, and they are the modes. Consequently, mode of a continuous random variable may not exist, see for

example the following probability density function:  $f(x) = \begin{cases} e^{-x} & 0 < x \\ 0 & \text{if } x \le 0 \end{cases}$ . It has its maximum

value at zero, at the endpoint of the interval  $[0,\infty)$  and no other maximum value exists.



Figure e.1. Probability density function without local maximum

• Mode of a continuous random variable may be unique, see for example

$$f(x) = \begin{cases} 7(e^{-x} + x^3 e^{-x}) & \text{if } 0 < x \\ 0 & \text{if } x < 0 \end{cases}$$

The graph of this probability density function can be seen in Fig.e.2.



Figure e.2. Probability density function with unique local maximum

The maximum can be determined by taking the derivative of f(x) and finding where the derivative equals zero. Namely,

$$f'(x) = \begin{cases} 7 \cdot (-e^{-x} + 3x^2 e^{-x} - x^3 e^{-x}) & \text{if } 0 < x \\ 0 & \text{if } x \le 0 \end{cases}$$

f'(x) = 0 implies  $-e^{-x} + 3x^2e^{-x} - x^3e^{-x} = 0$  which means that  $-1 + 3x^2 - x^3 = 0$ . It is satisfied at x=2. 8794 and x=0.6527. At x=0.6527 the function takes its minimum, at x=2. 8794 the function takes its maximum. Consequently, the mode is 2.8794.

• Mode of a continuous random variable may not be unique. If the probability density

function of the random variable is  $f(x) = \frac{1}{2\sqrt{2\pi}} (e^{\frac{-x^2}{2}} + e^{\frac{-(x-5)^2}{2}})$ , it has two maximum

values, one of them is about zero, the other one is about 5. Consequently, two modes exist.



Figure e.3. Probability density function with double local maximums

## e.4. Median

Mode is the most likely value of the random variable, median is the middle one. Namely, the random variable takes values with equal chance under and below the median. More precisely, the probability of taking values at least median and at most median, both are at least 0.5

<u>Definition</u>  $\xi$  is a random variable. **Median** of  $\xi$  is the value y, if  $0.5 \le P(\xi \le y)$  and  $0.5 \le P(y \le \xi)$ .

## <u>Remark</u>

• If  $\xi$  is continuous random variable with cumulative distribution function F(x), then the median of  $\xi$  is the value y for which F(y) = 0.5 holds. The inequality  $0.5 \le P(y \le \xi) = 1 - F(y)$  implies  $F(y) \le 0.5$ . Taking into account that  $\xi$  is continuous random variable,  $P(\xi \le y) = P(\xi < y) = 0.5$ , therefore  $0.5 \le P(\xi \le y) = F(y)$ . Consequently, F(y) = 0.5. As the function F is continuous, and it tends to 0 if x tends to  $-\infty$  and it tends to 1 if x tends to infinity, therefore the median of a continuous random variable exists, but may not be unique.

• Let  $\xi$  be a discrete random variable. Median of  $\xi$  is the value y for which  $F(y) \le 0.5$  and  $0.5 \le F(y+)$ .  $0.5 \le P(y \le \xi) = 1 - F(y)$  implies  $F(y) \le 0.5$ , and  $0.5 \le P(\xi \le y) = \lim_{a \to y+} F(a) = F(y+)$  is the second inequality.

Examples

E1. Consider a random variable with cumulative distribution function  $F(x) = \begin{cases} 0 & \text{if } x \le 0 \\ 1 - (1 - x)^2 & \text{if } 0 < x \le 1 . \\ 1 & \text{if } 1 < x \end{cases}$ 

Determine the median of the random variable.

We have to find the cross point of F(x) and y=0.5. As the function takes the value 0.5 in the case [0,1], we have to solve equation  $1-(1-x)^2=0.5$ . It implies the equality  $2x - x^2 = 0.5$ , therefore  $x_1 = 0.293$ , and  $x_2 = 1.707$ . This last number is out of interval [0,1], consequently median is 0.293. As a checking,  $F(0.293) = 1 - (1 - 0.293)^2 = 0.5001$ .



Figure e.5. Cross point of the cumulative distribution function and line y = 0.5

E2. Let  $\xi$  be a discrete random variable with distribution  $\xi = \begin{pmatrix} 0 & 1 & 5 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$ .

Determine the median of  $\,\xi\,.$ 

$$F(x) = \begin{cases} 0 & ha \ x \le 0 \\ \frac{1}{3} & ha \ 0 < x \le 1 \\ \frac{2}{3} & ha \ 1 < x \le 5 \\ 1 & ha \ 5 < x \end{cases}.$$

Now  $F(x) \neq 0.5$ .  $P(\xi \le 1) = \frac{2}{3}$ ,  $P(1 \le \xi) = \frac{2}{3}$ , both of them are greater than 0.5. Any other value of x does not satisfy this property. Consequently the unique median is 1.



Figure e.6. Cumulative distribution function of the random variable  $\xi$  and the line y = 0.5Median equals the argument when the cumulative distribution function jumps the level 0.5.

E3. Let  $\xi$  be a discrete random variable with distribution  $\xi \sim \begin{pmatrix} 2 & 5 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$ .

Determine the median of  $\xi$ .

Now  $F(x) = \begin{cases} 0 \text{ if } x \le 2 \\ \frac{1}{2} \text{ if } 2 < x \le 5, \text{ and } F(x) \text{ takes value } 0.5 \text{ in the interval } (2,5]. P(\xi \le 2) = 0.5, \\ 1 \text{ if } 5 < x \end{cases}$ 

 $P(\xi \ge 2) = 0.5$ , consequently x = 2 is median. Moreover,  $P(\xi \le x) = P(\xi \ge x) = 0.5$  holds for any values of [2,5). Therefore, they are all median. Usually the middle of the interval (actually 3.5) is used for the value of median.



Figure e.7. Cumulative distribution function of the random variable  $\xi$  and the line y = 0.5

## The aim of this chapter

In the previous chapters we have got acquainted with the concept of random variables. Now we investigate some frequently used types. We compute their numerical characteristics, study their main properties, as well. We highlight their relationships.

## Preliminary knowledge

Random variables and their numerical characteristics. Computing numerical series and integrals. Sampling.

## Content

- f.1. Characteristically distributed random variables.
- f.2. Uniformly distributed discrete random variables.
- f.3. Binomially distributed random variables.
- f.4. Hypergeometrically distributed random variables.
- f.5. Poisson distributed random variables.
- f.6. Geometrically distributed random variables.

## f.1. Characteristically distributed random variables

First we deal with a very simple random variable. It is usually used as a tool in solving problems. Let  $\Omega$ ,  $\mathcal{A}$ , and P be given.

<u>Definition</u> The random variable  $\xi$  is called **characteristically distributed random** variable with parameter  $0 \le p \le 1$ , if it takes only two values, namely 0 and 1, furthermore

$$P(\xi=1) = p$$
 and  $P(\xi=0) = 1 - p$ . Briefly written,  $\xi \sim \begin{pmatrix} 0 & 1 \\ 1 - p & p \end{pmatrix}$ .

Example

E1. Let  $A \in \mathcal{A}$ , P(A) = p. Let us define  $\xi : \Omega \to R$  as follows:  $\xi(\omega) = \begin{cases} 1 & \text{if } \omega \in A \\ 0 & \text{if } \omega \notin A \end{cases}$ . Now  $\xi$  is characteristically distributed random variable with

# parameter p.

In terms of event,  $\xi$  equals 1 if A occurs and  $\xi$  equals zero if it does not. Therefore  $\xi$  characterizes the occurrence of event A. It is frequently called as indicator random variable of event A, and denoted by  $\mathbf{1}_A$ .

Numerical characteristics of characteristically distributed random variables:

#### Expectation

$$E(\xi) = p$$
, which is a straightforward consequence of  $E(\xi) = \sum_{i=1}^{2} x_i \cdot p_i = 1 \cdot p + 0 \cdot (1-p) = p$ 

**Dispersion** 

$$\frac{D(\xi)}{D(\xi)} = \sqrt{p \cdot (1-p)} \text{ . As a proof, recall that } D^2(\xi) = E(\xi^2) - (E(\xi))^2 \text{ .}$$

$$E(\xi^2) = \sum_{i=1}^2 x_i^2 \cdot p_i = 1^2 \cdot p + 0^2 \cdot (1-p) = p, \text{ consequently, } D^2(\xi) = p - p^2 = p(1-p) \text{ . This implies the formula } D(\xi) = \sqrt{p(1-p)} \text{ .}$$

#### Mode

There exist two possible values, namely 0 and 1. The most likely of them is 1, if 0.5 < p, and 0, if p < 0.5 and both of them, if p = 0.5.

<u>Median</u>

If p < 0.5, then  $0.5 \le P(\xi \le 0) = 1 - p$  and  $0.5 \le P(0 \le \xi) = 1$ . Consequently, the median equals 0.

If 0.5 < p , then  $0.5 \le P(\xi \le 1) = 1$  and  $0.5 \le P(1 \le \xi) = p$  . Consequently, the median equals 1.

If p=0.5, then  $P(\xi \le x) = 0.5$  and  $P(\xi \ge x) = 0.5$  for any value of (0,1). Moreover,  $P(\xi \le 0) = 0.5$ ,  $P(\xi \ge 0) = 1$ , and  $P(\xi \le 1) = 1$  and  $P(\xi \ge 1) = 0.5$ . This means that any point of [0,1] is median.

<u>Theorem</u> If A and B are independent events, then  $\mathbf{1}_A$  and  $\mathbf{1}_B$  are independent random variables.

$$\frac{\text{Proof}}{P(\mathbf{1}_{A} = 1 \cap \mathbf{1}_{B} = 1) = P(A \cap B) = P(A) \cdot P(B) = P(\mathbf{1}_{A} = 1) \cdot P(\mathbf{1}_{B} = 1) .$$

$$P(\mathbf{1}_{A} = 1 \cap \mathbf{1}_{B} = 0) = P(A \cap \overline{B}) = P(A) \cdot P(\overline{B}) = P(\mathbf{1}_{A} = 1) \cdot P(\mathbf{1}_{B} = 0) .$$

$$P(\mathbf{1}_{A} = 0 \cap \mathbf{1}_{B} = 1) = P(\overline{A} \cap B) = P(\overline{A}) \cdot P(B) = P(\mathbf{1}_{A} = 0) \cdot P(\mathbf{1}_{B} = 1) .$$

$$P(\mathbf{1}_{A} = 0 \cap \mathbf{1}_{B} = 0) = P(\overline{A} \cap \overline{B}) = P(\overline{A}) \cdot P(B) = P(\mathbf{1}_{A} = 0) \cdot P(\mathbf{1}_{B} = 0) .$$

### f.2. Uniformly distributed discrete random variables

The second type of discrete random variables applied frequently is uniformly distributed random variable. In this subsection we deal with discrete ones.

<u>Definition</u> The discrete random variable  $\xi$  is called uniformly **distributed random** variable, if it takes finite many values, and the probabilities belonging to the possible values are equal. Shortly written,  $\xi \sim \begin{pmatrix} x_1 & x_2 & ... & x_n \\ p_1 & p_2 & ... & p_n \end{pmatrix}$ ,  $p_i = p_j$ , i = 1, 2, ..., n, j = 1, 2, ..., n.

<u>Remarks</u>

• As 
$$1 = \sum_{i=1}^{n} p_i = np_1$$
,  $p_1 = p_2 = \dots = p_n = \frac{1}{n}$ .  $\xi = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ \frac{1}{n} & \frac{1}{n} & \dots & \frac{1}{n} \end{pmatrix}$ .

• There is no discrete uniformly distributed random variable if the set of possible values contains infinitely many elements. This is the straightforward consequence of the condition  $1 = \sum_{i=1}^{\infty} p_i$ . With notation  $P(\xi = x_i) = p$ , if p = 0 then  $\sum_{i=1}^{\infty} 0 = 0$ , if 0 < p,  $\sum_{i=1}^{\infty} p = \infty$ .

Numerical characteristics of uniformly distributed random variables:

Expectation

$$E(\xi) = \sum_{i=1}^{n} x_i \frac{1}{n} = \overline{x}.$$

Dispersion

$$D(\xi) = \sqrt{\frac{\sum_{i=1}^{n} x_i^2}{n} - \left(\frac{\sum_{i=1}^{n} x_i}{n}\right)^2},$$

which can be computed by substituting into the formula

concerning the dispersion.

#### Mode

All of possible values have the same chance, all of them are mode.

Median

$$\frac{x_{\frac{n-1}{2}} + x_{\frac{n+1}{2}}}{2}$$
 if n is odd, and  $x_{\frac{n}{2}}$  if n is even.

Example

E1. Throw a die, let  $\xi$  be the square of the result. Actually,  $\xi = \begin{pmatrix} 1 & 4 & 9 & 16 & 25 & 36 \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \end{pmatrix}$ . As all possible values have the same chance,  $\xi$  is uniformly

distributed random variable. Note that there is no requirement for the possible values.

#### f.3. Binomially distributed random variable

After the above simple distributions actually we consider a more complicated one.

<u>Definition</u> The random variable  $\xi$  is called **binomially distributed random variable** with parameters  $2 \le n$  and 0 , if its possible values are <math>0,1,2,...,n and  $P(\xi = k) = {n \choose k} \cdot p^k (1-p)^{n-k}$ , k = 0,1,2,...,n.

Remark

• It is obvious that 
$$0 \le P(\xi = k) = {n \choose k} \cdot p^k (1-p)^{n-k}$$
. Furthermore, binomial theorem

implies that  $\sum_{k=0}^{n} P(\xi = k) = \sum_{k=0}^{n} {n \choose k} \cdot p^{k} (1-p)^{n-k} = 1.$  Recalling that  $(a+b)^{n} = \sum_{k=0}^{n} {n \choose k} a^{k} b^{n-k}$ , and substituting a = p and b = 1-p, we get a+b = p+1-p=1.

<u>Theorem If</u>  $\xi_i$  i = 1,2,...,n are independent characteristically distributed random variables with parameter  $0 , then <math>\eta = \sum_{i=1}^{n} \xi_i$  is binomially distributed random variable with parameters n and p.

Proof Recall that  $\xi_i \sim \begin{pmatrix} 0 & 1 \\ 1-p & p \end{pmatrix}$ . Their sum can take any integer from 0 to n.  $P(\sum_{i=1}^n \xi_i = 0) = P(\xi_1 = 0 \cap \xi_2 = 0 \cap \dots \cap \xi_n = 0) = P(\xi_1 = 0) \cdot P(\xi_2 = 0) \cdot \dots \cdot P(\xi_n = 0) = (1-p)^n$ 

$$P(\sum_{i=1}^{n} \xi_{i} = 1) = n \cdot P(\xi_{1} = 1 \cap \xi_{2} = 0 \cap \dots \cap \xi_{n} = 0) = P(\xi_{1} = 1) \cdot P(\xi_{2} = 0) \cdot \dots \cdot P(\xi_{n} = 0) = n \cdot p \cdot (1 - p)^{n-1}$$

Multiplier n is included because the event A can occur at any experiment, not only at the first one.

$$P(\xi_{1} = 1 \cap \xi_{2} = 1 \cap ... \cap \xi_{k} = 1 \cap \xi_{k+1} = 0 \cap ... \cap \xi_{n} = 0) = P(\xi_{1} = 1) \cdot P(\xi_{2} = 1) \cdot ... \cdot P(\xi_{k} = 1) \cdot P(\xi_{k+1} = 0) \cdot ... \cdot P(\xi_{n} = 0) = p^{k} \cdot (1 - p)^{n-k}$$

If the event A occurs k times, then the serial numbers of experiments when A occurs can be

chosen  $\binom{n}{k}$  times, consequently,  $P(\sum_{i=1}^{n} \xi_i = k) = \binom{n}{k} \cdot p^k \cdot (1-p)^{n-k}$ .

<u>Theorem</u> Repeat n times a trial, independently of each other. Let A be an event with probability P(A) = p,  $0 . Let <math>\xi$  be that number how many times the event A occurs during the n independent experiments. Then  $\xi$  is binomially distributed random variable with parameter n and p.

Proof:

Let  $\mathbf{1}_{\mathbf{A}^{i}} = \begin{cases} 1 \text{ if } A \text{ occurs at the ith experiment} \\ 0 \text{ if } A \text{ does not occurs at the ith experiment} \end{cases}$ .

Taking into account that the experiments are independent, so are  $\mathbf{1}_{A}^{i}$ , i=1,2,...,n.

As  $\xi = \sum_{i=1}^{n} \mathbf{1}_{A}^{i}$ ,  $\xi$  is the sum of n independent indicator random variable, consequently,  $\xi$  is binomially distributed random variable.

### Examples

E1. Throw n times a fair die. Let  $\xi$  be the number of "6". Then  $\xi$  is binomially distributed random variable with parameter n and  $p = \frac{1}{6}$ .

E2. Flip n times a coin. Let  $\xi$  be the number of heads. Then  $\xi$  is binomially distributed random variable with parameter n and  $p = \frac{1}{2}$ .

E3. Throw n times a die. Let  $\xi$  be the number of even numbers. Then  $\xi$  is binomially distributed random variable with parameters n and  $p = \frac{1}{2}$ . We note that the random variable being in this example is identically distributed random variables with the random variable presented in E2..

E4. Draw 10 cards with replacement from the pack of French cards. Let  $\xi$  be the number of diamonds among the picked cards. Then  $\xi$  is binomially distributed random variable with parameters n = 10,  $p = \frac{8}{32}$ .

E5. Draw 10 cards with replacement from the pack of cards. Let  $\xi$  be the number of aces among the picked cards. Then  $\xi$  is binomially distributed random variable with parameters n = 10,  $p = \frac{4}{32}$ .

E6. There are N balls in an urn, M of them are red, N-M are white. Pick n with replacement among them. Let  $\xi$  be the number of red balls among the chosen ones.  $\xi$  is the

number of events when we succeed in choosing red balls during n experiments.  $\xi$  is binomially distributed random variable with parameters n and  $p = \frac{M}{N} \cdot (2 \le N, 1 \le M, 1 \le N - M, 2 \le n)$ 

Numerical characteristics of binomially distributed random variables

Expectation

$$\begin{split} E(\xi) &= np, & \text{which} \quad \text{is a straightforward consequence of} \\ E(\xi) &= E(\sum_{i=1}^{n} \mathbf{1}_{A}^{i}) = \sum_{i=1}^{n} E(\mathbf{1}_{A}^{i}) = \sum_{i=1}^{n} p = np. \\ \underline{\text{Dispersion}} \\ \overline{D(\xi)} &= \sqrt{np \cdot (1-p)} \,. \end{split}$$

As an explanation take into consideration that, as  $1^{i}_{A}$  (i = 1,2,...,n) are independent,

$$D^{2}(\xi) = D^{2}(\sum_{i=1}^{n} \mathbf{1}_{i}) = nD^{2}(\mathbf{1}_{i}) = n \cdot p$$
. This implies  $D(\xi) = \sqrt{np \cdot (1-p)}$ .

Mode

If (n + 1)p is integer, then there are two modes, namely  $(n + 1) \cdot p$  and (n + 1)p - 1. If (n + 1)p is not integer, then there is a unique mode, namely  $[(n + 1) \cdot p]$ .

As an explanation, investigate the ratio of probability of consecutive possible values.

$$\frac{P(\xi = k)}{P(\xi = k - 1)} = \frac{\binom{n}{k} p^{k} \cdot (1 - p)^{n-k}}{\binom{n}{k-1} p^{k-1} \cdot (1 - p)^{n-(k-1)}} = \frac{\frac{n!}{k!(n-k)!}}{\frac{n!}{(k-1)!(n-k+1)!}} \cdot \frac{p}{1-p} = \frac{n-k+1}{k} \cdot \frac{p}{1-p},$$

$$k = 1, 2, ..., n.$$

$$1 < \frac{P(\xi = k)}{P(\xi = k - 1)} \text{ implies that } P(\xi = k - 1) < P(\xi = k), \text{ that is the probabilities are growing.}$$

$$\frac{P(\xi = k)}{P(\xi = k - 1)} < 1 \text{ implies that } P(\xi = k) < P(\xi = k - 1), \text{ that is the probabilities are decreasing.}$$

$$\frac{P(\xi = k)}{P(\xi = k - 1)} < 1 \text{ then } P(\xi = k) = P(\xi = k - 1).$$

$$1 < \frac{n-k+1}{k} \cdot \frac{p}{1-p} \text{ holds, if only if } k < (n+1)p. \quad \frac{n-k+1}{k} \cdot \frac{p}{1-p} < 1 \text{ holds, if and only if } (n+1) \cdot p < k, \text{ and } \frac{n-k+1}{k} \cdot \frac{p}{1-p} = 1 \text{ holds if and only if } k = (n+1) \cdot p.$$
This is satisfied only in the case, if  $(n+1)p$  is integer. Therefore, if  $(n+1)p$  is not integer, then, up to  $k = [(n+1)p]$ , the probabilities are growing, after that the probabilities are decreasing. Consequently, the most probable value is  $[(n+1)p]$ . If  $(n+1)p$ ,  $(n+1)p-1$ .



Figure f.1. Probabilities of possible values of a binomially distributed random variable with parameters n = 10 and p = 0.2

Without proof we can state the following theorem:

#### **Theorem**

If  $\xi_1$  is binomially distributed random variable with parameters  $n_1$  and p,  $\xi_2$  is binomially distributed random variable with parameters  $n_2$  and p, furthermore they are independent, then  $\xi_1 + \xi_2$  is also binomially distributed with parameters  $n_1 + n_2$  and p.

As an illustration, if  $\xi_1$  is the number of "six" if we throw a fair die repeatedly  $n_1$  times,  $\xi_2$  is the number of "six" if we throw a fair die  $n_2$  times, then  $\xi_1 + \xi_2$  is the number of "six" if we throw a fair die  $n_1 + n_2$  times, which is also binomially distributed random variable.

#### Theorem

If  $\xi_n$  is sequence of binomially distributed random variables with parameters n and  $q_n$ , furthermore  $n \cdot q_n = \lambda$ , k is a fixed value, then  $P(\xi_n = k) = \binom{n}{k} (q_n)^k (1 - q_n)^{n-k} \rightarrow \frac{\lambda^k}{k!} e^{-\lambda}$ , if  $n \rightarrow \infty$ . <u>Proof</u> Substitute  $q_n = \frac{\lambda}{n}$ ,  $P(\xi_n = k) = \binom{n}{k} (q_n)^k (1 - q_n)^{n-k} = \frac{n!}{k!(n-k)!} \frac{\lambda^k}{n^k} (1 - \frac{\lambda}{n})^{n-k} = \frac{n(n-1)(n-2)....(n-k+1)}{n^k} (1 - \frac{\lambda}{n})^{-k} \frac{\lambda^k}{k!} (1 - \frac{\lambda}{n})^n$ . Taking separately the multipliers,  $\frac{n(n-1)(n-2)....(n-k+1)}{n^k} = \frac{n-1}{n} \cdot \frac{n-2}{n} \cdot ... \cdot \frac{n-k+1}{n} \rightarrow 1$ , if  $n \rightarrow \infty$ , as each multiplier

tends to 1, and k is fixed.

Similarly, 
$$\left(1 - \frac{\lambda}{n}\right)^{-k} \to 1$$
, if  $n \to \infty$ .  
As  $\left(1 + \frac{x}{n}\right)^n \to e^x$  if  $n \to \infty$ , consequently,  $\left(1 - \frac{\lambda}{n}\right)^n \to e^{-\lambda}$ , if  $n \to \infty$ .  
Summarizing,  $P(\xi_n = k) = {n \choose k} (q_n)^k (1 - q_n)^{n-k} \to \frac{\lambda^k}{k!} e^{-\lambda}$  supposing  $n \to \infty$ 

Example

E7. There are 10 balls and 5 boxes. We put the balls into the boxes, one after the other. We suppose that all balls fall into any box with equal chance, independently of the other balls. Compute the probability that there is no ball in the first box. Compute the probability that there is one ball in the first box. Compute the probability that there are two balls in the first box. Compute the probability that there are at most two balls in the first box. Compute the expectation of the balls being the first box. How many balls are in the first box most likely? Let  $\eta$  be the number of the balls in the first box.  $\eta$  is binomially distributed random

variable with parameters n = 10 and  $p = \frac{1}{5}$ . We can give the explanation of this statement as follows: we repeat 10 times that experiment that we put a ball into a box. We regard if the ball falls into the first box or no. If  $\eta$  is the number of balls in the first box, then  $\eta$  is the number of occurrences of the event A ="actual ball has fallen into the first box". It is easy to see that  $P(A) = \frac{1}{5}$ . Therefore, the possible values of  $\eta$  are 0,1,2,...,10, and the  $(10)(1)^k(-1)^{10-k}$ 

probabilities are  $P(\eta = k) = {\binom{10}{k}} {\binom{1}{5}}^k {\binom{1-\frac{1}{5}}{}^{10-k}}, \ k = 0,1,2,...,10.$ 

If we calculate the probabilities, we get

$$P(\eta = 0) = {\binom{10}{0}} {\binom{1}{5}}^0 {\binom{1-\frac{1}{5}}{1-\frac{1}{5}}}^{10} = 0.1074, P(\eta = 1) = {\binom{10}{1}} {\binom{1}{5}}^1 {\binom{1-\frac{1}{5}}{1-\frac{1}{5}}}^9 = 0.2684,$$

$$P(\eta = 2) = {\binom{10}{2}} {\binom{1}{5}}^2 {\binom{1-\frac{1}{5}}{8}}^8 = 0.3020, \ P(\eta = 3) = {\binom{10}{3}} {\binom{1}{5}}^3 {\binom{1-\frac{1}{5}}{7}}^7 = 0.2013, \dots,$$
  

$$P(\eta = 10) = {\binom{10}{10}} {\binom{1}{5}}^{10} {\binom{1-\frac{1}{5}}{9}}^0 = 10^{-7}. \ \text{In details,}$$
  

$$\eta \sim {\binom{0}{1074}} {\binom{1}{0.2884}} {\binom{1}{0.3020}} {\binom{1}{0.2013}} {\binom{1}{0.08808}} {\binom{1}{0.0264}} {\binom{1}{0.0055}} {\binom{1}{0.0007}} {\binom{1}{10^{-4}}} {\binom{1}{10^{-5}}} {\binom{1}{10^{-7}}} {\binom{1}{10^{-7}}}$$

Returning to our questions, the probability that there is no ball in the first box is

$$P(\eta = 0) = {\binom{10}{0}} {\binom{1}{5}}^0 {\binom{1-\frac{1}{5}}{1}}^{10} = 0.1074.$$
  
The probability that there is one ball in the first box equals  
$$P(\eta = 1) = {\binom{10}{1}} {\binom{1}{5}}^1 {\binom{1-\frac{1}{5}}{9}}^9 = 0.2684.$$

The probability that there are two balls in the first box is  $P(\eta = 2) = {\binom{10}{2}} {\left(\frac{1}{5}\right)^2} {\left(1 - \frac{1}{5}\right)^8} = 0.3020.$ 

The probability that there are at most two balls in the first box is  $P(\eta \le 2) = P(\eta = 0) + P(\eta = 1) + P(\eta = 2) = 0.1074 + 0.2684 + 0.3020 = 0.6778.$ 

The probability that there are at least two balls in the first box can be computed as  $P(2 \le \eta) = P(\eta = 2) + P(\eta = 3) + ... + P(\eta = 10) = 0.3020 + 0.2013 + 0.0088 + ... + 10^{-7} = 0.6242$ , or in a simpler way,

$$P(2 \le \eta) = 1 - (P(\eta = 0) + P(\eta = 1)) = 1 - (0.1074 + 0.2684) = 1 - 0.3758 = 0.6242.$$

The expectation of the balls being in the first box is  $E(\eta) = 10 \cdot \frac{1}{5} = 2$ , which coincides with

the mode, 
$$\left[(n+1)p\right] = \left[11 \cdot \frac{1}{5}\right] = 2$$
.

E8. There are 10 balls and 5 boxes, 100 balls and 50 boxes, 1000 balls and 500 boxes,  $10^n$  balls and  $10^n / 2$  boxes, n = 1, 2, 3, ... Balls are put into the boxes and all of the balls fall into any box with equal probability. Let us denote  $\xi_n = \eta_{10^n}$  the number of balls being in the first box. Let k be fixed and investigate the probabilities  $P(\xi_n = k)$ . Compute the limit of these probabilities.

Referring to the previous example,  $\xi_n$  is binomially distributed random variable with parameters  $10^n$  and  $q(n) = \frac{2}{10^n}$ . The product of the two parameters equals always  $10^n = \frac{2}{10^n}$ .

 $10^{n} \cdot \frac{2}{10^{n}} = 2$ , consequently,  $P(\xi_{n} = k) \rightarrow \frac{2^{k}}{k!} e^{-2}$ , if  $n \rightarrow \infty$ .

In details,

	$\xi_1(10, \frac{1}{5})$	$\xi_2 \ (100, \frac{1}{50})$	$\xi_3 (1000, \frac{1}{500})$	$\xi_3 (10000, \frac{1}{5000})$	•	•	$\frac{2^k}{k!}e^{-\lambda}$
k=0	0.1074	0.1326	0.1351	0.1353	•		0.1353
k=1	0.2684	0.2706	0.2707	0.2707	•		0.2707
k=2	0.3020	0.2734	0.2709	0.2707	•		0.2707
k=3	0.2013	0.1823	0.1806	0.1805	•	•	0.1804

Table f.1. Probabilities of falling k balls in a box in case of different parameters of total number of balls and boxes

We can see that the probabilities computed by the binomial formula are close to their limits, if the number of experiments is large (for example 10000). Consequently, the probabilities of binomially distributed random variables can be approximated by the formula  $\frac{\lambda^k}{k!}e^{-\lambda}$ , called Poisson probabilities.

## f.4. Hypergometrically distributed random variable

After sampling with replacement, we deal with sampling without replacement, as well. The random variable which handles the number of specified elements in the sample if the sampling has been performed without replacement is hypergeometrically distributed random variable.

<u>Definition</u> The random variable  $\xi$  is called **hypergeometrically distributed random** variable with parameters  $2 \le N$ ,  $1 \le S \le N-1$  and  $1 \le n$ ,  $n \le S$ ,  $n \le N-S$  integers, if its

 $(\alpha)$   $(\mathbf{x}, \alpha)$ 

possible values are 0,1,2,...,n and P(
$$\xi = k$$
) =  $\frac{\binom{S}{k} \cdot \binom{N-S}{n-k}}{\binom{N}{n}}$ , k = 0,1,2,...,n.

Example

E1. We have N products, S of them have a special property, N-S have not. We choose n ones among them without replacement. Let  $\xi$  be the number of products with the special property in the sample. Then, the possible values of  $\xi$  are 0,1,2,3,...,n, and the probabilities (referring to the subsection of classical probability) are

$$P(\xi = k) = \frac{\binom{S}{k} \cdot \binom{N-S}{n-k}}{\binom{N}{n}}.$$

<u>Remarks</u>

• The previous example shows that the sum of probabilities  $\frac{\binom{S}{k} \cdot \binom{N-S}{n-k}}{\binom{N}{n}}$  equals 1. The

events ,,there are k products with the special property in the sample" k=0,1,2,...n form a partition of the sample space, consequently the sum of their probabilities equals 1.

• Similarly to the binomially distributed random variable, actually,  $\xi$  can also be written as a sum of indicator random variables, but these random variables are not independent.

Numerical characteristics of hypergeometrically distributed random variables:

Expectation

 $E(\xi) = n \frac{S}{N}.$  This formula can be computed by the definition of expectation as follows:  $E(\xi) = \sum_{k=0}^{n} k \cdot \frac{\binom{S}{k} \cdot \binom{N-S}{n-k}}{\binom{N}{n}} =$ 

$$\sum_{k=0}^{n} k \cdot \frac{\frac{S(S-1)(S-2)...(S-k+1)}{k!} \cdot \frac{(N-S) \cdot (N-S-1) \cdot ... \cdot (N-S-(n-k)+1)}{(n-k)!}}{\frac{N!}{n!(N-n)!}} = \sum_{k=1}^{n} \frac{\frac{S(S-1)(S-2)...(S-k+1)}{(k-1)!} \cdot \frac{(N-S) \cdot (N-S-1) \cdot ... \cdot (N-S-(n-k)+1)}{(n-k)!}}{\frac{N!}{n!(N-n)!}} = \sum_{k=1}^{n} n \frac{\frac{S}{N} \frac{\binom{S-1}{k-1} \binom{N-1-(S-1)}{n-1-(k-1)}}{\binom{N-1}{n-1}}}{\binom{N-1}{(N-1)}} = \sum_{k=1=0}^{n-1} n \frac{\frac{S}{N} \frac{\binom{S-1}{k-1} \binom{N-1-(S-1)}{n-1-(k-1)}}{\binom{N-1}{n-1}}}{\binom{N-1}{(N-1)}} = \sum_{k=1=0}^{n-1} n \frac{\frac{S}{N} \frac{\binom{S-1}{k-1} \binom{N-1-(S-1)}{n-1-(k-1)}}{\binom{N-1}{n-1}}}{\binom{N-1}{n-1}} = 1, \text{ we get the presented closed}$$

of the expectation.

Dispersion

 $\overline{D(\xi)} = \sqrt{n \frac{S}{N} \cdot (1 - \frac{S}{N}) \left(1 - \frac{n-1}{N-1}\right)}$ . We do not prove this formula, because it requires too much computation.

Mode

 $\left[\frac{(S+1)(n+1)}{N+2}\right], \text{ if } \frac{(S+1)(n+1)}{N+2} \text{ is not integer and there are two modes, namely} \\ \frac{(S+1)(n+1)}{N+2} \text{ and } \frac{(S+1)(n+1)}{N+2} - 1, \text{ if } \frac{(S+1)(n+1)}{N+2} \text{ is integer.}$ 

Similarly to the way applied to the binomially distributed random variable we investigate the ratio  $\frac{P(\xi = k)}{P(\xi = k - 1)}$ . Writing it explicitly and making simplification we get

form

$$\frac{P(\xi=k)}{P(\xi=k-1)} = \frac{\frac{\begin{pmatrix} S\\k \end{pmatrix} \cdot \begin{pmatrix} N-S\\n-k \end{pmatrix}}{\begin{pmatrix} N\\n \end{pmatrix}}}{\frac{\begin{pmatrix} S\\k-1 \end{pmatrix} \cdot \begin{pmatrix} N-S\\n-k+1 \end{pmatrix}}{\begin{pmatrix} N\\n-k+1 \end{pmatrix}}} = \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1}.$$
 In order to know for which

indexes the probabilities are growing and the probabilities are decreasing we have solve the inequalities

$$\begin{split} &1 < \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1}, \quad \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1} < 1, \quad \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1} = 1.\\ &\text{After some computation we get that} \\ &1 < \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1} \text{ holds if and only if } k < \frac{(S+1)(n+1)}{N+2}, \\ &\frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1} < 1 \text{ holds if and only if } \frac{(S+1)(n+1)}{N+2} < k \\ &1 = \frac{S-k+1}{k} \cdot \frac{N-S-n+k}{n-k+1} \text{ holds if and only if } k = \frac{(S+1)(n+1)}{N+2}. \text{ This equality can be} \\ &\text{satisfied if } \frac{(S+1)(n+1)}{N+2} \text{ is integer. Consequently, the mode is unique and it equals} \\ &\left[ \frac{(S+1)(n+1)}{N+2} \right], \text{ if } \frac{(S+1)(n+1)}{N+2} - 1 \text{ if } \frac{(S+1)(n+1)}{N+2} \text{ is integer.} \end{split}$$

**Theorem** 

Let 
$$N \to \infty$$
,  $S \to \infty$ ,  $\frac{S}{N} = p$ , and let k, n be fixed integer values.  
Then  $\frac{\binom{S}{k} \cdot \binom{N-S}{n-k}}{\binom{N}{n}} \to \binom{n}{k} p^k (1-p)^{n-k}$ .  
Proof

$$\begin{pmatrix} S \\ S \\ k \end{pmatrix} \cdot \begin{pmatrix} N-S \\ n-k \end{pmatrix} \quad S(S-1)...(S-k+1) \quad (N-S)$$

$$\frac{\binom{k}{n-k}}{\binom{N}{n}} = \frac{S(S-1)...(S-k+1)}{k!} \cdot \frac{(N-S)(N-S-1)...(N-S-n+k+1)}{(n-k)!} \cdot \frac{n!}{N(N-1)...(N-n+1)}$$

The number of multipliers in the numerator is k + n - k = n and so is in the denominator. C 1

Taking into account that 
$$\frac{n!}{k!(n-k)!} = \binom{n}{k}$$
, and  $\frac{S}{N} = p$ ,  $\frac{S-1}{N-1} = \frac{\frac{S}{N} - \frac{1}{N}}{1 - \frac{1}{N}} \rightarrow p$  if  $N \rightarrow \infty$ ,  
 $\frac{S-k+1}{N-k+1} = \frac{\frac{S}{N} - \frac{k}{N} + \frac{1}{N}}{1 - \frac{k}{N} + \frac{1}{N}} \rightarrow p$  if  $N \rightarrow \infty$ , furthermore  $\frac{N-S}{N-k} = \frac{1 - \frac{S}{N}}{1 - \frac{k}{N}} \rightarrow 1 - p$ ,  
 $\frac{(N-S-n+k+1)}{N-n+1} = \frac{1 - \frac{S}{N} - \frac{n}{N} - \frac{k}{N} + \frac{1}{N}}{1 - \frac{n}{N} + \frac{1}{N}} \rightarrow 1 - p$  if  $N \rightarrow \infty$ .

The number of multipliers tending to p equals k, the number of multipliers tending to 1-p (S).(N-S)

equals n-k, consequently 
$$\frac{\binom{k}{n-k}}{\binom{N}{n}} \rightarrow \binom{n}{k} p^k (1-p)^{n-k}$$

## Remark

The meaning of the previous theorem is the following: if the number of all elements • is large and we choose a sample of small elements, then the probabilities of having k elements with a special property in the sample is approximately the same if we take the sample with and without replacement.

#### Example

E1. There are 100 products, 60 of them are of first quality, 40 of them are substandard. Choose 10 of them with/ without replacement. Let  $\xi$  be the number of substandard products in the sample if we take the sample with replacement. Let  $\eta$  be the number of substandard products in the sample if we take the sample without replacement. Give the distribution, expectation, dispersion, mode of both random variables.

 $\xi$  is binomially distributed random variable with parameters n = 10,  $p = \frac{40}{100}$ . This means,

that the possible values of  $\xi$  are 0,1,2,3,...,10, and  $P(\xi = k) = {10 \choose k} 0.4^k 0.6^{10-k}$ .  $\eta$  is

hypergeometrically distributed random variable with parameters N = 100, S = 40, n = 10.

hypergeometrically distributed terms Therefore the possible values of  $\eta$  are 0,1,2,3,..,10 and  $P(\eta = k) = \frac{\begin{pmatrix} 40 \\ k \end{pmatrix} \cdot \begin{pmatrix} 60 \\ 10-k \end{pmatrix}}{\begin{pmatrix} 100 \\ 10 \end{pmatrix}}$ . To

compare the probabilities we write them in the following Table f.2.

k	0	1	2	3	4	5	6	7	8	9	10
$P(\xi = k)$	0.00	0.040	0.12	0.21	0.25	0.20	0.11	0.04	0.01	0.00	0.0001

	6		1	5	1	1	1	2	0	1	
$P(\eta = k)$	0.00	0.003	0.11	0.22	0.26	0.20	0.10	0.03	0.00	0.00	0.0000
	4	4	5	0	4	8	8	7	8	1	4

Table f.2.Probabilities of the numbers of substandard products in the sample in case of sampling with and without replacement

It can be seen that there are very small differences between the appropriate probabilities, therefore it is almost the same if we take the sample with or without replacement.

E(\xi) = 10 · 0.4 = 4, E(\eta) = 10 · 
$$\frac{40}{100}$$
 = 4.  
D(\xi) =  $\sqrt{10 \cdot 0.4 \cdot 0.6}$  = 1.55, D(\eta) =  $\sqrt{10 \cdot \frac{40}{100} \cdot \frac{60}{100} \cdot \left(1 - \frac{9}{99}\right)}$  = 1.48

Mode of  $\xi$  and  $\eta$  are the same values, namely 4, as it can be seen in the Table f.1., or applying the formula  $[(n+1) \cdot p] = [11 \cdot 0.4] = 4$ , or  $\left[\frac{(S+1)(n+1)}{N+2}\right] = \left[\frac{41 \cdot 11}{102}\right] = [4.42] = 4$ , respectively.

E2. There are N balls in a box, S are red, N-S are white. Choose 10 among them without replacement. Compute the probability that there are 4 red balls in the sample if the total number of balls are  $N_1 = 10$ ,  $N_2 = 100$ ,  $N_3 = 1000$ ,  $N_4 = 10000$ ,  $N_4 = 100000$ , and

$S_1 = 4$ , $S_2 = 40$ , $S_3 = 400$ , $S_4 = 4000$ , $S_5 = 40000$ . Notice that $\frac{S_i}{N_i} = p = 0.4$ is contracted by $S_1 = 10000$ .	onstant.
--	----------

					1	
Ν	10	100	1000	10000	100000	limit
$P(\eta_N = 4)$	1	0.26431	0.25209	0.25095	0.25084	0.25082

Table f.3. Probabilities of 4 red balls in the sample in case of different numbers of total balls

One can follow the convergence in Table f.3. very easily on the basis of the computed probabilities. We emphasize that both values n and k are fixed.

#### f.5. Poisson distributed random variable

After investigating sampling without replacement, we return to the limit of probabilities of binomially distributed random variables.

<u>Definition</u> The random variable  $\xi$  is called **Poisson distributed random variable** with

parameter  $0 < \lambda$ , if its possible values are 0,1,2,..., and  $P(\xi = k) = \frac{\lambda^k}{k!} e^{-\lambda}$ , k=0,1,2,...

<u>Remarks</u>

• 
$$0 < \frac{\lambda^k}{k!} e^{-\lambda}$$
 holds obviously, furthermore  $\sum_{k=0}^{\infty} \frac{\lambda^k}{k!} e^{-\lambda} = e^{-\lambda} \cdot \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} = e^{-\lambda} \cdot e^{\lambda} = 1$ .

• The last theorem of subsection f.3. states that the limit of the distribution of binomially distributed random variables is Poisson distribution.

#### Numerical characteristics of Poisson distributed random variables

#### Expectation

 $E(\xi) = \lambda$ . This formula can be proved as follows:

$$E(\xi) = \sum_{k=0}^{\infty} k \cdot \frac{\lambda^k}{k!} e^{-\lambda} = e^{-\lambda} \sum_{k=1}^{\infty} \frac{\lambda^k}{(k-1)!} = \lambda e^{-\lambda} \sum_{k=1}^{\infty} \frac{\lambda^{k-1}}{(k-1)!} = \lambda e^{-\lambda} \sum_{i=0}^{\infty} \frac{\lambda^i}{i!} = \lambda e^{-\lambda} e^{\lambda} = \lambda.$$

## Dispersion

$$\begin{split} & \mathsf{D}(\xi) = \sqrt{\lambda} \text{ . Recall that } \mathsf{D}^{2}(\xi) = \mathsf{E}(\xi^{2}) - \left(\mathsf{E}(\xi)\right)^{2} \text{ .} \\ & \mathsf{E}(\xi^{2}) = \sum_{k=0}^{\infty} k^{2} \cdot \frac{\lambda^{k}}{k!} e^{-\lambda} = \sum_{k=1}^{\infty} k^{2} \cdot \frac{\lambda^{k}}{k!} e^{-\lambda} = \sum_{k=1}^{\infty} k \cdot \frac{\lambda^{k}}{(k-1)!} e^{-\lambda} = e^{-\lambda} \cdot \lambda \sum_{k=1}^{\infty} k \cdot \frac{\lambda^{k-1}}{(k-1)!} = \\ & e^{-\lambda} \cdot \lambda \left( \sum_{k=1}^{\infty} (k-1) \cdot \frac{\lambda^{k-1}}{(k-1)!} + \sum_{k=1}^{\infty} \cdot \frac{\lambda^{k-1}}{(k-1)!} \right) = e^{-\lambda} \cdot \lambda^{2} \sum_{k=2}^{\infty} \frac{\lambda^{k-2}}{(k-2)!} + e^{-\lambda} \cdot \lambda \sum_{k=1}^{\infty} \cdot \frac{\lambda^{k-1}}{(k-1)!} = \\ & e^{-\lambda} \cdot \lambda^{2} \cdot e^{\lambda} + e^{-\lambda} \cdot \lambda \cdot e^{\lambda} = \lambda^{2} + \lambda \text{ . Therefore } \mathsf{D}^{2}(\xi) = \mathsf{E}(\xi^{2}) - \left(\mathsf{E}(\xi)\right)^{2} = \lambda^{2} + \lambda - \lambda^{2} = \lambda \text{ .} \end{split}$$
Finally,  $\mathsf{D}(\xi) = \sqrt{\mathsf{D}^{2}(\xi)} = \sqrt{\lambda}$ .

### Mode

There is a unique mode, namely  $[\lambda]$ , if  $\lambda$  is not integer and there are two modes, namely  $\lambda$  and  $\lambda - 1$  if  $\lambda$  is integer.

Similarly to the way applied in the previous subsections, we investigate the ratio  $2^{k}$ 

$$\frac{P(\xi = k)}{P(\xi = k - 1)}$$
. Writing it explicitly and making simplification we get 
$$\frac{\frac{\lambda}{k!}e^{-\lambda}}{\frac{\lambda^{k-1}}{(k-1)!}e^{-\lambda}} = \frac{\lambda}{k}$$
. The

inequality  $1 < \frac{\lambda}{k}$ , holds, if and only if  $k < \lambda$ , the inequality  $\frac{\lambda}{k} < 1$ , holds, if and only if  $\lambda < k$ , and  $1 = \frac{\lambda}{k}$ , holds, if and only if  $k = \lambda$ . This can be achieved only in the case, if  $\lambda$  is integer. Summarizing, for the values of k less than  $\lambda$  the probabilities are growing, for the values of k greater than  $\lambda$  the probabilities are decreasing, consequently the mode is  $[\lambda]$ . The same probability appears at  $\lambda - 1$ , if  $\lambda$  is integer.

#### Examples

E1. Number of the faults being in some material is supposed to be Poisson distributed random variable. In a unit volume material there are 2.3 faults, in average. Compute the probability that there are at most 3 faults in a unit volume material. How much volume contain at least 1 fault with probability 0.99?

Let  $\xi_1$  be the number of faults in a unit volume of material. Now the possible values of  $\xi_1$  are 0,1,2,...,k,... and  $P(\xi_1 = k) = \frac{\lambda^k}{k!} e^{-\lambda}$ . The parameter  $\lambda$  equals the expectation, hence

$$P(\xi_1 = k) = \frac{2.3^k}{k!} e^{-2.3}.$$
 Now,  $P(\xi_1 \le 3) = P(\xi_1 = 0) + P(\xi_1 = 1) + P(\xi_1 = 2) + P(\xi_1 = 3) = 0$ 

$$\frac{2.3^{0}}{0!}e^{-2.3} + \frac{2.3^{1}}{1!}e^{-2.3} + \frac{2.3^{2}}{2!}e^{-2.3} + \frac{2.3^{3}}{3!}e^{-2.3} = 0.799.$$

Compute the probability that there are at least 3 faults in a unit volume material.

 $P(\xi_1 \ge 3) = 1 - (P(\xi_1 = 0) + P(\xi_1 = 1) + P(\xi_1 = 2)) = 1 - (\frac{2.3^0}{0!}e^{-2.3} + \frac{2.3^1}{1!}e^{-2.3} + \frac{2.3^2}{2!}e^{-2.3}) = 0.404.$ 

How many faults are most likely in a unit volume material?

 $\lambda = 2.3$  is not integer, consequently there is a unique mode, namely  $\lfloor 2.3 \rfloor = 2$ . The probabilities are included into the following Tables f.5. and can be seen in Fig.f.2.

k	0	1	2	3	4	5	6	7	8	9
$P(\xi_1 = k)$	0.100	0.230	0.203	0.117	0.0538	0.0206	0.0068	0.0019	0.0005	0.0001

Table f.5. Probabilities belonging to the possible values in case of Poisson distribution with parameter  $\lambda = 2.3$ 



Figure f.2. Probabilities belonging to the possible values in case of Poisson distribution with parameter  $\lambda = 2.3$ 

How many faults are most likely in 10 unit volume material?

Let  $\xi_{10}$  is the number of faults a 10 unit volume.  $\xi_{10}$  is also Poisson distributed random variable with parameter  $\lambda^* = 10 \cdot 2.3 = 23$ . As  $\lambda^*$  is integer, two modes exist, namely  $\lambda^* = 23$  and  $\lambda^* - 1 = 22$ . It is easy to see that  $P(\xi_{10} = 22) = \frac{(\lambda^*)^{22}}{22!} e^{-\lambda^*} = \frac{(23)^{22}}{22!} e^{-23} = \frac{(23)^{23}}{23!} e^{-23} = P(\xi_{10} = 23)$ .

How much volume contains at least on fault with probability 0.99?

Let x denote the unknown volume and  $\xi_x$  the number of faults being x volume material. We want to know x if we know that  $P(1 \le \xi_x) = 0.99$ . Taking into account that  $P(1 \le \xi_x) = 1 - P(\xi_x = 0)$ ,  $P(1 \le \xi_x) = 0.99$  implies  $P(\xi_x = 0) = 0.01$ .  $\xi_x$  is Poisson distributed random variable with parameter  $\lambda_x = x \cdot 2.3$ , consequently  $\frac{(x \cdot 2.3)^0}{0!} e^{-2.3x} = 0.01$ . As  $(x \cdot 2.3)^0 = 1$ , 0! = 1, we get  $e^{-2.3x} = 0.01$ . Taking the logarithm

of both sides, we ends in  $-2.3x = \ln 0.1$ , therefore  $x = \frac{\ln 0.01}{-2.3} = 2.003 \approx 2$ .

E2. The number of viruses arriving at a computer is Poisson distributed random variable. The probability that there is no file with viruses during 10 minutes equals 0.7. How many files arrive at the computer most likely during 12 hours?

Let  $\xi_{10}$  be the number of viruses arriving at our computer during a 10 minutes period. We do not know the parameter of  $\xi_{10}$ , but we know that  $P(\xi_{10} = 0) = 0.7$ . As  $\xi_{10}$  is Poisson distributed random variable with parameter  $\lambda$ , therefore  $P(\xi_{10} = 0) = \frac{\lambda^0}{0!}e^{-\lambda} = 0.7$ . It implies  $\lambda = -\ln 0.7 = 0.357$ .

If  $\xi_{720}$  is the number of viruses arriving at the computer during 12 hours,  $\xi_{720}$  is also Poisson distributed random variable with parameter  $\lambda^* = 12 \cdot 6 \cdot 0.357 = 25.68$ , consequently there is unique mode, [25.68] = 25.

<u>Theorem</u> If  $\xi$  is Poisson distributed random variable with parameter  $\lambda_1$ ,  $\eta$  is Poisson distributed random variable with parameter  $\lambda_2$  furthermore they are independent, then  $\xi + \eta$  is also Poisson distributed random variable with parameter  $\lambda_1 + \lambda_2$ . Proof

As  $\xi$  is Poisson distributed random variable with parameter  $\lambda_1$ , the possible values of  $\xi$ 

are 0,1,2,3,... and  $P(\xi = i) = \frac{(\lambda_1)^i}{i!} e^{-\lambda_1}$ . As  $\eta$  is Poisson distributed random variable with

parameter  $\lambda_2$ , the possible values of  $\eta$  are 0,1,2,3,... and  $P(\eta = j) = \frac{(\lambda_2)^j}{j!} e^{-\lambda_2}$ . It is obvious that the possible values of  $\xi + \eta$  are 0,1,2,3,.... We prove that  $P(\xi + \eta = k) = \frac{(\lambda_1 + \lambda_2)^k}{k!} e^{-(\lambda_1 + \lambda_2)}$ .

First, investigate  $P(\xi + \eta = 0)$ .

$$\begin{split} P(\xi + \eta = 0) &= P(\xi = 0 \cap \eta = 0) = P(\xi = 0) \cdot P(\eta = 0) = \\ \frac{(\lambda_1)^0}{0!} e^{-\lambda_1} \cdot \frac{(\lambda_2)^0}{0!} e^{-\lambda_2} = e^{-(\lambda_1 + \lambda_2)} = \frac{(\lambda_1 + \lambda_2)^0}{0!} e^{-(\lambda_1 + \lambda_2)}. \\ \text{Similarly,} \\ P(\xi + \eta = 1) &= P(\xi = 1 \cap \eta = 0) + P(\xi = 0 \cap \eta = 1) = P(\xi = 1) \cdot P(\eta = 0) + P(\xi = 0) \cdot P(\eta = 1) = \\ \frac{(\lambda_1)^1}{1!} e^{-\lambda_1} \cdot \frac{(\lambda_2)^0}{0!} e^{-\lambda_2} + \frac{(\lambda_1)^0}{0!} e^{-\lambda_1} \cdot \frac{(\lambda_2)^1}{1!} e^{-\lambda_2} = \frac{(\lambda_1 + \lambda_2)^1}{1!} e^{-(\lambda_1 + \lambda_2)^1} \text{ coinciding with the requirement.} \end{split}$$

Generally,

$$P(\xi + \eta = k) = \sum_{i=0}^{k} P(\xi = i \cap \eta = k - i) = \sum_{i=0}^{k} P(\xi = i) \cdot P(\eta = k - i) = \sum_{i=0}^{k} \frac{(\lambda_{1})^{i}}{i!} e^{-\lambda_{1}} \frac{(\lambda_{2})^{k-i}}{(k-i)!} e^{-\lambda_{2}} = e^{-(\lambda_{1}+\lambda_{2})} \sum_{i=0}^{k} \frac{(\lambda_{1})^{i}}{i!} \frac{(\lambda_{2})^{k-i}}{(k-i)!} = \frac{e^{-(\lambda_{1}+\lambda_{2})}}{k!} \sum_{i=0}^{k} \binom{k}{i!} (\lambda_{1})^{i} (\lambda_{2})^{k-i} = \frac{e^{-(\lambda_{1}+\lambda_{2})}}{k!} (\lambda_{1}+\lambda_{2})^{k}.$$

E3. The number of served people in an office is Poisson distributed random variable. There are two attendants in the office and the number of people served by the first one and

the second one are independent random variables. The average number served by them during an hour is 3 and 2.5, respectively. Compute the probability that together they serve more than 4 people during an hour.

Let  $\xi_1$  and  $\xi_2$  be the numbers of people served by the attendants, respectively.  $\xi_1$  is Poisson distributed random variable with parameter  $\lambda_1 = 3$ ,  $\xi_2$  is Poisson distributed random variable with parameter  $\lambda_2 = 2.5$ , and according to the assumption, they are independent. The total number of people served by them is  $\xi_1 + \xi_2$ . Applying the previous theorem,  $\xi_1 + \xi_2$  is also Poisson distributed random variable with parameter  $\lambda = \lambda_1 + \lambda_2 = 5.5$  Consequently,

$$P(4 < \xi_1 + \xi_2) = 1 - (P(\xi_1 + \xi_2 = 0) + P(\xi_1 + \xi_2 = 1) + P(\xi_1 + \xi_2 = 2) + P(\xi_1 + \xi_2 = 3) + P(\xi_1 + \xi_2 = 4)) = 0$$

$$1 - \left(\frac{5.5^{0}}{0!}e^{-5.5} + \frac{5.5^{1}}{1!}e^{-5.5} + \frac{5.5^{2}}{2!}e^{-5.5} + \frac{5.5^{3}}{3!}e^{-5.5} + \frac{5.5^{4}}{4!}e^{-5.5}\right) = 1 - 0.358 = 0.642.$$

Given that they serve 5 people together, compute the probability that the first attendant serves 3 and the second one serves two clients.

The second question can be written as follows:  $P(\xi_1 = 3 \cap \xi_2 = 2 | \xi_1 + \xi_2 = 5) = ?$ 

Recall that the conditional probability is given by  $P(A | B) = \frac{P(A \cap B)}{P(B)}$ . Consequently,

$$P((\xi_1 = 3 \cap \xi_2 = 2) | (\xi_1 + \xi_2 = 5)) = \frac{P((\xi_1 = 3 \cap \xi_2 = 2) \cap (\xi_1 + \xi_2 = 5))}{P(\xi_1 + \xi_2 = 5)}$$

The event  $\{\xi_1 + \xi_2 = 5\}$  is the consequence of  $\{\xi_1 = 3 \cap \xi_2 = 2\}$ , therefore their intersection is the event  $\{\xi_1 = 3 \cap \xi_2 = 2\}$ . Now, taking into consideration the independence of random variables  $\xi_1$  and  $\xi_2$  we get

$$P((\xi_1 = 3 \cap \xi_2 = 2) | (\xi_1 + \xi_2 = 5)) = \frac{P(\xi_1 = 3 \cap \xi_2 = 2)}{P(\xi_1 + \xi_2 = 5)} = \frac{P(\xi_1 = 3) \cdot P(\xi_2 = 2)}{P(\xi_1 + \xi_2 = 5)} = \frac{\frac{3^3}{3!}e^{-3} \cdot \frac{2.5^2}{2!}e^{-2.5}}{\frac{5.5^5}{5!}e^{-5.5}}$$

$$= {\binom{5}{3}} {\binom{3}{5.5}}^3 {\binom{1-\frac{3}{5.5}}}^2 = 0.615.$$

### f.6. Geometrically distributed random variable

At the end of this section we deal with geometrically distributed random variables. In this case we perform independent experiments until a fixed event occurs. We finish the experiments when the event occurs first. Actually we do not know the number of experiments, in advance.

<u>Definition</u> The random variable  $\xi$  is called **geometrically distributed random variable** with parameter 0 , if its possible values are <math>1, 2, 3, ..., k, ... and  $P(\xi = k) = p(1-p)^{k-1}$ , k=1,2,3,...

<u>Remarks</u>

• The above probabilities are really nonnegative, and their sum equals 1. It can be seen easily if we apply the formula concerning the sum of infinite geometrical series,  $\infty$ 

namely 
$$\sum_{i=1}^{\infty} x^i = \frac{1}{1-x}$$
, if  $|x| < 1$  holds.  
 $P(\xi = k) = \sum_{k=1}^{\infty} P(\xi = k) = \sum_{k=1}^{\infty} p(1-p)^{k-1} = p \sum_{k=1}^{\infty} (1-p)^{k-1} = p \sum_{k=0}^{\infty} (1-p)^k = p \cdot \frac{1}{1-(1-p)} = 1$ .

• The quantities  $p(1-p)^{k-1}$  form a geometrical series, this is the reason of the denomination.

• Do not confuse this discrete random variable with the geometrical probability presented in the first chapter.

<u>Theorem</u> We repeat an experiment until a fixed event A occurs, 0 < P(A) < 1. Suppose that the experiments are independent. Let  $\xi$  be the number of necessary experiments. Then,  $\xi$  is geometrically distributed random variable with parameter p = P(A).

<u>Proof</u> Let  $A_i$  denote that the event A occurs at the ith experiment. Now, the values of  $\xi$  can be 1,2,3,..., whatever positive integer.  $\xi = 1$  means that the event A occurs at the first experiment, therefore  $P(\xi=1) = P(A_1) = p$ .  $\xi = 2$  means that the event A does not occur at the first experiment, but it does at the second experiment, that is  $P(\xi=2) = P(\overline{A_1} \cap A_2) = P(\overline{A_1}) \cdot P(A_2) = (1-p)p$ , which meets the requirements. Generally,  $\xi = k$  means, that the event A does not occur at the 1.,2., ...,(k-1)th experiments, but it occurs at the kth one. Hence

 $P(\overline{A_1} \cap \overline{A_2} \cap ... \cap \overline{A_{k-1}} \cap A_k) = P(\overline{A_1})P(\overline{A_2})P(\overline{A_3})...P(\overline{A_{k-1}})P(A_k) = (1-p)^{k-1} \cdot p, \text{ which is the statement to be proved.}$ 

Numerical characteristics of geometrically distributed random variables

#### Expectation

$$\begin{split} E(\xi) &= \frac{1}{p}. \text{ This formula can be proved as follows:} \\ E(\xi) &= \sum_{i=1}^{\infty} x_i p_i = \sum_{k=1}^{\infty} k \cdot p(1-p)^{k-1} = p \sum_{k=1}^{\infty} k(1-p)^{k-1}. \quad k(1-p)^{k-1} \text{ is similar to derivative. If} \\ \text{we investigate the function} \quad \sum_{k=1}^{\infty} kx^{k-1} \quad \text{for values} \quad |x| < 1, \end{split}$$

we investigate the function  $\sum_{k=1}^{\infty} kx^{k-1}$  for values |x| < 1,  $\sum_{k=1}^{\infty} kx^{k-1} = \sum_{k=1}^{\infty} (x^k)^{k} = (\sum_{k=1}^{\infty} x^k)^{k} = (\frac{x}{1-x})^{k} = \frac{1}{(1-x)^2}$ . Substituting x = 1-p, we get  $\sum_{k=1}^{\infty} 1 (1-x)^{k-1} = \frac{1}{(1-x)^2}$ .

$$\sum_{k=1}^{\infty} k(1-p)^{k-1} = \frac{1}{(1-(1-p))^2} = \frac{1}{p^2}.$$
 This implies the formula  
$$E(\xi) = p \sum_{k=1}^{\infty} k(1-p)^{k-1} = \frac{p}{p^2} = \frac{1}{p}.$$

Dispersion
$D(\xi) = \frac{\sqrt{1-p}}{p}$ . We do not prove this formula. It can be proved similarly to the previous

statement, but it requires more computation.

#### <u>Mode</u>

There is a unique mode, namely always 1. This is the straightforward consequence of the fact that the ratio of consecutive probabilities is  $\frac{P(\xi = k)}{P(\xi = k - 1)} = \frac{p(1 - p)^{k-1}}{p(1 - p)^{k-2}} = 1 - p < 1$ . This implies that the probabilities are decreasing, therefore the first one is the greatest.

### Example

E1. We throw a die until we succeed in "six". Compute the probability that at most 6 throws are needed. Let  $\xi$  be the number of necessary throws.  $\xi$  is geometrically distributed random variable with parameter  $\frac{1}{6}$ . This means that the possible values of  $\xi$  are 1,2,3,... and  $P(\xi = k) = \left(\frac{5}{6}\right)^{k-1} \cdot \left(\frac{1}{6}\right)$ .

$$P(\xi \le 6) = \sum_{i=1}^{6} P(\xi = i) = \frac{1}{6} + \left(\frac{1}{6}\right)\left(\frac{5}{6}\right) + \left(\frac{1}{6}\right)\left(\frac{5}{6}\right)^2 + \left(\frac{1}{6}\right)\left(\frac{5}{6}\right)^3 + \left(\frac{1}{6}\right)\left(\frac{5}{6}\right)^4 + \left(\frac{1}{6}\right)\left(\frac{5}{6}\right)^3 = \frac{1}{6}\frac{\left(\frac{6}{5}\right)^{-1}}{\frac{5}{6}-1} = \frac{1}{6}\frac{\left(\frac{6}{5}\right)^{-1}}{$$

$$1 - \left(\frac{5}{6}\right)^6 = 0.655.$$

Generally,  $P(\xi \le n) = \frac{1}{6} \frac{\left(\frac{5}{6}\right)^n - 1}{\frac{5}{6} - 1} = 1 - \left(\frac{5}{6}\right)^n$ .

Compute the probability that more than 10 throws is needed. According to the previous formula,  $P(\xi > 10) = \left(\frac{5}{6}\right)^{10} = 0.161$ . At most how many throws are needed with probability 0.9? The question is to find the value of n for which  $P(\xi \le n) = 0$ .

The question is to find the value of n for which  $P(\xi \le n) = 0.99$ . As  $P(\xi \le n) = 1 - \left(\frac{5}{6}\right)^n$ , we have to solve the equality  $1 - \left(\frac{5}{6}\right)^n = 0.99$ . This implies  $\left(\frac{5}{6}\right)^n = 0.01$ , that is  $n \ln(\frac{5}{6}) = \ln 0.1$ . Computing the value of n we get  $n = \frac{\ln 0.1}{\ln \frac{5}{6}} = 12.63$ . But we expect integer

value for n, hence we have to decide whether n=12 or n=13 is appropriate.

P( $\xi \le 12$ ) = 1 -  $\left(\frac{5}{6}\right)^{12}$  = 0.888, which is less than the required probability 0.99. P( $\xi \le 13$ ) = 1 -  $\left(\frac{5}{6}\right)^{13}$  = 0.907, which is larger than the requirement. Exactly 0.9 can not be achieved, the series skip over this level, as it can be seen in Fig. f.3.



Figure f.3. Probabilities  $P(\xi \le k)$  and the level y=0.9

The probabilities  $P(k) = P(\xi = k)$  are presented in Fig.f.4.



Figure f.4. Probabilities  $P(\xi = k)$ 

Which is the most probable value of the throws? The most probable value of  $\xi$  equals 1, the probability belonging to them is  $\frac{1}{6}$ . All of the probabilities belonging to other value are smaller than  $\frac{1}{6}$ . We draw the attention that  $P(\xi \neq 1) = \frac{5}{6}$ , which is much more than the probability belonging to value 1.

the intersection is  $\{\xi > m + n\}$ . Therefore

$$P(\xi > m + n | \xi > n) = \frac{P(\xi > m + n)}{P(\xi > n)} = \frac{(1 - p)^{m + n}}{(1 - p)^n} = (1 - p)^m, \text{ which coincides with } P(\xi > n).$$

## **Remarks**

• The property  $P(\xi > m + n | \xi > n) = P(\xi > m)$  is the so called forever young property. If we do not succeed until n, the probability that we will not succeed until further m experiments is the same that the probability that we do not succeed until m. Everything begins as if we were at the starting point.

• One can also prove that the forever young property implies the geometrical distribution in the set of positive integer valued random variables. Consequently, this property is a pivotal property.

 $\begin{array}{ll} \bullet & P(\xi > m+n \,|\, \xi > n) = P(\xi > m) \hspace{0.2cm} implies \hspace{0.2cm} the \hspace{0.2cm} formula \hspace{0.2cm} P(\xi \leq m+n \,|\, \xi > n) = P(\xi \leq m) \\ as \hspace{0.2cm} well. \hspace{0.2cm} As \hspace{0.2cm} an \hspace{0.2cm} explanation \hspace{0.2cm} recall \hspace{0.2cm} that \hspace{0.2cm} P(\overline{A} \,|\, B) = 1 - P(A \,|\, B) \,. \\ P(\xi \leq m+n \,|\, \xi > n) = 1 - P(\xi > m+n \,|\, \xi > n) \hspace{0.2cm} = 1 - P(\xi > m) = P(\xi \leq m) \,. \end{array}$ 

## Example

E2. At an exam there are 10 tests. The candidate gives it back if the test is not from the first three tests. Compute the probability that the candidates will succeed until 4 experiments.

Let  $\xi$  be the number of bids.  $\xi$  is geometrically distributed random variable with parameter 3

$$p = \frac{1}{10}.$$

$$P(\xi \le 4) = P(\xi = 1) + P(\xi = 2) + P(\xi = 3) + P(\xi = 4) = 0.3 + 0.3 \cdot 0.7 + 0.3 \cdot 0.7^{2} + 0.3 \cdot 0.7^{3} = 1 - 0.7^{4} = 0.760$$

At most how many bids does he need with probability 0.95?

n=?  $P(\xi \le n) = 0.95$ .  $P(\xi \le n) = 1 - 0.7^n = 0.99$ , which implies n=8.4. Consequently, the candidates needs at most 9 bids until the hit.

If he does not succeed up to the  $5^{th}$  experiment, compute the probability that he succeed until the  $8^{th}$  one.

The question can be easily answered by applying the forever young property as follows:

 $P(\xi \le 8 | \xi > 5) = P(\xi \le 3) = P(\xi = 1) + P(\xi = 2) + P(\xi = 3) = 0.3 + 0.3 \cdot 0.7 + 0.3 \cdot 0.7^{2} = 0.657.$ 

# g. Frequently used continuous distributions

### The aim of this chapter

In chapter d. we have dealt with continuous random variables. Now we investigate some frequently used types. We compute their numerical characteristics, study their main properties and we present their relationships with some discrete distributions, as well. We derive new random variables from normally distributed random variables. These are often used in statistics.

# Preliminary knowledge

Random variables and their numerical characteristics. Density function. Partial integrate.

# Content

- g.1. Uniformly distributed random variables.
- g.2. Exponentially distributed random variables.
- g.3. Normally distributed random variables.
- g.4. Further random variables derived from normally distributed ones.

## g.1. Uniformly distributed random variables

In this chapter we deal with some frequently used continuous random variable. We defined them by the help of probability density function.

First we deal with a very simple continuous random variable. Let  $\Omega$ ,  $\mathcal{A}$ , and P be given and  $\xi$  is a random variable.

<u>Definition</u> The random variable  $\xi$  is called **uniformly distributed random variable with** parameter **a**, **b** (a<b), if its probability density function is  $f(x) = \begin{cases} c & \text{if } a \le x \le b \\ 0 & \text{otherwise} \end{cases}$ .

<u>Remarks</u>

• As the area under the probability density function equals 1,  $c = \frac{1}{b-a}$ . This value is positive, consequently all values of the probability density function are nonnegative.

• The constant values of the probability density function express that all the values of the interval [a, b] are equally probable.

• Uniformly distributed random variable with parameter a, b (a<b) are often called uniformly distributed random variable in [a, b]

• The graph of the probability density function of the uniformly distributed random variable with parameters a = -1, b = 4 can be seen in Fig.g.1.



Figure g.1. Probability density function of uniformly distributed random variable with parameters a=-1, b=4

Theorem

The cumulative distribution function of uniformly distributed random variable in [a, b] is

$$F(x) = \begin{cases} 0 & \text{if } x \le a \\ \frac{x-a}{b-a} & \text{if } a < x \le b \\ 1 & \text{if } b < x \end{cases}$$

Proof

Recall the relationship  $F(x) = \int_{-\infty}^{x} f(t) dt$  between the probability density function and cumulative distribution function presented in section d.

If 
$$x < a$$
, then  $F(x) = \int_{-\infty}^{x} f(t)dt = \int_{-\infty}^{x} 0dt = 0$ .  
If  $a \le x \le b$ , then  $F(x) = \int_{-\infty}^{x} f(t)dt = \int_{-\infty}^{a} 0dt + \int_{a}^{x} \frac{1}{b-a}dt = 0 + \frac{1}{b-a} \cdot [t]_{a}^{x} = \frac{x-a}{b-a}$ .  
Finally, if  $b < x$ , then  $F(x) = \int_{-\infty}^{x} f(t)dt = \int_{0}^{a} 0dt + \int_{0}^{b} \frac{1}{b-a}dt + \int_{0}^{x} 0dt = 0 + 1 + 0 = 1$ .

The graph of the cumulative distribution function of a uniformly distributed random variable with parameters a=-1 and b=4 is presented in Fig.g.2.



Figure g.2. Cumulative distribution function of uniformly distributed random variable with parameters a=-1, b=4

<u>Remarks</u>

• Let  $\xi$  be uniformly distributed random variable in the interval [a, b] and a < c < d < b. Then  $P(c < \xi < d) = F(d) - F(c) = \frac{d-a}{b-a} - \frac{c-a}{b-a} = \frac{d-c}{b-a}$ . The probability of being in the interval (c, d) is proportional to the length of the interval (c, d).

• Choose a number from the interval [a,b] by geometrical probability. Let  $\xi$  be the chosen number. Then  $\xi$  is uniformly distributed random variable in the interval [a,b]. As justification take into consideration that  $P(\xi < x) = P(\emptyset) = 0$ , if x < a,  $P(\xi < x) = P(a \le \xi < x) = \frac{x-a}{b-a}$ , if  $a \le x \le b$  and  $P(\xi < x) = P(\Omega) = 1$ , if  $b < x \cdot F(x) = P(\xi < x)$ , and  $f(x) = F'(x) = \frac{1}{b-a}$  if a < x < b, and 0 if x < a or b < x. At the endpoints x = a and x = b the cumulative distribution function is not differentiable, we can define the probability density function anyhow. Defining  $f(a) = \frac{1}{b-a} = f(b)$ , f equals to one in the definition.

Random number generator of computers usually generates approximately uniformly distributed random variables in [0,1].

Numerical characteristics of uniformly distributed random variables:

### Expectation

 $E(\xi) = \frac{a+b}{2}$ , which is a straightforward consequence of  $E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{a}^{b} x \cdot \frac{1}{b-a} dx = \frac{1}{b-a} \int_{a}^{b} x dx = \frac{1}{b-a} \left[ \frac{x^{2}}{2} \right]_{a}^{b} = \frac{b^{2} - a^{2}}{2(b-a)} = \frac{b+a}{2}.$  Note that this value is the middle of the interval [a, b].

#### Dispersion

$$D(\xi) = \frac{b-a}{\sqrt{12}} \text{ As a proof, recall that } D^{2}(\xi) = E(\xi^{2}) - (E(\xi))^{2}.$$

$$E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2} f(x) dx = \int_{a}^{b} x^{2} \frac{1}{b-a} dx = \frac{1}{b-a} \left[\frac{x^{3}}{3}\right]_{a}^{b} = \frac{b^{3}-a^{3}}{3(b-a)} = \frac{b^{2}+ab+a^{2}}{3}.$$

$$D^{2}(\xi) = E(\xi^{2}) - (E(\xi))^{2} = \frac{b^{2}+ab+a^{2}}{3} - \left(\frac{a+b}{2}\right)^{2} = \frac{b^{2}-2ab+b^{2}}{12} = \frac{(b-a)^{2}}{12}.$$
Consequently,  $D(\xi) = \sqrt{\frac{(b-a)^{2}}{12}} = \frac{|b-a|}{\sqrt{12}} = \frac{b-a}{2}.$ 

## Mode

All of the values of interval [a,b] have the same chance, consequently, all the points of (a,b)are mode.

# Median

 $me = \frac{a+b}{2}$ . We have to find the value y for which F(y) = 0.5. As neither 0 nor 1 do not equal 0.5, the following equality has to be held:  $\frac{y-a}{b-a} = 0.5$ . This implies y-a = 0.5(b-a). Arranging it, finally we get  $y = \frac{b+a}{2}$ .

### Example

E1. Let  $\xi$  be uniformly distributed random variable in [2,10]. Compute the probability that the value of the random variable is between 5 and 8.

The cumulative distribution function of  $\xi$  is given by  $F(x) = \begin{cases} \frac{x-2}{8} & \text{if } 2 < x \le 10, \\ 1 & \text{if } 10 < x \end{cases}$ 

which is a useful tool to compute probabilities.

$$P(5 < \xi < 8) = F(8) - F(5) = \frac{8-2}{8} - \frac{5-2}{8} = \frac{3}{8} = 0.375.$$

Compute the probability that the value of the random variable is less than 5.

$$P(\xi < 5) = F(5) = \frac{5-2}{8} = \frac{3}{8} = 0.375.$$

Compute the probability that the value of the random variable is greater than 8.

$$P(8 < \xi) = 1 - F(8) = 1 - \frac{8 - 2}{8} = \frac{2}{8} = 0.25.$$

Compute the probability that the value of the random variable is greater than the half of its expectation and less than the double of the expectation.

$$E(\xi) = \frac{2+10}{2} = 6, \ P(3 < \xi < 12) = F(12) - F(3) = 1 - \frac{3-2}{8} = \frac{7}{8}.$$

At most how much is the value of the random variable with probability 0.9?

x=? for which  $P(\xi \le x) = 0.9$ .  $P(\xi \le x) = F(x)$ , we have to solve  $\frac{x-2}{8} = 0.9$ . This implies x = 9.2.

At least how much is the value of the random variable with probability 0.9?

x=? for which  $P(\xi \ge x) = 0.9$ .  $P(x \le \xi) = 1 - F(x)$ , we have to solve  $1 - \frac{x - 2}{8} = 0.9$ . This implies x = 2.8

implies x = 2.8.

Given that the value of the random variable is more than 5, compute the probability that it is less than 8.

$$P(\xi < 8 \mid \xi \ge 5) = \frac{P((\xi < 8) \cap (\xi \ge 5))}{P(\xi \ge 5)} = \frac{P(5 \le \xi < 8)}{P(\xi \ge 5)} = \frac{F(8) - F(5)}{1 - F(5)} = \frac{\frac{8 - 2}{8} - \frac{5 - 2}{8}}{1 - \frac{5 - 2}{8}} = \frac{3}{5} = 0.6$$

Notice that this conditional probability is proportional to the length of the interval [5,8) if the number originates from [5,10].

<u>Theorem</u> If  $\xi$  is uniformly distributed random variable in [0,1], 0 < c and  $d \in R$ , then  $\eta = c\xi + d$  is uniformly distributed random variable in [d, c + d].

<u>Proof</u> Investigate the cumulative distribution function of  $\eta$ , then take its derivative.

$$\begin{split} F_{\eta}(x) &= P(\eta < x) = P(c\xi + d < x) = P(\xi < \frac{x - d}{c}) = F_{\xi}\left(\frac{x - d}{c}\right).\\ \text{Recalling that } F_{\xi}(x) &= \begin{cases} 0 & \text{if } x \le 0\\ x & \text{if } 0 < x \le 1, \\ 1 & \text{if } 1 < x \end{cases} = \begin{cases} 0 & \text{if } \frac{x - d}{c} \le 0\\ \frac{x - d}{c} & \text{if } 0 < \frac{x - d}{c} \le 1\\ 1 & \text{if } 1 < x \end{cases} \\ \begin{cases} 0 & \text{if } x \le d\\ 1 & \text{if } 1 < \frac{x - d}{c} \end{cases} \\ \end{bmatrix} \begin{cases} 0 & \text{if } x \le d\\ \frac{x - d}{c} & \text{if } d < x \le c + d \end{cases}. \end{split}$$

Taking the derivative of  $F_{\eta}(x)$ ,  $f_{\eta}(x) = \begin{cases} \frac{1}{c} & \text{if } d \le x \le c+d \\ 0 & \text{otherwise} \end{cases}$ .

Remarks

• If c is negative, then  $\eta = c\xi + d$  is uniformly distributed random variable in [c + d, d].

• Using the random number generator, we can get uniformly distributed random variable in [a, b] by multiplying the generated random number by b - a and adding a.

• If  $\xi$  is uniformly distributed random variable in [0,1], then so is  $\eta = 1 - \xi$ . To justify it, first take into consideration that all of values of  $\xi$  are in [0,1], hence so are the values of  $\eta = 1 - \xi$ . Moreover,

$$\begin{split} F_{\eta}(x) = P(\eta < x) = P(1 - \xi < x) = P(1 - x < \xi) = 1 - F_{\xi}(1 - x) = 1 - (1 - x) = x, \quad \text{if} \quad 0 < x < 1. \end{split}$$
Therefore  $f_{\eta}(x) = F'_{\eta}(x) = 1$ , if 0 < x < 1 and zero out of [0,1].

### Theorem

Let  $\xi$  be uniformly distributed random variable in [0,1]. Let F a continuous cumulative distribution function in R. Let  $I = \{x \in R : F(x) \neq 0, F(x) \neq 1\}$  and suppose that F is strictly monotone in I. Then  $\eta = F^{-1}(\xi)$  is a random variable those cumulative distribution function is F.

 $F^{-1}:(0,1) \to I$ ,  $P(\xi=0)=0$ ,  $P(\xi=1)=0$ ,  $\eta=F^{-1}(\xi)$  is well defined. Take any value  $x \in I$ , and investigate the cumulative distribution function of  $\eta$  at x. Taking into account that

$$F_{\xi}(x) = \begin{cases} 0 & \text{if } x \le 0 \\ x & \text{if } 0 < x \le 1 \\ 1 & \text{if } 1 < x \end{cases}$$

 $F_{\eta}(x) = P(\eta < x) = P(F^{-1}(\xi) < x).$ 

As F is monotone increasing,  $\{F^{-1}(\xi) < x\} = \{F(F^{-1}(\xi)) < F(x)\} = \{\xi < F(x)\}$ . Consequently, P(F<sup>-1</sup>(\xi) < x) = P(\xi < F(x)) = F\_{\xi}(x) = F(x).

If 
$$x \le \inf I$$
, then  $F(x) = 0$  and  $F_{\eta}(x) = P(\eta < x) = P(F^{-1}(\xi) < x) = 0$ .

If sup 
$$I \le x$$
, then  $F(x) = 1$  and  $F_n(x) = P(\eta < x) = P(F^{-1}(\xi) < x) = 1$ .

Consequently, the cumulative distribution function of  $F^{-1}(\xi)$  is F(x).

### Remark

• The previous statement gives us possibility to generate random variables with cumulative distribution function F.

### Example

E2. Generate random variables with cumulative distribution function  $F(x) = \begin{cases} 0 & \text{if } x \le 1 \\ 1 - \frac{1}{x} & \text{if } x < 1 \end{cases}$  Apply the previous statement. F is strictly monotone increasing function in the interval  $(1,\infty)$ ,  $F^{-1}(y) = \frac{1}{1-y}$ , 0 < y < 1. Consequently, if  $\xi$  is uniformly distributed in [0,1], then  $F^{-1}(\xi)$  is a random variable with cumulative distribution function F. Consequently, substituting the random number generated by the computer into  $F^{-1}$  we get a random variable with cumulative distribution function F. The relative frequencies of the random numbers and the probability density function  $f(x) = F'(x) = \frac{1}{x^2}$ ,  $1 \le x$ , can be seen in Fig.g.3.



Figure g.3. Relative frequencies of random numbers  $F^{-1}(\xi)$  situated in different subintervals and the probability density function

## g.2. Exponentially distributed random variables

In this subsection we deal a frequently used continuous distribution, namely exponential one. It is very useful, because many examples can be computed for it due to the exponential probability density and exponential cumulative distribution function.

<u>Definition</u>: The random variable  $\xi$  is **exponential distributed random variable with parameter**  $0 < \lambda$ , if its probability density function is  $f(x) = \begin{cases} 0 & \text{if } 0 \le x \\ \lambda e^{-\lambda x} & \text{if } 0 < x \end{cases}$ .

Remarks

•  $0 \le f(x)$  is obvious, furthermore,

 $\int_{-\infty}^{\infty} f(x) dx = \int_{0}^{\infty} \lambda e^{-\lambda x} dx = \left[ \lambda \frac{e^{-\lambda x}}{-\lambda} \right]_{0}^{\infty} = \lim_{x \to \infty} \left( -e^{-\lambda x} \right) - \left( -e^{0} \right) = 0 + 1 = 1.$  These properties imply that

f(x) is a probability density function. The graphs of probability density functions of exponentially distributed random variables belonging to different parameters are presented in Fig.g.4.



Figure g.4. Probability density functions of exponentially distributed random variables with parameters  $\lambda = 1$  (black),  $\lambda = 0.5$  (blue) and  $\lambda = 2$  (red)

• Exponentially distributed random variable takes its value with large probability around zero, whatever the parameter is. All of its values are nonnegative.

<u>Theorem</u> The cumulative distribution function of an exponentially distributed random variable with parameter  $0 < \lambda$  is  $F(x) = \begin{cases} 0 & \text{if } x \le 0 \\ 1 - e^{-\lambda x} & \text{if } 0 < x \end{cases}$ .

Proof

$$F(x) = \int_{-\infty}^{x} f(t)dt = \int_{-\infty}^{x} 0dx = 0, \text{ if } x \le 0.$$
  

$$F(x) = \int_{-\infty}^{x} f(t)dt = \int_{0}^{x} \lambda e^{-\lambda t} dx = \left[\frac{e^{-\lambda t}}{-1}\right]_{0}^{x} = e^{-\lambda x} - (-1) = 1 - e^{-\lambda x}, \text{ if } 0 < x.$$

The graphs of the cumulative distribution function belonging to the previous probability density functions are presented in Fig.g.5.



Figure g.5. Cumulative distribution functions of exponentially distributed random variables with parameters  $\lambda = 1$  (black),  $\lambda = 0.5$  (blue) and  $\lambda = 2$  (red)

# Remark

• Simple way to generate exponentially distributed random variable to substitute the uniformly distributed random variable into  $F^{-1}(y) = \frac{\ln(1-y)}{-\lambda}$ . Relative frequencies of exponentially distributed random variables situated in the interval [0,5] are presented in Fig.g.6. One can notice that the relative frequencies follow the probability density function drawn by red line.



Figure g.6. Relative frequencies of random numbers  $-\ln(1-\xi)$  situated in different subintervals and the exponential probability density function with parameter  $\lambda = 1$ 

## Numerical characteristics of exponentially distributed random variables:

Expectation

$$E(\xi) = \frac{1}{\lambda} \text{. It follows from}$$
$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{0}^{\infty} x \cdot \lambda e^{-\lambda x} dx = \left[x \cdot (-e^{-\lambda x})\right]_{0}^{\infty} - \int_{0}^{\infty} -e^{-\lambda x} dx = 0 - \left[\frac{e^{-\lambda x}}{-\lambda}\right]_{0}^{\infty} = \frac{1}{\lambda}.$$

Taking the average of random numbers generated previously by the presented way, for  $\lambda = 1$ , the results are in Table g.1. Differences from the exact expectation 1 are also presented:

N=	1000	10000	100000	1000000	1000000
Average	0.9796	1.0083	1.0015	1.0005	0.9996
Difference	0.0204	0.0083	0.0015	0.0005	0.0004

Table g.1. The average of the values of random variable  $-\ln(1-\xi)$ , if  $\xi$  is uniformly distributed random variable in [0,1] in case of different numbers of simulations N

# **Dispersion**

$$D(\xi) = \frac{1}{\lambda}.$$
 As a proof, recall that  $D^{2}(\xi) = E(\xi^{2}) - (E(\xi))^{2}$ . Twice partially integrating  $E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2} f(x) dx = \frac{2}{\lambda^{2}}, D^{2}(\xi) = E(\xi^{2}) - (E(\xi))^{2} = \frac{2}{\lambda^{2}} - \frac{1}{\lambda^{2}} = \frac{1}{\lambda^{2}}.$ 

Mode .

There is no mode.

### Median

 $me = \frac{\ln 0.5}{-\lambda}$ . We have to find the value x for which F(x) = 0.5. In order to do this, we have to solve the following equation  $1 - e^{-\lambda x} = 0.5$ . This implies  $e^{-\lambda x} = 0.5$ . Taking the logarithm of both sides, we get  $-\lambda x = \ln 0.5$ , finally  $x = \frac{\ln 0.5}{-\lambda}$ .

### Example

E1. Lifetime of a bulb is supposed to be exponentially distributed random variable with expectation 1000hours. Compute the probability that the bulb breaks down before 500 hours.

Let  $\xi$  denote the lifetime of a bulb. As  $\xi$  is exponentially distributed random variable, its cumulative distribution function looks  $F(x) = 1 - e^{-\lambda x}$ ,  $x \ge 0$ . As  $E(\xi) = \frac{1}{\lambda} = 1000$ ,  $\lambda = 0.001$ .

 $P(\xi < 500) = F(500) = 1 - e^{\frac{500}{1000}} = 0.393.$ 

Compute the probability that the bulb goes wrong between 1000 and 2000 hours.

$$P(1000 < \xi < 2000) = F(2000) - F(1000) = \left(1 - e^{-\frac{2000}{1000}}\right) - \left(1 - e^{-\frac{1000}{1000}}\right) = 0.233.$$

At most how many hours is the lifetime of a bulb with probability 0.98?

x=?,  $P(\xi \le x) = 0.98$ .  $P(\xi \le x) = F(x) = 1 - e^{-\frac{x}{1000}} = 0.98$ , consequently,  $e^{-\frac{x}{1000}} = 0.02$ , and  $x = -1000 \cdot \ln 0.02 = 3912$ 

At least how many hours is the lifetime of a bulb with probability 0.98?

x=?,  $P(\xi \ge x) = 0.98$ .  $P(\xi \ge x) = 1 - F(x) = 1 - e^{-\frac{x}{1000}} = 0.98$ , consequently,  $e^{-\frac{x}{1000}} = 0.98$ , and  $x = -1000 \cdot \ln 0.98 = 20.2$ .

Compute the probability that, out of 10 bulbs, having independent exponentially distributed lifetimes with expectation 1000 hours, 7 go wrong before 1000 hours and 3 operate after 1000 hours.

Let  $\xi_i$  denote the lifetime of the ith bulb. They are independent random variables and  $P(\xi_i < 1000) = F(1000) = 1 - e^{\frac{1000}{1000}} = 0.632$ ,  $P(\xi_i \ge 1000) = 0.368$ . If  $\eta$  is the number of bulbs

going wrong until 1000 hours,  $\eta$  is binomially distributed random variable with parameters

n = 10 and p = P(
$$\xi_i < 1000$$
). Therefore P( $\eta = 7$ ) =  $\binom{10}{7} \cdot 0.632^7 \cdot 0.368^3 = 0.241$ .

Actually we present characteristic feature of exponentially distributed random variables.

<u>Theorem</u> If  $\xi$  is exponentially distributed random variable, then for any  $0 \le x, 0 \le y$  the following property holds:  $P(\xi \ge x + y | \xi \ge x) = P(\xi \ge y)$ .

<u>Proof</u>

Recall that  $P(\xi \ge a) = 1 - F(a) = 1 - (1 - e^{-\lambda a}) = e^{-\lambda a}$ .

Moreover,

 $P(\xi \ge x + y \,|\, \xi \ge x) = \frac{P(\xi \ge x + y \cap \xi \ge x)}{P(\xi \ge x)} = \frac{P(\xi \ge x + y)}{P(\xi \ge x)} = \frac{e^{-\lambda(x + y)}}{e^{-\lambda x}} = e^{-\lambda y} = P(\xi \ge y) \,.$ 

Remark

• The previous property can be written in the form  $P(\xi < x + y | \xi \ge x) = P(\xi < y)$ , as well. Take into consideration that

 $P(\xi < x + y \,|\, \xi \ge x) = 1 - P(\xi \ge x + y \,|\, \xi \ge x) = 1 - P(\xi \ge y) = P(\xi < y) \,.$ 

• As exponentially distributed random variables are continuous random variable, then we do not bother if strict inequality (>) or  $\geq$  holds. We can also write  $P(\xi > x + y | \xi > x) = P(\xi > y)$ , which coincides with the property stated for geometrically distributed random variable.

• The property can be interpreted as forever young property. If  $\xi$  is the lifetime of an appliance, then  $\xi$  is the time point when it goes wrong. If it does not go wrong until x, the probability that it will not go wrong until further y unit time is the same that it does not go wrong until y from the beginning. This is the reason of the denomination of the property.

• The forever young property is valid essentially for the exponential distributed random variable in the set of continuous random variables.

<u>Theorem</u> Let  $\xi$  be continuous random variable with nonnegative values, suppose that its cumulative distribution function is differentiable and  $\lim_{x\to 0^+} F(x) = \lambda$ ,  $0 < \lambda$ . Moreover, for any  $0 \le x, y$   $P(\xi \ge x + y | \xi \ge x) = P(\xi \ge y)$  holds. Then  $\xi$  is exponentially distributed random variable with parameter  $\lambda$ . <u>Proof</u> Denote G(x) = 1 - F(x). As  $\xi$  is nonnegative, F(0) = 0, G(0) = 1. As the conditional

exists,  $0 < P(\xi \ge x)$ , consequently G(x) < 1. Let probability  $0 < y = \Delta x$ ,  $P(\xi \ge x + \Delta x \mid \xi \ge x) = P(\xi \ge \Delta x) .$  $P(\xi \ge x + y \mid \xi \ge x) = P(\xi \ge y)$ has the form  $P(\xi \ge x + \Delta x \mid \xi \ge x) = \frac{P(\xi \ge x + \Delta x)}{P(\xi \ge x)} = \frac{G(x + \Delta x)}{G(x)} = G(\Delta x).$ This implies the form

 $G(x + \Delta x) = G(\Delta x)G(x)$ . Subtracting G(x) and applying G(0) = 1 we get  $G(x + \Delta x) - G(x) = G(x)(G(\Delta x) - G(0))$ . Dividing by  $\Delta x$  and taking the limit of both sides if  $0 < \Delta x \rightarrow 0$  we arrive at G'(x) = G'(0+)G(x).  $F'(0+) = \lambda$  implies  $G'(0+) = -\lambda$ , therefore  $G'(x) = -\lambda G(x)$ . This is an ordinary differential equation which is easy to solve. Dividing by G'(x)

 $G(x) \neq 0$ ,  $\frac{G'(x)}{G(x)} = -\lambda$ , consequently  $\ln|G(x)| = -\lambda x + c$ . G(x) is nonnegative, hence

$$\begin{split} &\ln G(x) = -\lambda x + c \quad \text{and} \quad G(x) = e^{-\lambda x + c} . \quad G(0) = e^{-\lambda \cdot 0 + c} = 1 \quad \text{implies} \quad c = 0 \quad \text{and} \quad G(x) = e^{-\lambda x} . \\ &\text{Finally, } 1 - F(x) = e^{-\lambda x} , \ F(x) = 1 - e^{-\lambda x} \text{ and } f(x) = F'(x) = \lambda e^{-\lambda x} . \end{split}$$

**Remarks** 

• Assumptions of the previous statement can be slightly depleted.

Forever young property can be assumed of lifetime of appliances when the fault is not • caused by the age. For example, if  $\xi$  is the age of a person, then  $P(\xi \ge 100 | \xi \ge 90) \neq P(\xi \ge 10)$ . In other words, if he survives 90 years, the probability that he survives further 10 years is obviously less than the probability of surviving 10 years from the birth. Exponentially distributed random variables are punctures. Punctures are usually caused by a pin. I we do not enter into a pin until x, the wheel do not remember the previous passage.

Forever young property of the exponentially and geometrically distributed random variables indicates that geometrically distributed random variable is the respective one of the

exponentially distributed random variable. This is supported by the formulas  $E(\xi) = \frac{1}{2}$  and

$$E(\xi) = \frac{1}{\lambda}$$
, respectively.

### Example

E2. The ways between the consecutive punctures are independent exponentially distributed random variables. The probability that there is no puncture until 20000 km equals 0.6. Compute the probability that there is no puncture until 50000 km.

Let  $\xi_1$  the way until the first puncture. Because of the forever young property, we can suppose that the way begins at 0. Actually we do not know the expectation and the value of the parameter, but we know data  $P(\xi_1 < 20000) = 0.6$ , This is suitable for determining the value of the parameter  $\lambda$  as follows. P( $\xi_1 < 20000) = F(20000) = 1 - e^{-\lambda 20000} = 0.6$ .  $e^{-\lambda 20000} = 0.4$ , which implies  $\lambda = \frac{\ln 0.4}{-20000} = 4.58 \cdot 10^{-5}$ . P( $\xi_1 \ge 50000$ ) = 1 -  $(1 - e^{-4.5810^{-5} \cdot 50000}) = 0.101$ . Returning to the question,

Compute the expectation of the way between consecutive punctures.

$$E(\xi_1) = \frac{1}{\lambda} = 21827.$$

Given that the first puncture is not until 50000 km, compute the probability that it is until 70000 km.

$$P(\xi_1 < 70000 | \xi_1 \ge 50000) = P(\xi_1 < 2000) = F(2000) = 1 - e^{-2000} = 0.6$$
.

Given that the first puncture is until 50000 km, compute the probability that it is until 10000 km.

$$P(\xi_1 < 10000 | \xi_1 < 50000) = \frac{P(\xi_1 < 10000 \cap \xi_1 < 50000)}{P(\xi_1 < 50000)} = \frac{P(\xi_1 < 10000)}{P(\xi_1 < 50000)} = \frac{F(10000)}{F(50000)} = 0.408.$$

Theorem (Relationship between the exponentially distributed random variables and Poisson distributed random variable)

Let  $\xi_i$ , i=1,2,3,... be independent exponentially distributed random variables with parameter

$$\lambda \ , \ 0 < T \ fixed \ and \ \eta_T = \begin{cases} 0 & if \quad T \leq \xi_1 \\ 1 & if \quad \xi_1 < T \leq \xi_2 \\ 2 & if \quad \xi_1 + \xi_2 < T \leq \xi_1 + \xi_2 + \xi_3 \\ . \\ . \\ k & if \quad \sum_{i=1}^k \xi_i < T \leq \sum_{i=1}^{k+1} \xi_i \\ . \\ . \\ . \\ . \\ . \end{cases}$$

ſ

Then,  $\eta_T$  is Poisson distributed random variable with parameter  $\,\lambda^*\!=\!\lambda\cdot T$  .

The proof of this statement is omitted as it requires the knowledge of the distribution of the sum of exponentially distributed random variables.

E3. Returning to the Example E2, compute the probability that until 100000 km there are at most 2 punctures.

Denote the number of puncture until T (km) by  $\eta_T$ . Applying the previous statement  $\eta_{100000}$  is Poisson distributed random variable with parameter  $\lambda * = 100000 \lambda = 100000 4.58 \cdot 10^{-5} = 4.58$ .

Consequently, 
$$P(\eta_{100000} \le 2) = P(\eta_{100000} = 0) + P(\eta_{100000} = 1) + P(\eta_{100000} = 2) =$$

$$\frac{4.58^{0}}{0!}e^{-4.58} + \frac{4.58^{1}}{1!}e^{-4.58} + \frac{4.58^{2}}{2!}e^{-4.58} = 0.165.$$

How many punctures happen until 200000 km most likely?

 $\eta_{200000}$  is also Poisson distributed random variable with parameter  $\lambda^{**} = 200000 \cdot 4.58 \cdot 10^{-5} = 9.16$ . As the parameter  $\lambda^{**}$  is not integer, there is a unique mode, namely  $[\lambda^{**}] = [9.16] = 9$ .

### Theorem

If  $\xi$  is exponentially distributed random variables with parameter  $\lambda$ , then  $\eta = [\xi] + 1$  is geometrically distributed random variable with parameter  $p = 1 - e^{-\lambda}$ .

<u>Proof</u> As  $0 < \xi$ ,  $[\xi]$  takes nonnegative integer,  $\eta$  takes positive integer.

$$\begin{split} P(\eta = 1) &= P([\xi] + 1 = 1) = P([\xi] = 0) = P(0 \le \xi < 1) = F(1) - F(0) = 1 - e^{-\lambda 1} - 0 = p \,. \\ P(\eta = 2) &= P([\xi] + 1 = 2) = P([\xi] = 1) = P(1 \le \xi < 2) = F(2) - F(1) = (1 - e^{-\lambda 2}) - (1 - e^{-\lambda 1}) = e^{-\lambda} - e^{-2\lambda} = e^{-\lambda}(1 - e^{-\lambda}) = p(1 - p) \,. \\ Generally, \\ P(\eta = k) &= P([\xi] + 1 = k) = P([\xi] = k - 1) = P(k - 1 \le \xi < k) = F(k) - F(k - 1) = (1 - e^{-\lambda k}) - (1 - e^{-\lambda(k - 1)}) = e^{-\lambda(k - 1)}(1 - e^{-\lambda}) = (e^{-\lambda})^{k - 1}(1 - e^{-\lambda}) = (1 - p)^{k - 1} \cdot p \,, \text{ which is the formula to prove.} \end{split}$$

Example

E4. Telecommunication companies invoices the fee of calls on the basis of minutes. It means that all minutes which were begun have to be paid totally. If the duration of a call is exponentially distributed random variable with expectation 3 minutes, how much is the expectation of its fee if every minute costs 25HUF.

Let  $\xi$  denote the duration of a call. The minutes invoiced are  $\eta = [\xi] + 1$ . The previous statement states that  $\eta$  is geometrically distributed random variable with parameter  $p = 1 - e^{-\lambda} = 1 - e^{-0.5} = 0.393$ . Consequently,  $E(\eta) = \frac{1}{p} = \frac{1}{0.393} = 2.54$ . The expectation of the fee of a call is  $E(25 \cdot \eta) = 25 \cdot E(\eta) = 25 \cdot 2.54 = 63.54$ .

# g.3. Normally distributed random variables

In this subsection we deal with the most important continuous distribution, namely normal distribution. First of all we investigate the standard normal one.

<u>Definition</u> The continuous random variable  $\xi$  is standard normal distributed random variable,

if its probability density function is  $f(x) = \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}}$ ,  $x \in \mathbb{R}$ .

**Remarks** 

• The inequality 0 < f(x) holds for any value of  $x \in \mathbb{R}$ , and it can be proved that  $\int_{-\infty}^{\infty} e^{\frac{-x^2}{2}} dx = \sqrt{2\pi}$ . Consequently,  $\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}} dx = 1$ . This means that f(x) is really probability

density function.

- The above function is often called as Gauss curve and is denoted by  $\varphi(x)$ .
- The function  $\varphi(x)$  is obviously symmetrical to the axis x.
- We use the following notation:  $\xi \sim N(0,1)$ .
- Standard normally distributed random variables take any value.
- The graph of the probability density function can be seen in Fig.g.7.



Figure g.7. Probability density function of a standard normally distributed random variable

• The cumulative distribution function of a standard normally distributed random variable is  $F(x) = \int_{-\infty}^{x} f(t)dt = \int_{-\infty}^{x} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$ , which is the area under the Gauss-curve presented in Fig.g.8.



Figure g.8. The value of the cumulative distribution function as area under the probability density function

• The cumulative distribution function of standard normally distributed random variables is denoted by  $\Phi(x)$  (capital F in Greek alphabet). Its graph can be seen in Fig.g.9.



Figure g.9. Cumulative distribution function of standard normally distributed random variables

• The function  $\Phi$  can not be written in closed form, its values are computed numerically and are included in a table (see Table 1 at the end of the booklet and Table g.2.)

2	$\Phi(\mathbf{x})$
0	0.5
1	0.8413
2	0.9773
3	0.9986

Table g.2. Some values of the cumulative distribution function of standard normally distributed random variables

Data from this table can be read out as follows:  $\Phi(0) = 0.5$ ,  $\Phi(1) = 0.8413$ ,  $\Phi(2) = 0.9773$ ,  $\Phi(3) = 0.9986$ .

### Remarks

• The tables do not contain arguments greater than 3.8. As the cumulative distribution function is monotone increasing and it takes values at most 1, furthermore  $\Phi(3.8) = 0.99993$ ,  $0.9999 < \Phi(x) < 1$  in case of 3.8 < x. We use  $\Phi(x) \approx 1$  for 3.8 < x.

• The tables do not contain arguments less than 0, because the values at negative arguments can be computed as follows.

#### Theorem

If 
$$0 \le x$$
, then  $\Phi(-x) = 1 - \Phi(x)$ 

<u>Proof</u> The proof is based on the symmetry of the probability density function.  $\Phi(-x) = \int_{-\infty}^{-x} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt = 1 - \int_{-\infty}^{x} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt = 1 - \Phi(x).$ 

Expressively, stripped areas of the Fig.g.9. are equal.



Figure g.9. Equal areas under the standard normal probability density function due to its symmetry

Obviously,  $\Phi(-x) = 1 - \Phi(x)$  holds for any value of x.

 $\frac{\text{Theorem}}{\text{If } \xi \sim N(0,1) \text{, then } -\xi \sim N(0,1) \text{ holds, as well.}}$   $\frac{\text{Proof}}{\text{Fq}} \text{Let } \eta = -\xi.$   $F_{\eta}(x) = P(\eta < x) = P(-\xi < x) = P(0 < \xi + x) = P(-x < \xi) = 1 - \Phi(-x) = 1 - (1 - \Phi(x)) = \Phi(x).$ Now  $f_{\eta}(x) = F_{\eta}'(x) = \Phi'(x) = \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}}, \text{ which proves the statement.}$ 

Numerical characteristics of standard normally distributed random variables:

Expectation

E(\xi) = 0. It follows from the fact that 
$$\int x \cdot e^{\frac{x^2}{2}} dx = -e^{\frac{x^2}{2}}$$
 and

$$E(\xi) = \int_{-\infty}^{\infty} x \cdot f(x) dx = \int_{-\infty}^{\infty} x \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx = \lim_{x \to \infty} -\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} - \lim_{x \to -\infty} -\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} = 0.$$

### **Dispersion**

 $D(\xi) = 1$ . As a proof, recall that  $D^{2}(\xi) = E(\xi^{2}) - (E(\xi))^{2}$ . Applying partially integration

$$E(\xi^{2}) = \int_{-\infty}^{\infty} x^{2} f(x) dx = \int_{-\infty}^{\infty} x^{2} \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^{2}}{2}} dx = \int_{-\infty}^{\infty} x \cdot x \frac{1}{\sqrt{2\pi}} e^{-\frac{x^{2}}{2}} dx = \left[ x \frac{-1}{\sqrt{2\pi}} e^{-\frac{x^{2}}{2}} \right]_{-\infty}^{\infty} + \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^{2}}{2}} dx$$

Recalling L' Hopital law we get

 $\lim_{x \to \infty} x \frac{-1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} = \lim_{x \to -\infty} x \frac{-1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} = 0. \text{ Moreover, } \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx = 1, \text{ as } \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \text{ is a}$ 

probability density function. Consequently,  $D^2(\xi) = E(\xi^2) - (E(\xi))^2 = 1 - 0^2 = 0$ , which proves the statement.

# Mode

Local maximum of  $\varphi$  is at x = 0, consequently the mode is zero.

#### Median

me=0. We have to find the value x for which  $\Phi(x)=0.5$ . Using the table of cumulative distribution function of standard normal distribution, we get x = 0.

#### Example

E1. Let  $\xi$  be standard normally distributed random variable. Compute the probability that  $\xi$  is less than 2.5.

 $P(\xi < 2.5) = \Phi(2.5) = 0.9938.$ 

Compute the probability that  $\xi$  is greater than -1.2.

 $P(-1.2 < \xi) = 1 - \Phi(-1.2) = 1 - (1 - \Phi(1.2)) = \Phi(1.2) = 0.8849.$ 

Compute the probability that  $\xi$  is between -0.5 and 0.5.

 $P(-0.5 < \xi < 0.5) = \Phi(0.5) - \Phi(-0.5) = \Phi(0.5) - (1 - \Phi(0.5)) = 2\Phi(0.5) - 1 = 2 \cdot 0.6915 - 1 = 0.3830.$ At most how much is  $\xi$  with probability 0.9?

x=?  $P(\xi \le x) = 0.9$ .  $P(\xi \le x) = \Phi(x) = 0.9$ . We have to find the value 0.9 in the columns of  $\Phi$ , as the value of the function equals 0.9. Therefore, x = 1.28.

At least how much is 
$$\xi$$
 with probability 0.95?

x=?  $P(\xi \ge x) = 0.95$ .  $1 - \Phi(x) = 0.95 \Rightarrow \Phi(x) = 0.05$ . As  $\Phi(x) < 0.5$  and  $\Phi$  is monotone increasing function, x < 0. If we denote x = -a, 0 < a and  $\Phi(x) = \Phi(-a) = 1 - \Phi(a) = 0.05$ . This implies  $\Phi(a) = 0.95$  and a = 1.645. Finally, we end in x = -1.645.

Give an interval symmetrical to 0 in which the values of  $\xi$  are situated with probability 0.99. x=? P(-x <  $\xi$  < x) = 0.99. P(-x <  $\xi$  < x) =  $\Phi(x) - \Phi(-x) = 2\Phi(x) - 1 = 0.99$ . This implies  $\Phi(x) = 0.995$  and x = 2.58. The interval is (-2.58, 2.58) Now we turn to the general form of normal distribution.

<u>Definition</u> Let  $\xi$  be standard normal distributed random variable,  $m \in \mathbb{R}$  and  $0 < \sigma$ . The random variable  $\eta = \sigma \xi + m$  is called **normally distributed random variable with parameters** m and  $\sigma$ . We use notation  $\eta \sim N(m, \sigma)$ .

Remarks

• With m=0 and  $\sigma=1$ ,  $\eta=\sigma\xi+m=\xi$  is standard normally distributed random variable. It fits with notation  $\xi \sim N(0,1)$ .

•  $\eta$  is linear transformation of a standard normally distributed random variable.

• If a < 0 and  $m \in R$ , then  $\eta = a\xi + m = (-a)(-\xi) + m$ . Recall that  $-\xi \sim N(0,1)$  holds as well, furthermore 0 < -a, consequently  $\eta$  is normally distributed random variable with parameters m and -a.

<u>Theorem</u> Let  $\xi$  be standard normally distributed random variable,  $m \in \mathbb{R}$  and  $0 < \sigma$ . The cumulative distribution function of the random variable  $\eta = \sigma \xi + m$  is  $F_{\eta}(x) = \Phi(\frac{x-m}{\sigma})$  and the probability density function of  $\eta$  is  $f_{\eta}(x) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-m)^2}{2\sigma^2}}$ . <u>Proof</u>  $F_{\eta}(x) = P(\sigma\xi + m <) = P(\xi < \frac{x-m}{\sigma}) = \Phi(\frac{x-m}{\sigma})$ .  $f_{\eta}(x) = F_{\eta}'(x) = \left(\Phi(\frac{x-m}{\sigma})\right)' \cdot \frac{1}{\sigma} = \phi(\frac{x-m}{\sigma}) \cdot \frac{1}{\sigma} = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-m)^2}{2\sigma^2}}$ .

The graph of the cumulative distribution functions can be seen in Fig.g.10. In all cases m=0, red line is for  $\sigma=1$ , yellow line is for  $\sigma=2$ , blue line is for  $\sigma=4$  and green line is for  $\sigma=0.5$ .



Figure g.10. Cumulative distribution functions for normally distributed random variables for different values of  $\sigma$ 

The graph of the probability distribution functions be seen in Fig.g.11. In all cases m = 0, red line is for  $\sigma = 1$ , yellow line is for  $\sigma = 2$ , blue line is for  $\sigma = 4$  and green line is for  $\sigma = 0.5$ .



Figure g.10. Probability density functions for normally distributed random variables for different values of  $\sigma$ 

One can notice that if the value of  $\sigma$  is large, then the curve is depressed, if the value of  $\sigma$  is small, then the curve is peaky. It is the obvious consequence of the fact that the peak is at high

of 
$$\frac{1}{\sqrt{2\pi\sigma}}$$

If we want to present the roll of parameter m, then we can notice that the probability density function is symmetric to m. In fig.g.11., the parameter  $\sigma$  equals 1, red line is for m=0, blue line is for m=1 and green line is for m=-1.



Figure g.11. Probability density functions for normally distributed random variables for different values of m

Numerical characteristics of normally distributed random variables:

## Expectation

If  $\eta \sim N(m, \sigma)$ , then  $E(\eta) = m$ . It follows from the fact that

 $E(\eta) = E(\sigma \cdot \xi = m) = \sigma E(\xi) + m = \sigma \cdot 0 + m = m.$ 

Dispersion

If  $\eta \sim N(m, \sigma)$ , then  $D(\eta) = \sigma$ . To prove it, take into consideration that  $D(\eta) = D(\sigma \cdot \xi = m) = \sigma D(\xi) = \sigma \cdot 1 = \sigma$ .

Summarizing, the first parameter is the expectation, the second one is the dispersion.

#### Mode

Local maximum of  $f_n(x)$  is at x = m, consequently the mode is m.

### Median

me = m. We have to find the value x for which  $F_{\eta}(x) = 0.5$ . This means  $\Phi(\frac{x-m}{\sigma}) = 0.5$ . It implies  $\frac{x-m}{\sigma} = 0 \Rightarrow x = m$ .

### Example

E2. Let  $\eta \sim N(5,2)$ . Compute the probability that  $\eta$  is less than 0.

$$P(\eta < 0) = F_{\eta}(x) = \Phi(\frac{0-5}{2}) = \Phi(-2.5) = 1 - \Phi(2.5) = 1 - 0.9938 = 0.0062$$

Compute the probability that the value of  $\eta$  is between 0 and 6.

 $P(0 < \eta < 6) = F_{\eta}(6) - F_{\eta}(0) = \Phi(\frac{6-5}{2}) - \Phi(\frac{0-5}{2}) = \Phi(0.5) - \Phi(-2.5) = 0.6915 - 0.0062 = 0.6853.$ Compute the probability that the value of  $\eta$  is greater than 6.

$$6-5$$

$$P(6 < \eta) = 1 - F_{\eta}(6) = 1 - \Phi(\frac{0 - 3}{2}) = 1 - \Phi(0.5) = 1 - 0.6915 = 0.3085.$$

At most how much is the value of  $\eta$  with probability 0.8?

x=? 
$$P(\eta \le x) = 0.8$$
.  $\Phi(\frac{x-5}{2}) = 0.8$ . As  $\Phi(0.84) \approx 0.8$ , therefore  $\frac{x-5}{2} = 0.84$ . This implies  $x = 5 + 0.84 \cdot 2 = 6.68$ .

At least how much is the value of  $\eta$  with probability 0.98?

x=?  $P(x \le \eta) = 0.98$ .  $P(x \le \eta) = 1 - \Phi(\frac{x-5}{2}) = 0.98$ .  $\Phi(\frac{x-5}{2}) = 0.02$ . If we introduce new variable  $y = \frac{x-5}{2}$ , we reduce our task to determine the solution of  $\Phi(y) = 0.02$ . This type of problem was previously solved. We can first realize that y is negative and if y = -a, then  $\Phi(a) = 0.98$ . Consequently, a = 2.33, y = -2.33, that is  $\frac{x-5}{2} = -2.33$ . Finally, arranging the equation we get  $x = 5 - 2.33 \cdot 2 = 0.34$ .

Compute the value of the probability density function at 6.  $(1 - 1)^2$ 

$$f_{\eta}(6) = \frac{1}{\sqrt{2\pi}} e^{\frac{-(6-5)^2}{2\cdot 2^2}} = 0.176.$$

<u>Theorem</u> (k times  $\sigma$  law) If  $\eta \sim N(m, \sigma)$ , then  $P(m - k\sigma < \eta < m + k\sigma) = 2\Phi(k) - 1$ .

<u>Proof</u> The proof is very simple, compute the probability.  $P(m - k\sigma < \eta < m + k\sigma) = F_{\eta}(m + k\sigma) - F_{\eta}(m - k\sigma) = \Phi(\frac{m + k\sigma - m}{\sigma}) \Phi(\frac{m - k\sigma - m}{\sigma}) = \Phi(k) - \Phi(-k) = \Phi(k) - (1 - \Phi(k)) = 2\Phi(k) - 1.$ 

Remarks

• Substituting the values k = 0,1,2,3 into the previous formula, we get  $P(m - \sigma < \eta < m + \sigma) = 2\Phi(1) - 1 = 2 \cdot 0.8413 - 1 = 0.6826$ ,  $P(m - 2\sigma < \eta < m + 2\sigma) = 2\Phi(2) - 1 = 2 \cdot 0.9772 - 1 = 0.9544$ ,  $P(m - 3\sigma < \eta < m + 3\sigma) = 2\Phi(3) - 1 = 2 \cdot 0.9987 - 1 = 0.9974$ .

• The last equality states that a normally distributed random variable takes its values in the interval symmetrical to the expectation and radius 3 times dispersion with probability almost 1.

• The probability density function with parameters m=1 and  $\sigma=1$ , for k=1,2 present the k times  $\sigma$  law (see Fig.g.12.).



Figure g.12. The areas under the probability density function

Example

E3. Let  $\eta \sim N(3,12)$ . Give an interval, symmetrical to 3, in which the values of  $\eta$  are situated with probability 0.99!

Apply "k times  $\sigma$ " law. As the required probability equals 0.99, consequently,  $2\Phi(k) - 1 = 0.99$ . This implies  $\Phi(k) = 0.995$ , and as a consequence, k = 2.58. Therefore the interval looks  $(m - k\sigma, m + k\sigma) = (3 - 12 \cdot 2.58, 3 + 12 \cdot 2.58) = (-27.96, 33.96)$ . It is also presented in Fig.g.13.



Figure g.13. Area 0.99 under the probability density function

<u>Theorem</u> If  $\eta$  is normally distributed random variable, then so is its linear transformation. Namely, if  $\eta \sim N(m, \sigma)$ ,  $a \neq 0$ , then  $\theta = a\eta + b \sim N(a \cdot m + b, |a| \cdot \sigma)$ . Proof

Recall the definition of the normally distributed random variable,  $\eta = \sigma \cdot \xi + m$  with  $\xi \sim N(0,1)$ .  $\theta = a\eta + b = a(\sigma \cdot \xi + m) + b = a\sigma\xi + am + b$ . If 0 < a, then  $\theta \sim N(am + b, a\sigma)$ , if a < 0, then  $\theta \sim N(am + b, -a\sigma)$ . Summarizing these formulas we get the statement to be proved.

<u>Theorem</u> If  $\eta_1 \sim N(m_1, \sigma_1)$ ,  $\eta_2 \sim N(m_2, \sigma_2)$  furthermore  $\eta_1$  and  $\eta_2$  are independent, then  $\eta_1 + \eta_2 \sim N(m_1 + m_2, \sqrt{\sigma_1^2 + \sigma_2^2})$ .

#### Remarks

• Although we can not prove the previous statement, notice, that the parameters are calculated according to the properties of expectation and variance. The first parameter is the expectation. Expectation of the sum is the sum of expectations. The second parameter is dispersion. Dispersions can not be given, but variances can.  $D^2(\eta_1 + \eta_2) = D^2(\eta_1) + D^2(\eta_2)$ , therefore  $D(\eta_1 + \eta_2) = \sqrt{\sigma_1^2 + \sigma_2^2}$ .

• As a consequence of the previous statement we emphasize the following: If  $\xi_i$  i = 1,2,3,...,n are independent identically distributed random variables,  $\xi_i \sim N(m,\sigma)$ , then  $\boxed{\sum_{i=1}^{n} \xi_i \sim N(n \cdot m, \sigma \cdot \sqrt{n})}$ . • If  $\xi_i$  i = 1,2,3,...,n are independent identically distributed random variables,  $\xi_i \sim N(m,\sigma)$ , then  $\boxed{\frac{\sum_{i=1}^{n} \xi_i}{n} \sim N\left(m, \frac{\sigma}{\sqrt{n}}\right)}$ .

Example

E4. Weights of adults are normally distributed random variables with expectation 75kg and dispersion 10 kg. Weights of 5 year children are also normally distributed random variables with expectation 18 kg and dispersion 3 kg. Compute the probability that the average weight of 20 adults is less than 70 kg.

$$\xi_{a} \sim N(75,10), \ \xi_{c} \sim N(18,2). \frac{\sum_{i=1}^{20} \xi_{a,i}}{20} \sim N(75,\frac{10}{\sqrt{20}}),$$
$$P(\frac{\sum_{i=1}^{20} \xi_{a,i}}{20} < 70) = F_{20} \sum_{\substack{i=1\\ j=1\\ \frac{1}{20}}} (70) = \Phi(\frac{70-75}{2.236}) = \Phi(-2.236) = 1 - \Phi(2.236) = 1 - 0.9873 = 0.0127.$$

Give an interval symmetrical to 75kg in which the average weight of 10 adults is with probability 0.9.

 $\frac{\sum_{i=1}^{20} \xi_{a,i}}{10} \sim N(75, \frac{10}{\sqrt{10}})$ . To answer the question apply the "k times  $\sigma$  law" with expectation 75

and dispersion  $10/\sqrt{10}$ .  $2\Phi(k) - 1 = 0.9$  implies k = 1.645, therefore the required interval looks  $(75 - 1.645 \cdot 3.16, 75 + 1.645 \cdot 3.16) = (69.8, 80.2)$ .

At most how much is the total weight of 6 adults in the elevator with probability 0.98?

x=? 
$$P(\sum_{i=1}^{6} \xi_{a,i} < x) = 0.98$$
.  $\sum_{i=1}^{6} \xi_{a,i} \sim N(6 \cdot 75, \sqrt{6} \cdot 10)$ . It means that  $\Phi_{\substack{6 \\ \sum \xi_{a,i} \\ i=1}}^{6} (x) = 0.98$ .

$$\Phi(\frac{x-450}{24.495}) = 0.98$$
. Consequently,  $\frac{x-450}{24.495} = 2.06$ , finally  
x = 450+24.495 \cdot 2.06 = 500.46 kg \approx 500 kg.

Compute the probability that the total weight of an adult and a 5 year child is more than 100 kg, if their weights are independent.

$$\xi_{a} + \xi_{c} \sim N(75 + 18, \sqrt{10^{2} + 3^{2}}),$$
  

$$P(100 < \xi_{a} + \xi_{c}) = 1 - F_{\xi_{a} + \xi_{c}}(100) = 1 - \Phi(\frac{100 - 93}{13.82}) = 1 - 0.6937 = 0.3063$$

E5. Daily return of a shop is normally distributed random variable with expectation 1 million HUF and dispersion 0.2 million HUF. Suppose that returns belonging to different days are independent random variables. Compute the probability that there is at most 0.1 million HUF difference between the returns of two different days.

Let  $\xi_1$  denote the return of the first day,  $\xi_2$  denote the return of the second day.  $\xi_1 \sim N(1,0.2)$ ,  $\xi_2 \sim N(1,0.2)$ . The question is  $P(|\xi_1 - \xi_2| < 0.1)$ .

$$P(|\xi_1 - \xi_2| < 0.1) = P(-0.1 < \xi_1 - \xi_2 < 0.1) = F_{\xi_1 - \xi_2}(0.1) - F_{\xi_1 - \xi_2}(-0.1).$$

If we knew the cumulative distribution function of  $\xi_1 - \xi_2$ , then we can substitute 0.1 and -0.1 into it.

As 
$$\xi_1 - \xi_2 = \xi_1 + (-\xi_2)$$
, furthermore  $-\xi_2 \sim N(-1, 0.2)$ ,  $\xi_1 - \xi_2 \sim N(1 - 1, \sqrt{0.2^2 + 0.2^2})$ .  
Consequently,  $\xi_1 - \xi_2 \sim N(0, 0.283)$ . This implies  $F_{\xi_1 - \xi_2}(x) = \Phi(\frac{x - 0}{0.283})$ .

Finally, 
$$P(|\xi_1 - \xi_2| < 0.1) = \Phi(\frac{0.1}{0.283}) - \Phi(\frac{-0.1}{0.283}) = 2\Phi(\frac{0.1}{0.283}) - 1 = 2 \cdot 0.6381 - 1 = 0.2762.$$

Compute the probability that the return of a fixed day is less than the 80% of the return of another day.

 $P(\xi_1 < 0.8 \cdot \xi_2) = ? P(\xi_1 < 0.8 \cdot \xi_2) = P(\xi_1 - 0.8 \cdot \xi_2 < 0) = F_{\xi_1 - 0.8\xi_2}(0).$ 

If we knew the cumulative distribution function of  $\xi_1 - 0.8\xi_2$ , then we could substitute 0 into it.

$$\xi_2 \sim N(0.8 \cdot 1, 0.8 \cdot 0.2), -\xi_2 \sim N(-0.8 \cdot 1, 0.8 \cdot 0.2).$$

 $\xi_1 - 0.8 \cdot \xi_2 \sim N(1 - 0.8, \sqrt{0.2^2 + (0.8 \cdot 0.2)^2})$ . Consequently,  $\xi_1 - 0.8 \cdot \xi_2 \sim N(0.2, 0.256)$ . Now we can finish computations as follows:

$$P(\xi_1 < 0.8 \cdot \xi_2) = F_{\xi_1 < 0.8 \cdot \xi_2}(0) = \Phi(\frac{0 - 0.2}{0.256}) = \Phi(-0.78) = 0.2173.$$

# g.4. Further distributions derived from normally distributed ones

In statistics, there are many other distributions which are originates from normal ones. Actually we investigate chi-square and Student's t distributions. We will use them in chapter j, as well.

<u>Definition</u> Let  $\xi \sim N(0,1)$ . Then  $\theta = \xi^2$  is called **chi-squared distributed random variable** with degree of freedom 1 and it is denoted by  $\theta \sim \chi_1^2$ 

<u>Theorem</u> The cumulative distribution function of  $\theta = \xi^2$  is  $F_{\theta}(x) = \begin{cases} 0 & \text{if } x \le 0 \\ 2\Phi(\sqrt{x}) - 1 & \text{if } 0 < x \end{cases}$ .

The probability density function of  $\eta$  is  $f_{\theta}(x) = \begin{cases} 0 & \text{if } x < 0 \\ \frac{1}{\sqrt{2\pi}} e^{\frac{-x}{2}} \cdot \frac{1}{\sqrt{x}} & 0 < x \end{cases}$ .

Proof

All of values of 
$$\chi_1^2$$
 are nonnegative, consequently,  $F_{\chi_1^2}(x) = 0$ , if  $x \le 0$ . For positive x values,  
 $F_{\theta}(x) = P(\theta < x) = P(\xi^2 < x) = P(-\sqrt{x} < \xi < \sqrt{x}) = F_{\xi}(\sqrt{x}) - F_{\xi}(-\sqrt{x}) = \Phi(\sqrt{x}) - \Phi(-\sqrt{x})$   
 $= 2\Phi(\sqrt{x}) - 1.$   
 $f_{\theta}(x) = \left(F_{\theta}\right)'(x) = \begin{cases} 0 \text{ if } x < 0 \\ 2 \cdot \Phi'(\sqrt{x}) \cdot (\sqrt{x})' = 2 \cdot \frac{1}{\sqrt{2\pi}} e^{\frac{-(\sqrt{x})^2}{2}} \cdot \frac{1}{2\sqrt{x}} = \frac{1}{\sqrt{2\pi} \cdot \sqrt{x}} e^{-\frac{x}{2}} & \text{if } 0 < x \end{cases}$ 

The graph of the above cumulative distribution function and the probability density function can be seen in Fig. g.14.



Figure g.14. Graph of the cumulative distribution function and the probability density function of  $\chi_1^2$  distributed random variables

Numerical characteristics of chi-squared distributed random variables with degree of freedom <u>1:</u>

### Expectation

 $E(\theta) = 1$ , which is a straightforward consequence of  $E(\xi^2) = D^2(\xi) + (E(\xi))^2 = 1 + 0 = 1$ .

## **Dispersion**

 $D(\theta) = \sqrt{2}$ , which can be computed by partial integrating.

## Mode

There is no local maximum for the probability density function.

### Median

me = 0.675. We have to solve equation  $2\Phi(\sqrt{x}) - 1 = 0.5$ , that is  $\Phi(x) = 0.75$ . It is satisfied by x = 0.675.

<u>Definition</u> Let  $\xi_i \sim N(0,1), i = 1,2,3,..,n$ , and let  $\xi_i$  be independent. Then  $\theta = \sum_{i=1}^n \xi_i^2$  is called **chi-squared distributed random variable with degree of freedom n** and is denoted by  $\theta \sim \chi_n^2$ 

# Theorem

Probability density function of  $\chi_n^2$  distributed random variable is  $f_{\theta}(x) = \begin{cases} \frac{x^{\frac{n}{2}-1}e^{\frac{-x}{2}}}{2} & \text{if } 0 < x \\ \frac{2^{\frac{n}{2}}\Gamma(\frac{n}{2})}{0} & . \end{cases}$ 

The function  $\Gamma$  is the generalization of factorial for non integer values.  $\Gamma(0.5) = \sqrt{\pi}$ , furthermore  $\Gamma(x+1) = n \cdot \Gamma(x)$ .

The graph of the probability density function of  $\chi_n^2$  distributed random variable with degree of freedom n = 5 can be seen in Fig.g.15.



Figure g.15. Graph of the probability density function of  $\chi_5^2$  distributed random variables

## Remarks

• If n=2, the probability density function coincides with that of exponentially distributed random variable with parameter  $\lambda = 0.5$ .

• For general values of n, explicit form of cumulative distributions function of  $\chi_n^2$  is quite complicated, it is not usually used. The values for which the cumulative distribution function reaches certain levels are included in tables used in statistics. These tables are used in chapter j, as well. For example, if we seek the value x for which  $P(x < \chi_5^2) = 0.95$  holds, we get x = 11.07 (see Table 3 at the end of the booklet.)

Usually, the real number x for which  $P(x < \theta) = \alpha$  holds, can be found in tables and is denoted by  $\chi^2_{n,\alpha}$  (see Table 2 at the end of the booklet).



Figure g.15. The value exceeded with probability 0.05 in case of  $\chi_5^2$ 

Numerical characteristics of chi-squared distributed random variable:

### Expectation

 $E(\theta) = n$ , which is a straightforward consequence of  $E(\sum_{i=1}^{n} \xi_{i}^{2}) = \sum_{i=1}^{n} E(\xi_{i}^{2}) = n$ .

**Dispersion** 

$$D(\theta) = \sqrt{2n}$$
, which follows from  $D(\sum_{i=1}^{n} \xi_i^2) = \sum_{i=1}^{n} D^2(\xi_i^2) = 2 \cdot n$ .

Mode

There is no mode if  $n \le 2$ , and it is n - 2, if 2 < n.

Median

It can not be expressed explicitly, it is about  $n(1-\frac{2}{9n})^3$ 

<u>Definition</u> Let  $\xi_1, \xi_2, ..., \xi_n$  and  $\eta$  independent standard normally distributed random variables. The random variable  $\theta = \frac{\eta}{\sum_{i=1}^{n} \xi_i^2}$  is called **Student's t distributed random variable with** 

degree of freedom n and is denoted by  $\theta \sim \tau_n$ .

# Theorem

The probability density function of a Student's t distributed random variable with degree of

freedom n is 
$$f_n(x) = \frac{\Gamma(\frac{n+1}{2})}{\sqrt{n\pi} \cdot \Gamma(\frac{n}{2})} \left(1 + \frac{x^2}{n}\right)^{-\frac{n+2}{2}}$$

Remarks

• If n is odd, then the normalising constant is  $\frac{1}{2\sqrt{n}} \frac{(n-1)(n-3)...5\cdot 3}{(n-2)(n-4)...4\cdot 2}$ , and if n is even,

then it is  $\frac{1}{\pi\sqrt{n}} \frac{(n-1)(n-3)...4\cdot 2}{(n-2)(n-4)...5\cdot 3}$ .

• If n=1, then  $f_1(x) = \frac{1}{\pi} \cdot \frac{1}{1+x^2}$ . The random variable with this probability density

function is called Cauchy distributed random variable.

• If 
$$n \to \infty$$
, then  $\left(1 + \frac{x^2}{n}\right)^{-\frac{n+1}{2}} \to e^{\frac{-x^2}{2}}$ , consequently  $f_n(x) \to \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}} = \varphi(x)$  for

any values of x.

• The probability density functions of  $\tau_n$  distributed random variable can be seen in Fig.g.16.



Figure g.16. Probability density functions of  $\tau_n$  distributed random variable for n = 1 (black), n = 5 (red) and n = 100 (blue)

• Closed form of the cumulative distribution functions do not exist. The values for which the cumulative distribution function reach different levels are included in tables used in statistics (see Table 2 at the end of the booklet). These tables are used in chapter j, as well.

Supposing  $\theta \sim \tau_n$ , the value, for which  $P(-x \le \theta \le x) = 1 - \alpha$  and  $P(\alpha < |\theta|) = \alpha$  is usually denoted by  $t_{n,\alpha}$ . For example, if  $\alpha = 0.2$  and n = 5,  $t_{5,0.2} = 0.92$ . It is also presented in Fig. g.17.



Figure g.17. Bounds for  $\tau_5$  distributed random variables with probability 0.8

Numerical characteristics of chi-squared distributed random variable:

# Expectation

If  $\theta \sim \tau_n$ , then  $E(\theta) = 0$ , if 1 < n. It is straightforward consequence of the symmetry of the probability density function. If n = 1, expectation does not exist.

### Dispersion

 $D(\theta) = \frac{\sqrt{n-2}}{\sqrt{n}}$ , if 2 < n, otherwise it does not exist. It can be computed by partial integrating.

### <u>Mode</u> It is always zero.

-

# Median

It is always zero, due to the symmetry of probability density function.

# h. Law of large numbers

# The aim of this chapter

In this chapter we present asymptotical theorems which characterize the behaviour of the average of many independent identically distributed random variables. We return to the relative frequency, as well, and we prove that it is about the probability of the event. These theorems are the theoretical basis of the pools and computer simulations.

# Preliminary knowledge

Expectation, dispersion and their properties. Binomially distributed random variables.

# Content

- h.1. Markov's and Chebisev's inequalities.
- h.2. Law of large numbers.
- h.3. Bernoulli's theorem.

### h.1. Markov and Chebisev's inequalities

First we provide estimations for certain probabilities. Although these estimations are quite rough, they are appropriate to be applied for proving asymptotical statement. Their main advantage that they do not require the knowledge of the distribution of the random variable, they use only the expectation and dispersion.

Theorem (Markov's inequality)

Let  $\xi$  be a random variable all of values of that is nonnegative and  $E(\xi)$  exists. Then, for any  $0 < \varepsilon$  the following inequality holds:  $P(\xi \ge \varepsilon) \le \frac{E(\xi)}{\varepsilon}$ .

Proof

The proof is based on the following:  $\varepsilon \cdot \mathbf{1}_{\xi \ge \varepsilon} \le \xi$ . Recall that  $\mathbf{1}_{A} = \begin{cases} 1 & \text{if } A \text{ holds} \\ 0 & \text{if } A \text{ does not hold} \end{cases}$ . This implies  $\mathbf{1}_{\xi \ge \varepsilon} = \begin{cases} 1 & \text{if } \xi \ge \varepsilon \text{ holds} \\ 0 & \text{if } \xi < \varepsilon \text{ holds} \end{cases}$ .

Multiplying by  $\varepsilon$  we get  $\varepsilon \cdot \mathbf{1}_{\xi \ge \varepsilon} = \begin{cases} \varepsilon & \text{if } \xi \ge \varepsilon \text{ holds} \\ 0 & \text{if } \xi < \varepsilon \text{ holds} \end{cases}$ . Taking into account the nonnegativity of  $\xi$ , this means that  $\varepsilon \cdot \mathbf{1}_{\xi \ge \varepsilon} \le \xi$ . Applying the following property of expectation  $\eta_1 \le \eta_2 \Longrightarrow E(\eta_1) \le E(\eta_2)$ , we can see that  $E(\varepsilon \cdot \mathbf{1}_{\xi \ge \varepsilon}) = \varepsilon \cdot E(\mathbf{1}_{\xi \ge \varepsilon}) \le E(\xi)$ . Recalling that  $E(\mathbf{1}_A) = P(A)$  and dividing both sides by  $0 < \varepsilon$  the inequality ends in  $P(\xi \ge \varepsilon) \le \frac{E(\xi)}{\varepsilon}$ . This is the statement to be proved.

Theorem (Chebisev's inequality)

Let  $\eta$  be a random variable those dispersion exists. Then for any  $0 < \lambda$ , the following inequality is satisfied:  $P(|\eta - E(\eta)| \ge \lambda) \le \frac{D^2(\eta)}{\lambda^2}$ .

<u>Proof</u> Note that  $|\eta - E(\eta)| \ge \lambda$  holds if and only if  $(\eta - E(\eta))^2 \ge \lambda^2$ . Consequently,  $P(|\eta - E(\eta)| \ge \lambda) = P((\eta - E(\eta))^2 \ge \lambda^2)$ . Apply Markov inequality with  $\xi = (\eta - E(\eta))^2$  and  $\varepsilon = \lambda^2$ . Non-negativity obviously holds, and  $E(\xi) = E((\eta - E(\eta))^2) = D^2(\eta)$ . Therefore,  $P(|\eta - E(\eta)| \ge \lambda) = P(\xi \ge \varepsilon) \le \frac{E(\xi)}{\varepsilon} = \frac{D^2(\eta)}{\lambda^2}$ , and it is the statement to be proved.

Remark

• Chebisev's inequality can be also written in the following form:  $P(|\eta - E(\eta)| < \lambda) \ge 1 - \frac{D^{2}(\eta)}{\lambda^{2}}. \quad \{|\eta - E(\eta)| < \lambda\}\} \text{ is the compliment of the event}$   $\{|\eta - E(\eta)| \ge \lambda\}. \text{ If } P(A) \le x \text{ , then } P(\overline{A}) = 1 - P(A) \ge 1 - x \text{ , which implies the statement.}$ 

• Chebisev's inequality can be also written as follows:  $P(|\eta - E(\eta)| \ge kD(\eta)) \le \frac{1}{\ln^2}$ 

and  $P(|\eta - E(\eta)| < kD(\eta)) \ge 1 - \frac{1}{k^2}$ . Substitute  $\lambda = kD(\eta)$ . It can be done with  $k = \frac{\lambda}{D(\eta)}$ , supposing  $D(\eta) \ne 0$ . If  $D(\eta) = 0$ , then on the basis of the property of dispersion,  $P(\eta = E(\eta)) = 1$ , therefore  $P(|\eta - E(\eta)|) \ge kD(\eta)) = 0$  which is less than  $\frac{1}{k^2}$  for any value of k.

• The inequality  $P(|\eta - E(\eta)| \ge kD(\eta)) \le \frac{1}{k^2}$  expresses that the random variable  $\eta$  takes its values out of the neighbourhood with radius  $kD(\eta)$  of its expectation with probability not larger than  $\frac{1}{k^2}$ . Large deviation is with small probability.

• The inequality  $P(|\eta - E(\eta)| < kD(\eta)) \ge 1 - \frac{1}{k^2}$  states that a random variable  $\eta$  takes its values in the neighbourhood with radius  $kD(\eta)$  of its expectation with probability no smaller than  $1 - \frac{1}{k^2}$ . Small deviation is with large probability.

• The proofs do not use the distribution of the random variable.

• If we knew the distribution of  $\eta$ , the probabilities  $P(|\eta - E(\eta)| \ge kD(\eta))$  and  $P(|\eta - E(\eta)| < kD(\eta))$  can be computed explicitly.

# Example

E1. Let  $\eta$  be Poisson distributed random variable with parameter  $\lambda = 2$ . Compute the probability that the values of  $\eta$  are in the neighbourhood with radius  $D(\eta)$  of its expectation.

$$\begin{split} E(\eta) &= \lambda = 2, \qquad D(\eta) = \sqrt{\lambda} = \sqrt{2} = 1.41. \qquad \left| \eta - E(\eta) \right| < D(\eta) \qquad \text{means that} \\ E(\eta) - D(\eta) < \eta < E(\eta) + D(\eta). \qquad \text{Explicitly,} \qquad 2 - \sqrt{2} < \eta < 2 + \sqrt{2}, \qquad \text{that is } \qquad 0.59 < \eta < 3.41. \\ \text{Now } P(0.59 < \eta < 3.41) = P(\eta = 1) + P(\eta = 2) + P(\eta = 3) = \frac{2^1}{1!} e^{-2} + \frac{2^2}{2!} e^{-2} + \frac{2^3}{3!} e^{-2} = 0.722. \end{split}$$

E2. Let  $\eta$  be uniformly distributed random variable in [-1,2]=[a,b]. Compute the probability that  $\eta$  takes its value in the in the neighbourhood with radius  $1.5 \cdot D(\eta)$  of its expectation.

$$E(\eta) = \frac{a+b}{2} = \frac{-1+2}{2} = 0.5. \quad D(\eta) = \frac{b-a}{\sqrt{12}} = \frac{2-(-1)}{\sqrt{12}} = \frac{3}{2\sqrt{3}} = 0.866. \quad 1.5 \cdot D(\eta) = 1.299.$$

The interval is (0.5 - 1.2999, 0.5 + 1.299) = (-0.799, 1.299). The question can be written as  $P(\eta \in (-0.799, 1.799)) = P(-0.799 < \eta < 1.799) = F(1.799) - F(-0.799)$ . Recalling that

$$F(x) = \begin{cases} 0 & \text{if } x \le a = -1 \\ \frac{x-a}{b-a} = \frac{x+1}{3} & \text{if } -1 = a < x \le b = 2, \\ 1 & \text{if } b = 2 \le x \end{cases}$$

we get 
$$P(-0.799 < \eta < 1.799) = \frac{1.7999 + 1}{3} - \frac{-0.799 + 1}{3} = 0.866.$$

We note that one can check that the result ends in the same probability independently of the endpoints of the interval [a,b].

E3. Let  $\eta$  be exponentially distributed random variable. Determine the interval symmetric to expectation of  $\eta$  in which the values of  $\eta$  are situated with probability 0.99. Let the radius of the interval  $kD(\eta)$ .  $E(\eta) = \frac{1}{\lambda} = D(\eta)$ , the interval looks  $\left(\frac{1}{2}-k\cdot\frac{1}{2},\frac{1}{2}+k\cdot\frac{1}{2}\right)$  $P(\eta \in \left(\frac{1}{\lambda} - k \cdot \frac{1}{\lambda}, \frac{1}{\lambda} + k \cdot \frac{1}{\lambda}\right)) = P\left(\frac{1}{\lambda} - k \cdot \frac{1}{\lambda} < \eta < \frac{1}{\lambda} + k \cdot \frac{1}{\lambda}\right) = F(\frac{1}{\lambda} + k \cdot \frac{1}{\lambda}) - F(\frac{1}{\lambda} - k \cdot \frac{1}{\lambda}).$ Recalling that  $F(x) = \begin{cases} 0 & \text{if } x \le 0\\ 1 - e^{-\lambda x} & \text{if } 0 < x \end{cases}$ ,  $F(\frac{1}{\lambda} + k \cdot \frac{1}{\lambda}) = 1 - e^{-\lambda(\frac{1}{\lambda} + k \cdot \frac{1}{\lambda})} = 1 - e^{-(1 + \frac{1}{k})}$ . The value of  $F(\frac{1}{\lambda} - k \cdot \frac{1}{\lambda})$  depends on the sign of its argument. One can notice that  $\frac{1}{2} - k \cdot \frac{1}{2} < 0$ , if 1 < k and  $0 < \frac{1}{2} - k \cdot \frac{1}{2}$  if k < 1. If k = 1, then  $P(\eta \in (\frac{1}{2} - 1 \cdot \frac{1}{2}, \frac{1}{2} + 1 \cdot \frac{1}{2})) = P(0 < \eta < \frac{2}{2}) = F(\frac{2}{2}) - 0 = 1 - e^{-2} = 0.865 < 0.99$ . This implies 1 < k. Therefore,  $F(\frac{1}{2} - k \cdot \frac{1}{2}) = 0$ . Consequently,  $P(\eta \in \left(\frac{1}{\lambda} - k \cdot \frac{1}{\lambda}, \frac{1}{\lambda} + k \cdot \frac{1}{\lambda}\right)) = 1 - e^{-(1+k)} = 0.99, \quad e^{-(1+k)} = 0.01, \quad 1+k = -\ln 0.01 = 4.605,$ k = 3.605. As a control,  $P(\frac{1}{\lambda} - 3.605\frac{1}{\lambda} < \eta < \frac{1}{\lambda} + 3.605\frac{1}{\lambda}) = 1 - e^{-4.605} - 0 = 0.01$ , which was the requirement.

We note that the value of k is independent of the value of the parameter  $\lambda$ .

E4. We do not know the distribution of a random variable  $\eta$ , but we know its expectation and dispersion. If  $E(\eta) = 200$  and  $D(\eta) = 10$ . Give an interval in which the values of  $\eta$  are situated with probability at least 0.95!

According to the Chebisev's inequality  $P(E(\eta) - k(D(\eta) < \eta < E(\eta) + k(D(\eta)) \ge 1 - \frac{1}{k^2})$ . If  $1 - \frac{1}{k^2} = 0.95$ , then k = 4.472, and the looks interval  $(200-10\cdot 4.472, 200+10\cdot 4.472) = (155.28, 244.72).$ 

E5. Let  $\eta$  be binomially distributed random variable with expectation 200 and dispersion 10. Compute the probability that values of  $\eta$  are situated in the neighbourhood of its expectation with radius  $4.472D(\eta)$ .

As  $\eta$  is binomially distributed with parameters n and p,  $E(\eta) = n \cdot p = 200$ ,  $D(\eta) = \sqrt{np(1-p)} = 10$ , consequently  $1 - p = \frac{200}{100} = 0.5$ , which implies p = 0.5 and n = 400. The question is  $P(200 - 4.472 \cdot 10 < \eta < 200 + 4.472 \cdot 10)$   $= P(155.28 < \eta < 244.72) = P(\eta = 156) + P(\eta = 157) + ... + P(\eta = 244)$ . As  $\eta$  is binomially distributed random variable,  $P(\eta = k) = {n \choose k} p^k \cdot (1-p)^{n-k} = {400 \choose k} 0.5^k \cdot 0.5^{400-k}$ .  $P(155.28 < \eta < 244.72) = {400 \choose 156} 0.5^{156} \cdot 0.5^{400-156} + {400 \choose 157} 0.5^{157} \cdot 0.5^{400-157} + ... + {400 \choose 244} 0.5^{244} \cdot 0.5^{400-244}$ = 0.999999.

E6. Let  $\eta$  be a random variable with expectation 200 and dispersion 10. Give the probability that values of  $\eta$  are situated in the interval (175,225). As we do not know the distribution of  $\eta$ , we can not give exactly the required probability, but we can give an estimation for it. The interval (175,225) is symmetric to the expectation 200, it can be written as  $(200-2.5\cdot10,200+2.5\cdot10) = (E(\eta) - k \cdot D(\eta), E(\eta) + k \cdot D(\eta))$ with k = 2.5.  $P(|\eta - E(\eta)| < kD(\eta)) \ge 1 - \frac{1}{k^2}$  implies  $P(175 < \eta < 225) \ge 1 - \frac{1}{2.5^2} = 0.84$ .

E7. Let  $\eta$  be binomially distributed random variable with expectation 200 and dispersion 10. Compute the probability that the values of  $\eta$  are situated in the interval (175, 225).

$$P(175 < \eta < 225) = P(\eta = 176) + P(\eta = 177) + \dots + P(\eta = 224) = \begin{pmatrix} 400\\176 \end{pmatrix} 0.5^{176} 0.5^{224} + \begin{pmatrix} 400\\177 \end{pmatrix} 0.5^{177} 0.5^{223} + \dots + \begin{pmatrix} 400\\224 \end{pmatrix} 0.5^{224} 0.5^{176} = 0.9858, \text{ which is much}$$

more than the estimation 0.84 given by Chebisev's inequality. We draw the attention that actually we know the distribution of the random variable, and it is extra information to E6.

E8. Let  $\eta$  be normally distributed random variable with expectation 200 and dispersion 10. Compute the probability that the values of  $\eta$  are situated in the interval (175, 225).

Now, 
$$\eta \sim N(200,10)$$
, and  $F(x) = \Phi(\frac{x - 200}{10})$ . Now  $P(175 < \eta < 225) = F(225) - F(175) = \Phi(\frac{225 - 200}{10}) - \Phi(\frac{175 - 200}{10}) = \Phi(2.5) - \Phi(-2.5) = 2 \cdot \Phi(2.5) - 1 = 0.9876$ . We note that

this probability is also much more than the estimation given by Chebisev's inequality due to the extra information of distribution. Furthermore it is close to the probability computed in the previous example. The reason of this latter phenomenon will be given in the next section i.
# h.2. Law of large numbers

In this subsection we provide a form of large numbers which is easy to prove and which is able to give estimations for the probability of large deviations. This statement is the basic of computer simulations. One can state stronger forms of the law of large numbers and one also can give statements under weaker assumptions, as well.

<u>Theorem</u> Let  $\xi_1, \xi_2, ..., \xi_n, ...$  be independent identically distributed random variables with  $E(\xi_i) = m$  and  $D(\xi_i) = \sigma$ . Then, for any  $0 < \epsilon$ ,

$$\mathbf{P}\left(\left|\frac{\sum_{i=1}^{n}\xi_{i}}{n}-\mathbf{m}\right|<\varepsilon\right)\to 1, \text{ if } \mathbf{n}\to\infty,$$

and

$$\mathbf{P}\left(\left|\frac{\sum_{i=1}^{n}\xi_{i}}{n}-m\right| \geq \varepsilon\right) \to 0 \text{ if } n \to \infty.$$

Proof

Let  $\eta_n = \frac{\sum_{i=1}^n \xi_i}{n}$ . Now  $E(\frac{\sum_{i=1}^n \xi_i}{n}) = m$  and  $D\left(\frac{\sum_{i=1}^n \xi_i}{n}\right) = \frac{\sigma}{\sqrt{n}}$ . Apply the Chevisev' inequality

for  $\eta_n$ . This gives us  $P(|\eta_n - m| > \varepsilon) \le \frac{D^2(\eta_n)}{\varepsilon^2}$ , which implies  $P\left(\left|\frac{\sum_{i=1}^n \xi_i}{n} - m\right| > \varepsilon\right) \le \frac{\sigma^2}{n\varepsilon^2}$ .

As  $\varepsilon$  and  $\sigma$  are fixed,  $\frac{\sigma^2}{n\varepsilon^2} \to 0$ , if  $n \to \infty$ , which coincides with the second part of the  $\left( \left| \sum_{i=1}^{n} \xi_i \right|_{i=1}^{\infty} \right)_{i=1}^{-2}$ 

statement. The formula  $P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| \le \varepsilon\right) \ge 1 - \frac{\sigma^{2}}{n\varepsilon^{2}} \rightarrow 1 - 0$  is the first part is the

statement.

**Example** 

E1. Let  $\xi_1, \dots, \xi_{1000}$  are independent uniformly distributed random variable in (|1000 | )

[0,1]. Give an estimation for the probability 
$$P\left|\begin{vmatrix}\sum_{i=1}^{n}\xi_{i}\\1000-0.5\end{vmatrix}>0.05\end{vmatrix}$$
.  
Apply the above inequality  $P\left|\begin{vmatrix}\sum_{i=1}^{n}\xi_{i}\\\frac{1}{n}-m\end{vmatrix}\geq\epsilon\right|\leq\frac{\sigma^{2}}{n\epsilon^{2}}$ .  
Now  $E(\xi_{i})=0.5=m$ ,  $D(\xi_{i})=\frac{1}{\sqrt{12}}=0.2887=\sigma$ . Substitute  $\epsilon=0.05$ ,  
 $\sigma^{2}=1$ ,  $\sigma=0.023$ .

$$\frac{\sigma^2}{n\epsilon^2} = \frac{1}{12 \cdot 1000 \cdot 0.05^2} = 0.033.$$

Consequently, 
$$P\left(\left|\frac{\sum_{i=1}^{1000} \xi_i}{1000} - 0.5\right| \ge 0.05\right) \le 0.033$$
.

At most how much is the difference between the average and 0.5 with probability 0.95?

The question is the value of  $\varepsilon$ , for which  $P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < \varepsilon\right) = 0.95$ . As we do not know the

exact distribution of  $\frac{\sum_{i=1}^{n} \xi_i}{n}$ , we can not compute the exact probability, but we are able to

estimate the probability. 
$$P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < \varepsilon\right) \ge 1 - \frac{\sigma^{2}}{n\varepsilon^{2}}, \quad \text{if } 1 - \frac{\sigma^{2}}{n\varepsilon^{2}} = 0.95, \text{ then}$$

$$P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < \varepsilon\right) \ge 0.95 \text{ holds. } 1 - \frac{\sigma^{2}}{n\varepsilon^{2}} = 0.95 \text{ implies } \frac{1}{12 \cdot 1000 \cdot 0.05} = \varepsilon^{2}, \text{ consequently}$$

$$\varepsilon^2 = 1.6667 \times 10^{-3}$$
,  $\varepsilon = 0.041$ .

How many random variables have to be averaged in order to assure that the difference between the average and 0.5 should be at most 0.01 with probability 0.98?

The question is the value of n for which  $P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < 0.01\right) = 0.98$ . Applying the formula

$$P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < \varepsilon\right) \ge 1 - \frac{\sigma^{2}}{n\varepsilon^{2}} \quad \text{again, substitute} \quad 1 - \frac{\sigma^{2}}{n\varepsilon^{2}} = 0.98 \quad \text{and} \quad \varepsilon = 0.01.$$

$$\frac{\sigma^2}{\epsilon^2 \cdot 0.01} = \frac{1}{12 \cdot 0.01^2 \cdot 0.02} = n, \ n = 41667.$$

How many random variables have to be average in order to assure that the difference between the average and 0.5 be at most 0.005 with probability 0.98?

If  $\epsilon = 0.005$ , then , n=1.6667×10<sup>5</sup>, which is four times larger than the previous number of experiments. If we want to decrease the accuracy into the half, we need  $2^2$  times more experiments.

<u>Remark</u>

• If we fix the accuracy  $\varepsilon$ , and the value of n , then  $P\left(\left|\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m\right| < \varepsilon\right) \ge 1 - \frac{\sigma^{2}}{n\varepsilon^{2}}$ 

gives us an estimation for the probability that maximal difference between the average and the expectation exceeds the accuracy.

• If we fix the probability  $1 - \alpha$  (reliability) and the value of n, then  $1 - \frac{\sigma^2}{n\epsilon^2} \ge 1 - \alpha$ 

implies  $\varepsilon \leq \sqrt{\frac{\sigma^2}{n \cdot \alpha}}$ . Consequently, the accuracy is proportional to the square root of the reciprocal of the number of experiments.

• If we fix probability  $1 - \alpha$  (reliability) and the accuracy  $\varepsilon$ , then  $1 - \frac{\sigma^2}{n\varepsilon^2} \le 1 - \alpha$ 

implies  $\frac{\sigma^2}{\epsilon^2 \alpha} \le n$ . This means that the number of experiments is proportional to the square of the accuracy.

• As an illustration of the law of large numbers, we present the next Table h.1. The random variables were uniformly distributed in [0,1], the reliability level was fixed as  $1-\alpha = 0.95$  and  $1-\alpha = 0.99$ . The table shows that the difference between the average and the expectation is getting smaller and smaller as the number of simulations was increased.

The total requested time was less than 1 minute. The theoretical accuracy  $\varepsilon = \sqrt{\frac{\sigma^2}{n \cdot 0.05}}$  and

 $\varepsilon = \sqrt{\frac{\sigma^2}{n \cdot 0.01}}$  were computed for the reliability levels 0.95 and 0.99, respectively.

n	$\frac{\displaystyle\sum_{i=1}^{n}\xi_{i}}{n}$	$\left \frac{\displaystyle\sum_{i=1}^{n}\xi_{i}}{n}-0.5\right $	$\sqrt{\frac{\sigma^2}{n \cdot 0.05}}$	$\sqrt{\frac{\sigma^2}{n \cdot 0.01}}$
10	0.432756065694353	0.067243934305647	0.11785	0.2635
100	0.530898496906201	0.030898496906201	0.03 7268	0.0833
1000	0.506786612848606	0.006786612848606	0.011785	0.02635
10000	0.496156685345852	0.003843314654148	0.003 7268	0.00833
100000	0.500349684591498	0.000349684591498	0.0011785	0.002635
1000000	0.500158856526807	0.000158856526807	0.0003 7268	0.000833
10000000	0.499726933610529	0.000273066389471	0.00011785	0.0002635
100000000	0.499951340487525	0.000048659512475	0.000037268	0.0000833
1000000000	0.499985939301628	0.000014060698372	0.000011785	0.00002635

Table h.1. The averages and their differences from the expectation in case of uniformly distributed random numbers

Secondly, the random variables were exponentially distributed with expectation 0.1 and 10. Table h.2. shows that the difference between the average and the expectation depends on the value of the parameter. The parameter is the reciprocal of the dispersion, consequently, the larger the dispersion, the larger the difference.

	$\lambda = 0.1$	$\lambda = 0.1$	$\lambda = 10$	$\lambda = 10$
N	$\frac{\sum_{i=1}^{n}\xi_{i}}{n}$	$\boxed{\frac{\displaystyle \left  \frac{\displaystyle \sum_{i=1}^{n} \xi_{i} \right }{n} - 10}$	$\frac{\sum_{i=1}^{n}\xi_{i}}{n}$	$\boxed{\frac{\displaystyle{\sum_{i=1}^{n}\xi_{i}}}{n}-0.1}$
10	6.2277618964331	3.7722381035668	0.09447373893621	0.055276
100	11.756814668520	1.7568146685202	0.10392000570707	0.00392
1000	9.5670585169631	0.4329414830368	0.09696619091756	0.00304
10000	9.9932193771582	0.0067806228417	0.100150679660307	0.00015
100000	9.9708942677258	0.0291057322741	0.100629035751288	0.00063
1000000	9.9943200370807	0.0056799629192	0.100039656754390	0.00004
10000000	10.003113268035	0.0031132680354	0.099950954820648	0.00004
100000000	9.9994289522126	0.00057104778736	0.100000507690485	0.00000005
100000000	10.000097147933	0.00009714793369	0.100000729791939	0.00000007

 Table h.2. The averages and their differences from the expectation in case of exponentially distributed random numbers

• The law of large numbers is expressed by the sentence that the expectation is **about** the average of many values of random variable. Not exactly the same, but it is not far from it.

• As the expectation is an integral, the law of large numbers provides possibility to compute integrals numerically as follows: Let  $g: H \rightarrow R$ ,  $H \subset R$ ,  $[a,b] \subset H$ , suppose that g is continuous in [a,b]. Taking into account the properties of expectations,

 $I = \int_{a}^{b} g(x)dx = (b-a)\int_{a}^{b} g(x) \cdot \frac{1}{b-a} dx = (b-a) \cdot E(g(\eta)), \text{ where } \eta \text{ is uniformly distributed}$ random variable in [a, b].  $E(g(\eta))$  is about the average of many values of  $g(\eta)$ .  $\eta$  can be constructed as a linear transformation of a uniformly distributed random variable in [0,1]. Consequently, the algorithm of computing the approximate value of the integral  $\int_{a}^{b} g(x)dx$  is the following: generate a random number, multiply it by b-a and add "a", then substitute this value into the function g. Substitution can be made as the all the values we get are in the domain of g. Repeat the process n times and take the average of the values. Multiply the average by b - a and we get the approximate value of the integral. The necessary number of simulation can be determined as follows:

$$\begin{split} & \mathsf{P}(\left| \int\limits_{a}^{b} g(x)dx - (b-a) \cdot \frac{\sum\limits_{i=1}^{n} g(\eta_{i})}{n} < \varepsilon \right) = \mathsf{P}(\left| \frac{\int\limits_{a}^{b} g(x)dx}{(b-a)} - \frac{\sum\limits_{i=1}^{n} g(\eta_{i})}{n} < \frac{\varepsilon}{b-a} \right) \ge \\ & \ge 1 - (b-a)^{2} \frac{D^{2}(g(\eta_{i}))}{n \cdot \varepsilon^{2}} = 1 - \alpha \,. \\ & \mathsf{As} \ \eta_{i} \ \text{is in [a,b], } D(\eta_{i}) \le \frac{\max g(x) - \min g(x)}{2} \,. \\ & 1 - \alpha = \mathsf{P}(\left| \int\limits_{a}^{b} g(x)dx - (b-a) \cdot \frac{\sum\limits_{i=1}^{n} g(\eta_{i})}{n} < \varepsilon \right) \ge 1 - (b-a)^{2} \frac{\left(\max g(x) - \min g(x)\right)^{2}}{4 \cdot n \cdot \varepsilon^{2}}, \quad \text{which} \\ & \inf(b-a)^{2} \cdot \frac{\left(\max g(x) - \min g(x)\right)^{2}}{4\alpha \cdot \varepsilon^{2}} \le n \,. \end{split}$$

Example

E2. Compute 
$$\int_{0}^{1} \frac{1}{1+x} dx$$
 by random simulation.

Notice that  $\int_{0}^{1} \frac{1}{1+x} dx = E(\frac{1}{1+\xi})$  where  $\xi$  is uniformly distributed random variable in [0,1].

Consequently, generate random numbers by the computer, add 1, and take the reciprocal. This process has to be repeated many times. Take the average of the numbers you got, and this average is approximate value of the integral. As  $\xi \in ([0,1], \frac{1}{\xi+1} \in [0.5,1], D^2(\frac{1}{1+\xi}) \le \frac{0.5^2}{4} = 0.0625$ . If we fix the reliability level  $1 - \alpha = 0.99$ , the necessary number of simulation is  $\frac{0.0625}{\epsilon^2 \cdot 0.01} \le n$ . If we would like to compute the integral with difference less than 0.01, then we have to make  $0.0625 \cdot 10^6 = 62500 \le n$  simulations. As  $\int_{0}^{1} \frac{1}{1+x} dx = [\ln(1+x)]_{x=0}^{x=1} = \ln 2 - \ln 1 = \ln 2$ , we can follow the difference between the exact

value and the approximate value of the integral in Table h.3.

c is computed as 1	$\left(\frac{\max_{a \le x \le b} g(x) - \min_{a \le x \le b} g(x)}{2}\right)^2$	
e is computed as	$n \cdot \alpha$	$-\sqrt{0.01 \cdot n}$ $-c$ .

Ν	average	Difference	3
62	0.702627791231423	0.009480610671478	0.3175
625	0.694214696993436	0.001067516433491	0.1
6250	0.695502819777260	0.002355639217315	0.03175
62500	0.693417064411419	0.000269883851474	0.01
625000	0.693095119363388	0.000052061196558	0.003175
6250000	0.693134534818101	0.000012645741844	0.001
62500000	0.693167969772721	0.000020789212776	0.0003175
625000000	0.693142704368027	0.000004476191918	0.0001

Table h.3. The averages and their differences from the expectation in case of transformed random variables

For all simulations, elapsed time was 42.9 seconds.

E3. Compute the value of the integral  $\int_{1}^{3} \sin \frac{1}{x} dx$  with accuracy 0.01.

Note, that 
$$\int_{1}^{3} \sin \frac{1}{x} dx = 2 \cdot \int_{1}^{3} \sin \frac{1}{x} \cdot \frac{1}{2} dx = 2 \cdot E(\eta)$$
, where  $\eta = \sin(\frac{1}{\xi})$  and  $\xi$  is uniformly

distributed random variable in [1,3].  $-1 \le \sin \frac{1}{x} \le 1$ ,  $D^2(\sin \frac{1}{\eta}) \le \frac{(1-(-1))^2}{4} = 1$ ,

$$P(\left|2 \cdot \frac{\sum_{i=1}^{n} \frac{1}{1+\eta_{i}}}{n} - \int_{1}^{3} \sin \frac{1}{x} dx\right| \le \varepsilon) \ge 1 - 4 \cdot \frac{1}{n\varepsilon^{2}} \cdot 1 - 4 \cdot \frac{1}{n\varepsilon^{2}} = 0.99 \text{ and } \varepsilon = 0.01 \text{ implies}$$

n = 4000000.We can follow the average and the theoretical accuracy in the function of numbers of simulation in Table g.4. Elapsed time, together for all simulations, was 36.82 seconds.

n	average	ε
40	4.044413814196310	3.162
400	3.124480498240279	1
4000	3.266154820794264	0.3162
40000	3.241221397791890	0.1
400000	3.252187207202902	0.03162
4000000	3.251025444611742	0.01
4000000	3.251126290354754	0.003162
40000000	3.250561315440294	0.001

Table g.4. Averages of random variables given by  $\eta = \sin(\frac{1}{\xi})$  and the theoretical accuracy

We note that better estimations for the variance can be also given, we used  $-1 \le \sin y \le 1$  for the sake of simplicity.

E4. Compute 
$$\int_{-100}^{100} e^{\frac{-x^2}{2}} dx$$
 by random simulation.

Note that  $\int_{-100}^{100} e^{\frac{-x^2}{2}} dx = 200 \cdot E(e^{\frac{-\xi^2}{2}})$  where  $\xi$  is uniformly distributed random variable in

$$\begin{bmatrix} -100, 100 \end{bmatrix} \cdot \text{As } 0 \le e^{\frac{-\eta^2}{2}} \le 1 \quad D^2(e^{\frac{-\xi^2}{2}}) \le \frac{1}{4},$$

$$P(\left| 200 \cdot \frac{\sum_{i=1}^{n} e^{\frac{-\eta^2_i}{2}}}{n} - \int_{-100}^{100} e^{\frac{-x^2}{2}} dx \right| < \epsilon) \ge 1 - 200^2 \frac{1}{4n \cdot \epsilon^2}. \quad 1 - 10000 \frac{1}{4n \cdot \epsilon^2} \ge 0.99 \quad \text{implies}$$

 $n \ge 2500000$ C. As from standard normal probability density function we know that

$$\int_{-100} e^{-2} dx \approx \int_{-\infty} e^{-2} dx \sqrt{2\pi}$$
, comparing the average to  $\sqrt{2\pi}$  we get Table h.5.:

n	average	Difference	3
25	8.323342326487701	5.816714051856701	10
250	3.015562934762770	0.508934660131769	3.16227
2500	2.264787314861209	0.241840959769791	1
25000	2.441972159407621	0.064656115223379	0.316227
250000	2.451752388622218	0.054875886008782	0.1
2500000	2.511696184700974	0.005067910069974	0.0316227
25000000	2.508097777785709	0.001469503154709	0.01
250000000	2.504753761626246	0.001874513004754	0.00316227

Table h.5. Averages of the transformed random variable and their differences

from  $\sqrt{2\pi}$  in case of different numbers of simulations

We can see that actual difference is always smaller than the theoretical accuracy.

# h.3. Bernoulli's theorem

In this subsection we apply the law of large numbers to characteristically distributed random variables and we get a statement for relative frequencies. This statement tells us that the relative frequency of an event A are close to the probability of A.

<u>Theorem</u> (Bernoulli's theorem) Let A be an event, and  $k_A(n)$  is the frequency of the event performing n independent experiments. Then, for any  $0 < \varepsilon$ ,  $P(\left|\frac{k_A(n)}{n} - P(A)\right| \ge \varepsilon) \rightarrow 0$  if

 $n \to \infty$  and  $P(\left|\frac{k_A(n)}{n} - P(A)\right| < \varepsilon) \to 1$  supposing  $n \to \infty$ .

<u>Proof</u> Recall that  $k_A(n)$  is binomially distributed random variable with parameters n and p = P(A), and  $k_A(n)$  can be written as a sum of n independent characteristically distributed random variables  $\mathbf{1}_A^i$  with parameter p.  $E(\mathbf{1}_A^i) = p = P(A)$ ,  $D^2(\mathbf{1}_A^i) = \sqrt{p(1-p)}$ , consequently,  $P(\left|\frac{k_A(n)}{n} - P(A)\right| < \varepsilon) \ge 1 - \frac{p(1-p)}{n\varepsilon^2} \to 1 - 0$  supposing  $n \to \infty$  and  $P(\left|\frac{k_A(n)}{n} - P(A)\right| \ge \varepsilon) \le \frac{p(1-p)}{n\varepsilon^2} \to 0$  supposing  $n \to \infty$ .

**Remarks** 

• The above statement tells us that large deviation between the relative frequency and the probability occurs with small probability, small deviation is with large probability.

• Roughly spoken, the relative frequency is about the probability, if the number of simulations is large. This is the theoretical background of computer simulations and pools.

• 
$$0 \le p(1-p) \le \frac{1}{4}$$
, consequently  $P(\left|\frac{k_A(n)}{n} - P(A)\right| < \varepsilon) \ge 1 - \frac{1}{4n\varepsilon^2}$ . This inequality

provides possibility to estimate the necessary number of simulations.

• If we fix the number of simulation and the accuracy ( $\epsilon$ ), we can estimate the probability that the difference between the relative frequency and the probability exceeds accuracy  $\epsilon$ .

• If we fix the number of simulations and the reliability  $(1-\alpha)$ , we can compute the accuracy  $\varepsilon$  by  $1 - \frac{1}{4n\varepsilon^2} \ge 1 - \alpha$ ,  $\varepsilon \le \frac{1}{\sqrt{4n\alpha}}$ .

• If we fix the reliability  $(1-\alpha)$  and the accuracy  $\varepsilon$ , we can determine the necessary number of simulations by  $\frac{1}{4\alpha\varepsilon^2} \le n$ .

Examples

E1. To illustrate the above statement we present the following simulation example: flip 4 times a fair coin and determine the probability that there are heads and tails among the results.

Of course our computer can not flip a coin but it can generate a random number uniformly distributed on [0,1]. Imagine that if the result (random number) is less than 0.5, then we get head, in the opposite case we get tail. Repeat it four times and decide whether the results of flips are the same in all cases or there are at least one heads and at least one tails. Repeat the composite experiment n times and compute how many times you get both head and tail. The relative frequency is about the probability. If we would like to approximate the probability of the event "you get both head and tail " with accuracy  $\varepsilon = 0.01$  with probability 0.99, we

need  $\frac{1}{4\alpha\epsilon^2} = \frac{1}{4 \cdot 0.01 \cdot 0.01^2} = 250000 \le n$  experiments. The relative frequencies arising

from simulations and their differences from the exact probability  $\frac{14}{16}$  can be seen in Table h.6. One can notice that the real difference is much smaller than the accuracy showing that the estimation is not sharp. We can see better estimation in the next chapter.

n	Relative frequency	Difference	3
25	0.960000000000000	0.085000000000000	1
250	0.89200000000000	0.017000000000000	0.3162
2500	0.874800000000000	0.000200000000000	0.1
25000	0.87384000000000	0.00116000000000	0.03162
250000	0.87500000000000	0	0.01
2500000	0.87504160000000	0.00004160000000	0.003162
2500000	0.875081200000000	0.00008120000000	0.001
25000000	0.874980140000000	0.000019860000000	0.003162

Table h.6. Relative frequencies and their differences from the exact probability

The computer program is very simple and the elapsed time is small. The program for simulation was written in MatLab and it can be seen as follows:

```
function szim16
format long
tic
er=zeros(8,1)
for j=1:1:8
 jo=0;
for i=1:1:(2.5*10^j);
head=0;
for k=1:1:4
    vel=rand(1);
    if vel<0.5
        head=head+1;
    end
end
    if 0<head & head<4
        jo=jo+1;
    end
end
szim=jo/(2.5*10^j);
er(j,1)=szim;
end
toc
er
kul=abs(er-14/16)
```

The relative frequencies and their differences from the exact probability are plotted in Fig.h.1. and Fig.h.2. with  $n = 2.5 \cdot 10^k$ .



Figure h.1. Relative frequencies in the function of number of simulations on logarithm scale



Figure h.2. Differences of the relative frequencies and the probability in the function of number of simulations on logarithm scale

Of course, it is easy to find such events the probability of that is complicated to compute but computer program for simulation is easy to elaborate. In those cases the approximation of the probability by relative frequency is a useful tool for people who are able to apply informatics.

# i. Central limit theorem

# The aim of this chapter

In this chapter we present asymptotical theorems in connection with the distribution of the sum and the average of many independent identically distributed random variables. We will approximate the cumulative distribution functions and probability density functions by the help of those of normal distributions.

# Preliminary knowledge

Convergence of functions. Cumulative distribution function, normal distribution, properties of expectation, dispersion.

# Content

i.1. Central limit theorem for the sum of independent identically distributed random variables.

i.2. Moivre-Laplace formula.

i.3. Central limit theorem for the average of independent identically distributed random variables.

i.4. Central limit theorem for relative frequency.

# i.1. Central limit theorem for the sum of independent identically distributed random variables

In the previous section we have dealt with the difference of the average of many independent identically distributed random variables and their expectation. We have proved that the difference is small with large probability, if the number of random variables is large. In this chapter we deal with the distribution of the sum and the average of many independent random variables. We state that they are approximately normally distributed. We use this theorem for computations, as well.

<u>Theorem</u> (Central limit theorem) Let  $\xi_1, \xi_2, ..., \xi_n, ...$  be independent identically distributed random variables with expectation  $E(\xi_i) = m$  and dispersion  $D(\xi_i) = \sigma$ , i = 1, 2, ... Then,

$$\lim_{n \to \infty} P(\frac{\sum\limits_{i=1}^n \xi_i - nm}{\sigma \sqrt{n}} < x) = \Phi(x) \ \text{ for any } \ x \in R \, .$$

The proof of the theorem requires additional tools in probability theory and analysis, consequently we omit it.

<u>Remarks</u>

•  $P(\frac{\sum_{i=1}^{n} \xi_i - nm}{\sigma \sqrt{n}} < x)$  is the value of the cumulative distribution function of the

random variable  $\frac{\sum_{i=1}^{n} \xi_i - nm}{\sqrt{n}}$  at the point x.

• 
$$E\left(\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\sigma\sqrt{n}}\right) = \frac{1}{\sigma\sqrt{n}}E\left(\sum_{i=1}^{n}\xi_{i}-nm\right) = \frac{1}{\sigma\sqrt{n}}(E\left(\sum_{i=1}^{n}\xi_{i}\right)-nm) = \frac{1}{\sigma\sqrt{n}}(nm-nm) = 0.$$
$$D\left(\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\sigma\sqrt{n}}\right) = \frac{1}{\sigma\sqrt{n}}D\left(\sum_{i=1}^{n}\xi_{i}-nm\right) = \frac{1}{\sigma\sqrt{n}}D\left(\sum_{i=1}^{n}\xi_{i}\right) = \frac{\sigma\sqrt{n}}{\sigma\sqrt{n}} = 1.$$
  
• The random variable  $\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\sigma\sqrt{n}}$  is usually called as standardized sum.

Central limit theorem states that the limit of the cumulative distribution function of

the random variables  $\frac{\sum_{i=1}^{n} \xi_i - nm}{\sigma \sqrt{n}}$  equals the cumulative distribution function of standard normally distributed random variables. Consequently, for large values of n, the cumulative

distribution function of the standardized sum is approximately the function  $\Phi$ . It can be written in the form  $F_n$  (x)  $\approx \Phi(x)$ .

$$\frac{\sum_{i=1}^{n} \xi_i - nm}{\sigma \sqrt{n}}$$

• Distribution of  $\xi_i$  can be arbitrary. In practice, the approximation is good for  $100 \le n$ , in many times for  $30 \le n$ .

• The relative frequencies of the standardized sums can be seen in the following Figs.i.1, i.2. and i.3., if we sum up n=1, n=2,n=5, n=10, n=30, n=100 independent random variables. The random variables were uniformly distributed in [0,1].Red line is the probability density function of standard normal distribution. One can see that the shape of histogram follows more and more the shape of the Gauss curve.



Figure i.1. The relative frequencies of the values of the standardized sums if we sum up n=1 and n=2 random variables



Figure i.2. The relative frequencies of the values of the standardized sums if we sum up n=5 and n=10 random variables



Figure i.3. The relative frequencies of the values of the standardized sums if we sum up n=30 and n=100 random variables

• Distribution of  $\xi_i$  can be arbitrary. In Figs. i.4., i.5. and i.6. the relative frequencies of standardized sum of n exponentially distributed random variables with expectation  $E(\xi_i) = 1 = \frac{1}{\lambda}$  (n = 1,2,5,10,30,100) are presented. One can realize that the shape of Gauss curve appears for larger values of n than previously, due to the asymmetry of the exponential probability density function.



Figure i.4. The relative frequencies of the values of the standardized sums of exponentially distributed random variables, if we sum up n=1 and n=2 random variables



Figure i.5. The relative frequencies of the values of the standardized sums of exponentially distributed random variables, if we sum up n=5 and n=10 random variables



Figure i.6. The relative frequencies of the values of the standardized sums of exponentially distributed random variables, if we sum up n=30 and n=100 random variables

• Finally we illustrate the central limit theorem for the case when  $\theta_i \sim N(0,1)$ , and  $\xi_i = \theta_i^2$ , that is  $\sum_{i=1}^n \xi_i \sim \chi_n^2$ . Standardized sums are approximately normally distributed random variables. We note that many program languages have random number generator which provides normally distributed random variables, as well.



Figure i.7. The relative frequencies of the values of chi-squared distributed random variables with degree of freedom n=1 and n=2



Figure i.8. The relative frequencies of the values of chi-squared distributed random variables with degree of freedom n=5 and n=10



Figure i.9. The relative frequencies of the values chi-squared distributed random variables with degree of freedom n=30 and n=100

After illustrations we consider what can be stated about the distribution function of the sums, without standardization.

#### <u>Remark</u>

• The cumulative distribution function of the sum  $\sum_{i=1}^{n} \xi_i$  is about normal distribution

function with expectation  $n \cdot m$  and dispersion  $\sigma \sqrt{n}$ , that is  $F_{\substack{\sum \xi_i \\ i=1}}^n(x) \approx \Phi(\frac{x-nm}{\sigma \sqrt{n}})$ . This

can be supported as follows:  $F_{n}_{\sum_{i=1}^{n}\xi_{i}}(y) = P(\sum_{i=1}^{n}\xi_{i} < y) = P(\frac{\sum_{i=1}^{n}\xi_{i} - nm}{\sigma\sqrt{n}} < \frac{y - nm}{\sigma\sqrt{n}}) \approx \Phi(\frac{y - nm}{\sigma\sqrt{n}}),$ which coincides with the cumulative distribution function of  $\eta \sim N(nm, \sigma\sqrt{n})$ . We

which coincides with the cumulative distribution function of  $\eta \sim N(nm, \sigma\sqrt{n})$ . We emphasize that  $E(\sum_{i=1}^{n} \xi_i) = nm$  and  $D(\sum_{i=1}^{n} \xi_i) = \sigma\sqrt{n}$ .

# **Examples**

E1. Flip a fair coin. If the result is head, then you gain 10 HUF, if the result is tail, you pay 8 HUF. Applying central limit theorem, compute the probability, that after 100 games you are in loss. Determine the same probability by computer simulation.

Let  $\xi_i$  the gain during the ith game.  $\xi_i \sim \begin{pmatrix} -8 & 10 \\ 0.5 & 0.5 \end{pmatrix}$ , i=1,2,...,100.  $\xi_i$  are independent, identically distributed random variables. Moreover,  $E(\xi_i) = -8 \cdot \frac{1}{2} + 10 \cdot \frac{1}{2} = 1$ ,  $D(\xi_i) = \sqrt{(-8)^2 \cdot \frac{1}{2} + 10^2 \cdot \frac{1}{2} - 1^2} = 9$ . The question is the probability  $P(\sum_{i=1}^{100} \xi_i < 0)$ . Recall that  $P(\sum_{i=1}^{100} \xi_i < 0) = F_{100}_{\sum_{i=1}^{5} \xi_i}(0)$ . According to the central limit theorem,  $F_{100}_{\sum_{i=1}^{5} \xi_i}(x) \approx \Phi(\frac{x - 100 \cdot 1}{9 \cdot \sqrt{100}})$ , consequently,  $F_{100}_{\frac{5}{2}\xi_i}(0) \approx \Phi(\frac{0 - 100 \cdot 1}{9 \cdot \sqrt{100}}) = \Phi(-1.111) = 1 - \Phi(1.111) = 0.1336$ .

In order to approximate the probability by relative frequency with accuracy 0.001, according to the previous section, we need 25000000 simulations. After making the required number of simulations, we get  $\frac{k_A(n)}{n} = 0.13568732$  which is quite close to the approximate value

got by the central limit theorem.

E2. Supposing previous games, how many games have to be playd in order not to be in negative with probability 0.99?

Our question is the value of n for which  $P(\sum_{i=1}^{n} \xi_i \ge 0) = 0.99$ . This question can be expressed by the cumulative distribution function of the sum as follows: n=?

$$1 - F_{n}_{\sum_{i=1}^{n} \xi_{i}}(0) = 0.99. \quad \text{As} \quad F_{n}_{\sum_{i=1}^{n} \xi_{i}}(x) \approx \Phi(\frac{x - n \cdot 1}{9 \cdot \sqrt{n}}), \text{ we have to solve the equation}$$

$$\Phi(\frac{0-n}{9\cdot\sqrt{n}})=0.01$$
. This was detailed in the subsection of normally distributed random

variables in subsection g.3.  $\Phi(y) = 0.01$  implies y = -2.3263, therefore  $\frac{0 - n \cdot 1}{0 \sqrt{n}} = -2.3263$ ,

n = 438.35, that is n = 439. As a control, performing the simulation 25000000 times, the relative frequency was 0.98914.

E3. The accounts in the shops are rounded to 0 or 5. If the finial digit of the account equals 0, 1, 2, 8, or 9 than the money to pay ends in 0. If the finial digit of the account equals 3, 4, 5, 6, or 7, then the money to pay ends in 5. Suppose that all final digits are equally probable and they are independent during different payments. Applying the central limit theorem, determine the probability that the loss of the shop due to 300 payments is at least -30 and less than 30!

Let the  $\xi_i$  i=1,2,3,...,300 be the loss of the shop during the ith payment.  $\xi_i \sim \begin{pmatrix} -2 & -1 & 0 & 1 & 2 \\ 0.2 & 0.2 & 0.2 & 0.2 & 0.2 \end{pmatrix}$ , which are independent identically distributed random

variables. The total loss during 300 payments equals  $\sum_{i=1}^{300}\xi_i$  . The question is

 $P(-30 \le \sum_{i=1}^{300} \xi_i < 30)$  which can be expressed by the cumulative distribution function of

 $\sum_{i=1}^{100} \xi_i \text{ as follows: } P(-30 \le \sum_{i=1}^{300} \xi_i < 30) = F_{300} \underset{\sum_{i=1}^{5} \xi_i}{\sum_{i=1}^{5} \xi_i} (30) - F_{300} \underset{\sum_{i=1}^{5} \xi_i}{\sum_{i=1}^{5} \xi_i} (-30). \text{ According to the central}$ 

limit theorem,  $F_{300}_{\sum_{i}^{\xi_i}}(x) \approx \Phi(\frac{x - 300 \cdot m}{\sigma\sqrt{300}})$ , where  $m\!=\!E(\xi_i^{})\!=\!-\!2\!\cdot\!0.2\!-\!0.1\!\cdot\!0.2\!+\!0\!\cdot\!0.2\!+\!1\!\cdot\!0.2\!+\!2\!\cdot\!0.2\!=\!0$  and  $\sigma = D(\xi_i) = \sqrt{(-2)^2 \cdot 0.2 + (-1)^2 \cdot 0.2 + 0^2 \cdot 0.2 + 2^2 \cdot 0.2 + 1^2 \cdot 0.2 - 0^2} = \sqrt{2}.$ Consequently,  $F_{300}_{\sum_{i}^{j}}(30) \approx \Phi(\frac{30-0}{\sqrt{2}\sqrt{300}}) = 0.88966$ ,

$$\begin{split} F_{300} &\sum_{\substack{\Sigma \\ i=1}}^{5} (-30) \approx \Phi(\frac{-30-0}{\sqrt{2}\sqrt{300}}) = 1 - 0.88966 = 0.11034 \text{ and} \\ P(-30 \le \sum_{i=1}^{300} \xi_i < 30) = F_{300} & (30) - F_{300} & (-30) \approx 0.88966 - 0.11034 = 0.77932 \approx 0.8 \,. \end{split}$$

Give an interval in which the loss is situated with probability 0.99.

The interval in which a normally distributed random variable with parameters m=0 and  $\sigma = \sqrt{600}$  takes its values with probability 0.99 is (-63.1, 63.1). Therefore the loss is between -63.1 and 63.1 with probability 0.99. Notice that the loss may be -300, it is in a loose interval with large probability. This fact is appropriate for checking based on random phenomenon.

Throw a fair die 1000 times, repeatedly. At least how much is the sum of the results E4. with probability 0.95?

Let the result of the ith throw be denoted by  $\xi_i$ , i=1,2,...,1000. Now  $\xi_i \sim \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \end{pmatrix}$ , which are independent identically distributed random variables with expectation  $E(\xi_i) = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = 3.5 = m$  and

dispersion 
$$D(\xi_i) = \sqrt{1^2 \cdot \frac{1}{6} + 2^2 \cdot \frac{1}{6} + 3^2 \cdot \frac{1}{6} + 4^2 \cdot \frac{1}{6} + 5^2 \cdot \frac{1}{6} + 6^2 \cdot \frac{1}{6} - 3.5^2 = 1.7078 = \sigma.$$

Central limit theorem states that  $F_{\sum_{i=1}^{n} \xi_{i}}(x) \approx \Phi(\frac{x - n \cdot 3.5}{1.7078\sqrt{n}})$ . The question is the value of x

for which  $P(\sum_{i=1}^{1000} \xi_i \ge x) = 0.95$ , that is  $1 - F_{\sum_{i=1}^{n} \xi_i}(x) = 0.95$ . Solving the equation

 $1 - \Phi(\frac{x - 1000 \cdot 3.5}{1.7078 \cdot 1000}) = 0.95$ ,  $\frac{x - 1000 \cdot 3.5}{1.7078 \cdot 1000} = -1.645 \text{ x} = 3411.2$ . Summarizing, the sum of

1000 throws is at least 3412 with probability 0.95. Although we do not know what happens during one experiment, the sum of 1000 experiments can be well predicted.

# i.2. Moivre-Laplace formula

Moivre-Laplace formula is a special form of the central limit theorem, the form applied to the cumulative distribution function of binomially distributed random variable.

<u>Theorem</u> (Moivre-Laplace formula) Let  $k_A(n)$  be the frequency of the event A  $(P(A) = p, 0 during <math>2 \le n$  independent experiments, that is  $k_A(n)$  is binomially distributed random variable with parameters n and p. Then, for any  $x \in R$ ,  $\lim_{n\to\infty} P(\frac{k_A(n) - np}{\sqrt{np(1-p)}} < x) = \Phi(x).$ 

<u>Proof</u> Recall that  $\mathbf{k}_{\mathbf{A}}(n) = \sum_{i=1}^{n} \mathbf{1}_{\mathbf{A}}^{i}$  with

 $\mathbf{1}_{A}^{i} = \begin{cases} 1 & \text{if Aoccurs during theith experiments} \\ 0 & \text{if A does not occur during theith experiments} \end{cases}$ 

 $\mathbf{1}_{A}^{i}$  i = 1,2,... are independent, characteristically distributed random variables with parameter p,  $E(\mathbf{1}_{A}^{i}) = p$ ,  $D(\mathbf{1}_{A}^{i}) = \sqrt{p(1-p)}$ . Apply the central limit theorem and we get the statement to be proved.

Remarks

- $P(\eta < x)$  equals the cumulative distribution function of  $k_A(n)$  at point x.
- $E(k_A(n)) = np$ ,  $D(k_A(n)) = \sqrt{np(1-p)}$ .
- Moivre-Laplace formula states that  $F_{k_A(n)-np} (x) \approx \Phi(x)$ .
- $F_{k_A(n)}(x) \approx \Phi(\frac{x np}{\sqrt{np(1 p)}})$ , which can be proved as follows:

$$F_{k_A(n)}(y) = P(k_A(n) < y) = P(\frac{k_A(n) - np}{\sqrt{np(1-p)}} < \frac{y - np}{\sqrt{np(1-p)}}) \approx \Phi(\frac{y - np}{\sqrt{np(1-p)}})$$

• For any a < b,

$$P(a \le k_A(n) < b) = F_{k_A(n)}(b) - F_{k_A(n)}(a) \approx \Phi(\frac{b - np}{\sqrt{np(1 - p)}}) - \Phi(\frac{a - np}{\sqrt{np(1 - p)}})$$

- The approximation is good if  $100 \le n$  and  $10 \le np$ .
- $P(k_A(n) = k) = P(k \le k_A(n) < k+1) = F_{k_A(n)}(k+1) F_{k_A(n)}(k) \approx$

$$\approx \Phi(\frac{(k+1)-np}{\sqrt{np(1-p)}}) - \Phi(\frac{k-np}{\sqrt{np(1-p)}}).$$

Consequently,  $P(k_A(n) = k) = {n \choose k} p^k (1-p)^{n-k}$  can be approximated by the help of the

cumulative distribution function of a normally distributed random variable. The differences between the exact and the approximate values can be seen in Fig.i.10. The values of parameters are n = 100 and p = 0.1. Largest difference between the exact and the approximate values is less then 0.01.



Figure i.10. The exact and the approximate probabilities and their differences in case of binomial distribution

•  $P(k_A(n) = k) = {n \choose k} p^k (1-p)^{n-k}$  can be also approximated by the help of the

probability density function of normally distributed random variable. From analysis one can recall that if the function G is continuously differentiable in [a,b], then G(b) - G(a) = G'(c)(b-a), for some  $c \in (a,b)$ . Applying this theorem for a = k and b = k + 1 we get  $P(k \le k_A(n) < k + 1) = F_{k_A(n)}(k+1) - F_{k_A(n)}(k) \approx$ 

$$\begin{split} \Phi(\frac{k+1-np}{\sqrt{np(1-p)}}) &- \Phi(\frac{k-np}{\sqrt{np(1-p)}}) = \Phi'(\frac{c-np}{\sqrt{np(1-p)}}) \cdot \frac{1}{\sqrt{np(1-p)}} (k+1-k) \\ As \ \Phi'(x) &= \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}}, \ \frac{1}{\sqrt{2\pi}} e^{\frac{-x^2}{2}}, \\ \Phi'(\frac{c-np}{\sqrt{np(1-p)}}) \cdot \frac{1}{\sqrt{np(1-p)}} &= \frac{1}{\sqrt{2\pi}} e^{\frac{-\left(\frac{c-np}{\sqrt{np(1-p)}}\right)^2}{2}} \cdot \frac{1}{\sqrt{np(1-p)}}, \end{split}$$

**Central limit theorem** 

which coincides with the probability density function of a normally distributed random variable with expectation m = np and dispersion  $\sigma = \frac{1}{\sqrt{np(1-p)}}$  at some point  $c \in (k, k+1)$ .

If we choose the middle of he interval, that is c = k + 0.5 we get  $P(k_A(n) = k) \approx \frac{1}{\sqrt{np(1-p)}} \phi(\frac{k+0.5-np}{\sqrt{np(1-p)}})$ . The exact and the approximate probabilities and their differences are plotted in Fig.i.11. One can see that the largest difference between the

approximate and exact probability is less than 0.01.



Figure i.11. The exact and the approximate probabilities and their differences in case of binomial distribution

Example

E1. In an airport, the number of tickets sold for a fly is 500. Suppose that all of ticket holders are at the checking with probability 0.95 independently of each other. Compute the probability that the number of people coming up at the checking is at least 490. Let  $\eta$  denote the number of people coming up at the checking.  $\eta$  is binomially distributed random variable with parameters n = 500 and p = 0.95. The question is  $P(\eta \ge 490)$ . Now  $P(\eta \ge 490) = P(\eta = 490) + P(\eta = 491) + P(\eta = 492) + P(\eta = 493) + ... + P(\eta = 500) =$ 

$$\binom{500}{490} 0.95^{490} \cdot 0.05^{10} + \binom{500}{491} 0.95^{491} \cdot 0.05^9 + \dots + \binom{500}{500} 0.95^{500} \cdot 0.05^0 = 0.00046.$$

If one applies Moivre-Laplace formula,

$$P(\eta \ge 490) = 1 - F_{\eta}(490) \approx 1 - \Phi(\frac{490 - 500 \cdot 0.95}{\sqrt{500 \cdot 0.95 \cdot 0.05}}) = 1 - 0.99896 = 0.00104.$$
 The difference

between the exact and approximate probabilities is less than 0.001. One can conclude that that the probability of having at least 490 passengers on the fly is very small. More than 500 tickets may be sold, if the number of places is 500 and we would like to have less than 0.01 probability for overfilling.

E2. How many tickets may be sold in order to assure that at least 500 passengers be at the checking?

Let  $\eta_n$  the number of passengers at the checking in case of n sold tickets. The question is the value n for which  $P(\eta_n \le 500) = 0.99$ . We require  $F_{\eta_n}(501) = 0.99$ . Applying central limit theorem,  $F_{\eta_n}(x) \approx \Phi(\frac{x - n \cdot 0.95}{\sqrt{n \cdot 0.95 \cdot 0.05}})$ . Solving equation  $\Phi(\frac{501 - n \cdot 0.95}{\sqrt{n \cdot 0.95 \cdot 0.05}}) = 0.99$  we get  $\frac{501 - n \cdot 0.95}{\sqrt{n \cdot 0.95 \cdot 0.05}} = 2.3263$ , which is a quadratic equation for n. Solving it, we ends in n=515. As a control,

$$P(\eta_{515} \le 500) = \sum_{i=0}^{500} P(\eta_{515} = i) = 1 - \sum_{i=501}^{515} P(\eta_{515} = i) = 1 - \sum_{i=501}^{515} {\binom{515}{i}} 0.95^i \cdot 0.05^{515-i} = 0.9926 > 0.99.$$

E3. How many passengers are at the checking most likely? Compute/approximate the probability belonging to the mode in case of n=515 sold tickets.

Mode of binomially distributed random variable is  $[(n+1) \cdot p] = [516 \cdot 0.95] = [490.2] = 490$ ,

as 
$$(n+1) \cdot p$$
 is not integer.  $P(\eta_{515} = 490) = {\binom{515}{490}} 0.95^{490} \cdot 0.05^{25} = 8.0585 \cdot 10^{-2}$ .

Approximating this value by normal cumulative distribution function, we get  $P(\eta_{515} = 490) = P(490 \le \eta_{515} < 491) = F_{\eta_{515}}(491) - F(490) \approx$ 

$$\approx \Phi(\frac{491 - 515 \cdot 0.95}{\sqrt{515 \cdot 0.95 \cdot 0.05}}) - \Phi(\frac{490 - 515 \cdot 0.95}{\sqrt{515 \cdot 0.95 \cdot 0.05}}) = 0.63826 - 0.56026 = 0.078.$$
 If we apply

approximation by probability density function, we get

 $P(\eta_{515} = 490) \approx \frac{1}{\sqrt{2\pi}\sqrt{515 \cdot 0.95 \cdot 0.05}} \varphi(\frac{490 - 515 \cdot 0.95}{\sqrt{515 \cdot 0.95 \cdot 0.05}}) = 7.8125 \times 10^{-2}, \text{ which is almost the same as the previous approximation.}$ 

E4. Flip a fair die 400 times repeatedly. Give approximately the probability that the number of heads is at least 480 and less than 520.

Let  $\eta_{1000}$  be the frequency of heads in case of 1000 flips.  $\eta_{1000}$  is binomially distributed random variable with parameters n = 1000 and p = 0.5. The question is  $P(480 \le \eta_{1000} < 520)$ , which can be expressed by the cumulative distribution function of  $\eta_{1000}$  by the following way:  $P(480 \le \eta_{1000} < 520) = F_{\eta_{1000}}$  (520)  $-F_{\eta_{1000}}$  (480). Applying Moivre-Laplace formula  $F_{\mu_{1000}}(x) \ge \Phi(\frac{x - 1000 \cdot 0.5}{x})$  and

$$P(480 \le \eta_{1000} < 520) \approx \Phi(\frac{520 - 500}{\sqrt{250}}) - \Phi(\frac{480 - 500}{\sqrt{250}}) =$$

$$\Phi(\frac{520-500}{\sqrt{250}}) - \Phi(\frac{480-500}{\sqrt{250}}) = 2\Phi(\frac{20}{\sqrt{250}}) - 1 = 0.7941$$

Give an interval symmetric to 500 in which the number of heads is situated with probability 0.99.

If  $\theta \sim N(500, \sqrt{250})$ , then  $P(500-2.5758 \cdot \sqrt{250} < \theta < 500 + 2.5758 \cdot \sqrt{250}) = 0.99$ . That means  $P(459 < \eta_{1000} < 541) = 0.99$ .

What do you think if you count 455 heads in case of 1000 flips?

If we realize that the frequency of heads is less than 459, then there are two possibilities . First one is that an event with very small probability occurs. The second one is that the coin is not fair. People rather trust in the second one. This is the basic thinking of mathematical statistics.

At the end of this subsection we present the approximation of Poisson distribution by normal distribution. The possibility of that is not surprising: Poisson distribution is the limit of binomial distribution.

<u>Theorem</u> Let  $\eta_n$  be Poisson distributed random variable with parameters  $\lambda_n = n$ . Then  $\lim_{n \to \infty} P(\frac{\eta_n - n}{\sqrt{n}} < x) = \Phi(x).$ 

<u>Proof</u>  $\eta_n$  can be written as the sum of n independent Poisson distributed random variables with parameter  $\lambda = 1$ , consequently central limit theorem provides the formula presented above.

<u>Remarks</u>

• Condition  $\lambda_n = n$  is not crucial. Supposing that  $\eta$  is Poisson distributed random variable with parameter  $\lambda$  and  $10 \le \lambda$ , then  $P(\eta < x) \approx \Phi(\frac{x - \lambda}{\sqrt{\lambda}})$ .

• Expectation of  $\eta \quad E(\eta) = \lambda$ , dispersion of  $\eta \quad D(\eta) = \sqrt{\lambda}$ . Roughly spoken, the expectations of the approximated and the approximate distributions are the same values. Same can be stated about the dispersions.

• Similarly to the binomially distributed random variable,  $P(\eta = k) = \frac{\lambda^{k}}{k!}e^{-\lambda} = P(k \le \eta < k+1) \approx \Phi(\frac{k+1-\lambda}{\sqrt{\lambda}}) - \Phi(\frac{k-\lambda}{\sqrt{\lambda}})$ The goodness of the

approximation can be seen in Fig.i.12. in case of  $\lambda = 10$  and in Fig.i.13. in case of  $\lambda = 50$ .



Figure i.12. The exact and the approximate probabilities and their differences in case of Poisson distribution with parameter  $\lambda = 10$ 



Figure i.13. The exact and the approximate probabilities and their differences in case of Poisson distribution with parameter  $\lambda = 50$ 

# Example

E5. Working times of a certain part of a machine between consecutive failings are supposed to be independent exponentially distributed random variable with expectation 24 hours. If a

part goes wrong, it is changed immediately. How many spare parts should be had in order to have enough for a time period 90 days with probability 0.99.

Let  $\eta_T$  be denote the failings from time t = 0 to T. Recall that  $\eta_T$  is Poisson distributed random variable with parameter  $\lambda_T = \lambda \cdot T$ , where  $\lambda$  is the parameter of the exponential distribution. Actually, if the time unit is day, then  $\lambda = \frac{1}{E(\xi_i)} = \frac{1}{1} = 1$ , where  $\xi_i$  i = 1,2,3,... denote the time between the i-1th and ith failings. Consequently,  $\eta_{90}$  is Poisson distributed

random variable with parameter  $\lambda_{90} = 90$ . The question is the value of x for which

$$P(\eta_{90} < x) = 0.99$$
.  $P(\eta_{90} < x) = F_{\eta_{90}}(x) \approx \Phi(\frac{x > 0}{\sqrt{90}})$ . Solving the equation

$$\Phi(\frac{x-90}{\sqrt{90}}) = 0.99$$
 we get  $\frac{x-90}{\sqrt{90}} = 2.3263$ , which implies  $x = 90 + 2.3263 \cdot \sqrt{90} = 112.07$ .

Consequently, we should have 113 spare parts in order not to run out them with probability 0.99. As a control,  $P(\eta_{90} \le 113) = \sum_{i=0}^{113} \frac{90^i}{i!} e^{-90} = 0.99172$ , but

$$P(\eta_{90} \le 112) = \sum_{i=0}^{112} \frac{90^i}{i!} e^{-90} = 0.98924.$$
 This also supports the goodness of the presented

method.

# i.3. Central limit theorem for the average of independent identically distributed random variables

Central limit theorem was presented for the sum of many independent random variables. The average can be computed as a product of a sum and a constant value, consequently, central limit theorem can be written for the average, as well.

<u>Theorem</u> Let  $\xi_1, \xi_2, ..., \xi_n, ...$  be independent identically distributed random variables with expectation  $E(\xi_i) = m$  and dispersion  $D(\xi_i) = \sigma$ , i = 1, 2, ... Then,

$$\lim_{n \to \infty} P\left(\frac{\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m}{\frac{\sigma}{\sqrt{n}}}\right) < x = \Phi(x) \text{ for any } x \in \mathbb{R}.$$

Proof Notice that

$$P\left(\frac{\sum_{i=1}^{n}\xi_{i}}{\frac{n}{\sqrt{n}}-m} < x\right) = P\left(\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\frac{\sigma}{\sqrt{n}}} < x\right) = P\left(\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\frac{\sqrt{n}\cdot\sigma}{\sqrt{n}}} < x\right) = P\left(\frac{\sum_{i=1}^{n}\xi_{i}-nm}{\frac{\sigma}{\sqrt{n}\cdot\sigma}} < x\right)$$

Therefore the statement is the straightforward consequence of the central limit theorem for sums.

#### <u>Remarks</u>

• 
$$E(\frac{\sum_{i=1}^{n} \xi_{i}}{n}) = m, D(\frac{\sum_{i=1}^{n} \xi_{i}}{n}) = \frac{\sigma}{\sqrt{n}}.$$
  
•  $P\left(\frac{\sum_{i=1}^{n} \xi_{i}}{\frac{\sigma}{\sqrt{n}}} < x\right)$  is the cumulative distribution function of  $\frac{\sum_{i=1}^{n} \xi_{i}}{\frac{n}{\sqrt{n}}}$ , that is the

standardized average.

• 
$$F_{n} \atop \frac{\sum \xi_{i}}{n} (x) \approx \Phi\left(\frac{x-m}{\frac{\sigma}{\sqrt{n}}}\right)$$
. This can be proved as follows:  
 $F_{n} \atop \frac{\sum \xi_{i}}{n} (y) = P\left(\frac{\sum i=1}{n} < y\right) = P\left(\frac{\sum i=1}{n} - m \\ \frac{m}{\frac{\sigma}{\sqrt{n}}} < \frac{y-m}{\frac{\sigma}{\sqrt{n}}}\right) \approx \Phi\left(\frac{y-m}{\frac{\sigma}{\sqrt{n}}}\right).$ 

• The cumulative distribution function of the average can be approximated by cumulative distribution function of a normally distributed random variable. The expectations of the approximated and the approximate distributions are the same and so are their dispersions.

- Distribution of the averaged random variables can be arbitrary.
- Approximation can be applied if the number of random variables is at least 100.

• The fact, that the average is approximately normally distributed random variable and data are frequently averaged in statistics, is reason of the leading role of normal distribution in statistics.

#### Example

E1. Let us suppose that the lifetime of bulbs are independent exponentially distributed random variables with expectation 1000 hours. Give and interval symmetric to 1000 in which the lifetime of one bulb is situated with probability 0.8.

$$\begin{split} E(\xi_{i}) &= \frac{1}{\lambda} = \frac{1}{1000}. \text{ As } P(\xi_{i} < 2000) = 1 - e^{\frac{-2000}{1000}} = 0.865, \text{ consequently, the interval looks} \\ (1000 - x, 1000 + x) & \text{with} & x < 1000. \\ P(1000 - x < \xi_{i} < 1000 + x) = F_{\xi_{i}} (1000 + x) - F_{\xi_{i}} (1000 - x) = 1 - e^{\frac{-1000 + x}{1000}} - \left(1 - e^{\frac{-1000 - x}{1000}}\right) \\ &= e^{\frac{-1000 - x}{1000}} - e^{\frac{-1000 + x}{1000}}. \text{ Solving the equation } e^{\frac{-1000 - x}{1000}} - e^{\frac{-1000 + x}{1000}} = 0.8, \text{ we get} \\ e^{\frac{x}{1000}} - e^{-\frac{x}{1000}} = 0.8 \cdot e = 2.1746. \text{ Defining the new variable } y = e^{\frac{x}{1000}} \text{ we get} \\ y - \frac{1}{y} = 2.1746. \text{ This is a quadratic equation for the variable } y. \text{ Solving it we ends in } \end{split}$$

5824

-194176

y = -0.38993 and y = 2.5645. y =  $e^{\frac{1000}{1000}}$  can not be negative, therefore y = 2.5645. This implies x = 1000 ln(2.5645) = 941.76.

The interval looks 1000-941.76,1000+941.76 = (58.24,194.76). We note that the interval is quite large, almost 1900 hours is its length. As a control,

$$P(58.24 < \xi_i < 1941.76) = F_{\xi_i} (1941.76) - F_{\xi_i} (58.24) = 1 - e^{\frac{1941.76}{1000}} - (1 - e^{\frac{1041.76}{1000}}) = 0.8.$$

Give and interval symmetric to 1000 in which the average lifetime of 200 bulbs is situated with probability 0.8.

Turning to the average,

$$P\left(1000 - y < \frac{\sum_{i=1}^{200} \xi_i}{n} < 1000 + y\right) = F_{\frac{200}{\sum_{i=1}^{200} \frac{\xi_i}{i}}}(1000 + y) - F_{\frac{200}{\sum_{i=1}^{200} \frac{\xi_i}{i}}}(1000 - y) .$$
  
Taking into account that  $F_{\frac{200}{\sum_{i=1}^{200} \frac{\xi_i}{i}}}(x) \approx \Phi\left(\frac{x - 1000}{\frac{1000}{\sqrt{200}}}\right)$ , we should determine the value y for which  $\Phi\left(\frac{1000 + y - 1000}{\frac{1000}{\sqrt{200}}}\right) - \Phi\left(\frac{1000 - y - 1000}{\frac{1000}{\sqrt{200}}}\right) = 0.8$  holds. This implies  $2 \cdot \Phi\left(\frac{y}{\frac{1000}{\sqrt{200}}}\right) - 1 = 0.8$ , that is  $\frac{y\sqrt{200}}{1000} = 1.2816$ , that is  $y = 90.623$ .

The interval in which the average is situated with probability 0.8 is (1000-90.623,1000+90.623) = (909,1091). Notice that its length is about 182 hours, which is much less than it was in the case of exponential distribution.

# i.4. Central limit theorem for relative frequency

At the end of this chapter, we present the central limit theory for relative frequency. As the relative frequency is the average of independent characteristically distributed random variable with parameter p, this form of the central limit theorem is a special case of that concerning average.

<u>Theorem</u> Let  $k_A(n)$  be the frequency of the event A for which P(A) = p, 0 , during

$$2 \le n$$
 independent experiments. Then, for any  $x \in \mathbb{R}$ ,  $\lim_{n \to \infty} \mathbb{P}\left(\frac{\frac{k_A(n)}{n} - p}{\sqrt{\frac{p(1-p)}{n}}} < x\right) = \Phi(x)$ .

**Remarks** 

- $E(\frac{k_A(n)}{n}) = p$ ,  $D(\frac{k_A(n)}{n}) = \sqrt{\frac{p(1-p)}{n}}$ .  $P(\frac{\frac{k_A(n)}{n} p}{\sqrt{\frac{p(1-p)}{n}}} < x)$  is the value of the cumulative distribution function of the

standardized relative frequency.

• Returning to the relative frequency,  $F_{\underline{k_A(n)}}(x) \approx \Phi\left(\frac{x-p}{\sqrt{p(1-p)}}\right)$ . This can be argued

$$\begin{aligned} & \text{by } P(\frac{k_{A}(n)}{n} < y) = P\left(\frac{\frac{k_{A}(n)}{n} - p}{\sqrt{\frac{p(1-p)}{n}}} < \frac{y-p}{\sqrt{\frac{p(1-p)}{n}}}\right) \approx \Phi\left(\frac{y-p}{\sqrt{\frac{p(1-p)}{n}}}\right). \end{aligned} \right. \\ & \bullet \quad P\left(\left|\frac{k_{A}(n)}{n} - p\right| < \varepsilon\right) = P\left(p - \varepsilon < \frac{k_{A}(n)}{n} < p + \varepsilon\right) \approx \Phi\left(\frac{p + \varepsilon - p}{\sqrt{\frac{p(1-p)}{n}}}\right) - \Phi\left(\frac{p - \varepsilon - p}{\sqrt{\frac{p(1-p)}{n}}}\right) = 2\Phi\left(\frac{\varepsilon\sqrt{n}}{\sqrt{p(1-p)}}\right) - 1. \end{aligned}$$

It provides possibility to compute

- 1. the reliability  $1 \alpha$  in the function of  $\varepsilon$  and n,
- 2.  $\varepsilon$  (accuracy) in the function of reliability  $1 \alpha$  and n
- 3. number of necessary experiments (n) in the function of  $\varepsilon$  and  $1 \alpha$ .
- This formula can be directly applied if p is known. •

# Example

Throw a fair die 500 times repeatedly. Compute the probability that the E1. relative frequency of "six" is at least 0.15 and less than 0.18.

Let A be the event that the result is "six" performing one throw. The question is

 $P(0.15 \le \frac{k_A(500)}{500} < 0.18)$ . Recall that

$$P(0.15 \le \frac{k_A(500)}{500} < 0.18) = F_{\frac{k_A(500)}{500}}(0.18) - F_{\frac{k_A(500)}{500}}(0.15) \approx \Phi\left(\frac{0.18 - \frac{1}{6}}{\sqrt{\frac{1}{6} \cdot \frac{5}{6}}}\right) - \Phi\left(\frac{0.15 - \frac{1}{6}}{\sqrt{\frac{1}{6} \cdot \frac{5}{6}}}\right) = \Phi\left(\frac{1}{\sqrt{\frac{1}{6} \cdot$$

 $=\Phi(0.8)-\Phi(-1)=0.78814-0.15866=0.62948\approx 0.63.$ 

E2. Throw a fair die repeatedly 500 times. At most how much is the difference between the exact probability and the relative frequency with reliability 0.9?

Applying 
$$P\left(\left|\frac{k_A(n)}{n} - p\right| < \varepsilon\right) \approx 2\Phi\left(\frac{\varepsilon\sqrt{n}}{\sqrt{p(1-p)}}\right) - 1, \quad 2\Phi\left(\frac{\varepsilon\sqrt{n}}{\sqrt{p(1-p)}}\right) - 1 = 0.90 \text{ implies}$$

 $\frac{\epsilon\sqrt{n}}{\sqrt{p(1-p)}} = 1.645. \text{ Substituting } n = 500 \text{ and } p = \frac{1}{6}, \ \epsilon = \frac{1.654 \cdot \sqrt{\frac{1}{6} \cdot \frac{5}{6}}}{\sqrt{500}} = 0.0274. \text{ It means}$ 

that 
$$P(\frac{1}{6} - 0.0274 < \frac{k_A(500)}{500} < \frac{1}{6} + 0.0274) = P(0.1393 < \frac{k_A(500)}{500} < 0.1941) \approx 0.90$$
.

Computer simulation resulted in 0.907078. If we would like to increase the reliability, for example,  $1 - \alpha = 0.99$ , then  $2\Phi(\frac{\epsilon\sqrt{n}}{\sqrt{p(1-p)}}) - 1 = 0.99$ ,  $\frac{\epsilon\sqrt{500}}{\sqrt{\frac{1}{6}\cdot\frac{5}{6}}} = 2.5758$ ,  $\epsilon = 0.04293$ .

Consequently, the interval is  $(\frac{1}{6} - 0.04293, \frac{1}{6} + 0.04293) = (0.12374, 0.20960)$ . We can realize that the greater the reliability, the larger the interval.

E3. Throw a fair die 500 times repeatedly. How many throws should be done, if the relative frequency of "six" is closer to the exact probability than 0.01 with reliability 0.99?

Apply again the formula  $P(\left|\frac{k_A(n)}{n} - p\right| < \varepsilon) \approx 2\Phi(\frac{\varepsilon\sqrt{n}}{\sqrt{p(1-p)}}) - 1$  with  $\varepsilon = 0.01$  and

$$1 - \alpha = 0.99$$
.  $2\Phi(\frac{\epsilon\sqrt{n}}{\sqrt{p(1-p)}}) - 1 = 0.99$  implies  $\frac{0.01\sqrt{n}}{\sqrt{p(1-p)}}) = 2.5758$ , that is

$$\sqrt{n} = \frac{2.5758}{0.01} \sqrt{\frac{1}{6} \cdot \frac{5}{6}}, \quad n = \left(\frac{2.5758}{0.01} \sqrt{\frac{1}{6} \cdot \frac{5}{6}}\right)^2 = 9215$$
 instead of 500 experiments. As

 $2\Phi(\frac{\epsilon\sqrt{n}}{\sqrt{p(1-p)}})-1$  is monotone increasing function of n, if we increase the value of n, we

increase the reliability, as well. If we apply the estimation  $P(\left|\frac{k_A(n)}{n} - p\right| < \varepsilon) \ge 1 - \frac{p(1-p)}{n\varepsilon^2}$ 

presented in the previous chapter, substituting  $\varepsilon = 0.01$  and  $p = \frac{1}{6}$  and

 $1 - \frac{p(1-p)}{n\epsilon^2} = 0.99 \text{ we get } n = \frac{\frac{1}{6} \cdot \frac{5}{6}}{0.01 \cdot 0.01^2} \approx 13900 \text{ which is about the 1.5 times larger than}$ 

the previously determined simulation number. It means that it is rather worth computing by central limit theorem, than by the law of large numbers.

Note that if we would like to have accuracy  $\varepsilon = 0.001$ , then the number of simulation has to be  $10^2 = 100$  times larger than in the case of  $\varepsilon = 0.01$ .

**Central limit theorem** 

We would like to emphasize that in the previous examples the probability of the event A was known. But in many cases it is unknown and we would like to approximate the unknown probability by the relative frequency. In those cases we can apply upper estimation

for the probability  $2\Phi(\frac{\epsilon\sqrt{n}}{\sqrt{p(1-p)}}) - 1$ .

<u>Theorem</u> For any value of  $0 , <math>2\Phi(2\varepsilon\sqrt{n}) - 1 \le 2\Phi(\frac{\varepsilon\sqrt{n}}{\sqrt{p(1-p)}}) - 1$ .

 $\begin{array}{ll} \underline{\operatorname{Proof}} & \text{If } 0$ 

 $2\Phi - 1$ , therefore  $2 \cdot \epsilon \sqrt{n} \le \frac{\epsilon \sqrt{n}}{\sqrt{p(1-p)}}$  implies  $2\Phi(2 \cdot \epsilon \sqrt{n}) - 1 \le 2\Phi(\frac{\epsilon \sqrt{n}}{\sqrt{p(1-p)}}) - 1$ , which is the statement to be proved.

#### <u>Remark</u>

• Formula  $2\Phi(2\epsilon\sqrt{n}) - 1$  does not contain the unknown value of p, therefore the inequality  $2\Phi(2\epsilon\sqrt{n}) - 1 \le P(\left|\frac{k_A}{n} - p\right| < \epsilon)$  is suitable for estimating the accuracy, the reliability and the necessary number of simulation in the case of unknown p value.

For the sake of applications, we determine the reliability in the function of n and  $\epsilon$ , the accuracy  $\epsilon$  in the case of n and reliability  $1-\alpha$ , and the necessary number of simulations in the function of  $\epsilon$  and  $1-\alpha$ .

1. If n and  $\varepsilon$  are fixed then  $2\Phi(2\varepsilon\sqrt{n}) - 1 \le P(\left|\frac{k_A}{n} - p\right| < \varepsilon)$  supply a direct lower bound for the reliability.

2. If n and the reliability  $1 - \alpha$  are fixed, with the choice  $2\Phi(2\epsilon\sqrt{n}) - 1 = 1 - \alpha$ ,  $2\epsilon\sqrt{n} = \Phi^{-1}\left(1 - \frac{\alpha}{2}\right)$  and  $\epsilon = \frac{\Phi^{-1}\left(1 - \frac{\alpha}{2}\right)}{2\sqrt{n}}$ . Notice that the accuracy  $\epsilon$  is proportional to the

reciprocal of the square root of the number of simulations. We note that  $\Phi^{-1}\left(1-\frac{\alpha}{2}\right) = y$ 

means that 
$$\Phi(y) = 1 - \frac{\alpha}{2}$$
. Summarizing, if  $\varepsilon = \frac{\Phi^{-1}\left(1 - \frac{\alpha}{2}\right)}{2\sqrt{n}}$ , then  $1 - \alpha \le P\left(\left|\frac{k_A}{n} - p\right| < \varepsilon\right)$ .

• If the accuracy  $\varepsilon$  and the reliability  $1-\alpha$  are fixed, then  $2\Phi(2\varepsilon\sqrt{n})-1=1-\alpha$ 

serves again the formula  $2\varepsilon\sqrt{n} = \Phi^{-1}\left(1-\frac{\alpha}{2}\right)$  and,  $n = \left(\frac{\Phi^{-1}\left(1-\frac{\alpha}{2}\right)}{2\varepsilon}\right)^2$ . If n increases, then

the reliability increases supposing  $\epsilon$  is fixed. If the reliability is fixed and n increases, then  $\epsilon$  decreases. Note that the required number of simulation is proportional to the square of the

reciprocal of the accuracy. Summarizing, if 
$$\left(\frac{\Phi^{-1}\left(1-\frac{\alpha}{2}\right)}{2\epsilon}\right)^2 \le n$$
, then  $1-\alpha \le P\left(\left|\frac{k_A}{n}-p\right|<\epsilon\right)$ .

Examples

E1. At a survey, n = 1000 people are asked about a yes/no question. The relative frequency of answer "yes" is 0.35. Estimate the probability that the relative frequency is closer to the probability of answer "yes" (p) than 0.05, that is P(0.3 . Let A be the event that the answer is yes, <math>P(A) = p is unknown. Recalling  $2\Phi(2\epsilon\sqrt{n}) - 1 \le P(\left|\frac{k_A}{n} - p\right| < \epsilon)$  and substituting n = 1000 and  $\epsilon = 0.05$ ,  $2\Phi(2\epsilon\sqrt{n}) - 1 = 2\Phi(2 \cdot 0.05 \cdot \sqrt{1000}) = 0.99922$ . Therefore,  $0.99922 \le P(\left|k_A - p\right| < 0.05)$ .

E2. At a survey, n = 1000 people are asked about a yes/no question. How much is the largest difference between the relative frequency and the exact probability p with reliability 0.95?

We have a formula for accuracy, namely  $\varepsilon = \frac{\Phi^{-1}\left(1 - \frac{\alpha}{2}\right)}{2\sqrt{n}}$ . Now,  $1 - \alpha = 0.95$ ,

 $1 - \frac{\alpha}{2} = 0.975$ ,  $\Phi^{-1}\left(1 - \frac{\alpha}{2}\right) = 1.96$  and  $\frac{\Phi^{-1}\left(1 - \frac{\alpha}{2}\right)}{2\sqrt{n}} = \frac{1.96}{2\sqrt{1000}} = 0.031$ . That means

 $0.95 \le P(0.35 - 0.031 < \frac{k_A}{1000} < 0.35 + 0.031)$ . This is the reason why surveys publish the results with  $\pm 3\%$  in case of 1000 people.

E3. At a survey n = 1000some people are asked about a yes/no question. If we need accuracy  $\varepsilon = 0.01$  with reliability 0.95, how many people should be asked to be able to do this?

Apply 
$$\left(\frac{\Phi^{-1}\left(1-\frac{\alpha}{2}\right)}{2\epsilon}\right)^2 \le n$$
 with  $\epsilon = 0.01, 1-\alpha = 0.95$   
 $\left(\frac{\Phi^{-1}\left(1-\frac{\alpha}{2}\right)}{2\epsilon}\right)^2 = \left(\frac{1.96}{2\cdot0.01}\right)^2 = 98^2 = 9604.$ 

This is the reason why 10000people are asked to have accuracy 0.01 with reliability 0.95.

Summarizing our result, in case of  $9604 \le n$ ,  $0.95 \le P(\left|\frac{k_A}{n} - p\right| < 0.01) = P(0.34 < p < 0.35)$ .

Of course, the above questions should have been asked for computer simulation as well. The main difference between survey and computer simulation is that the number of simulation can be easily increased but the increment of number of people asked at a survey requires lots of money.

Finally we present Tables i.1.and i.2., which contain the required number of simulations for given accuracy, in case of reliability levels  $1-\alpha=0.95$  and  $1-\alpha=0.99$ . These reliability levels are often used in practice. In Tables i.3. and i.4., we present accuracy at given numbers of simulation.

$1 - \alpha = 0.95$		
n	3	
10	0.3099	
100	0.098	
500	0.043827	
1000	0.03099	
5000	0.013859	
10000	0.0098	
50000	0.0043827	
100000	0.003099	
500000	0.0013859	
1000000	0.00098	
500000	0.00043827	
1000000	0.0003099	
500000	0.00013859	
1000000	0.000098	
5000000	0.000043827	
10000000	0.00003099	

Table i.1.The accuracy in the function of number of simulations in case of reliability level 0.95

$1 - \alpha = 0.99$		
n	3	
10	0.40727	
100	0.12879	
500	0.05 7597	
1000	0.040727	
5000	0.018214	
10000	0.012879	
50000	0.005 7597	
100000	0.0040727	
500000	0.0018214	
1000000	0.0012879	
500000	0.0005 7597	
1000000	0.00040727	
5000000	0.00018214	
1000000	0.00012879	
5000000	0.00005 7597	
10000000	0.000040727	

 $1 - \alpha = 0.99$ 

Table i.2. The accuracy in the function of number of simulations in case of reliability level 0.95

3	n
0.1	97
0.05	385
0.025	1537
0.01	9604
0.005	38416
0.0025	153660
0.001	960400
0.0005	3841600
0.00025	15366000
0.0001	96040000

 $1 - \alpha = 0.95$ 

Table i.3.Necessary number of simulations to a given accuracy in case of reliability level 0.95

$1 - \alpha = 0.99$		
3	n	
0.1	166	
0.05	664	
0.025	2654	
0.01	16587	
0.005	66347	
0.0025	265390	
0.001	1658700	
0.0005	6634700	
0.00025	26539000	
0.0001	165870000	

Table i.4.Necessary number of simulations to a given accuracy in case of reliability level 0.99

# The aim of this chapter

In this chapter we present the basic concepts of mathematical statistics and we sketch of some branches of it. We introduce empirical cumulative distribution function, empirical density function, estimations of expectations and dispersions. We also present how to test hypothesis in some case.

# Preliminary knowledge

Properties of average. Normal distribution. Student's t distribution. Chisquared distribution.

# Content

- j.1. Empirical cumulative distribution functions and histogram.
- j.2. Estimation of probability, expectation and variance.
- j.3. Testing hypothesis

# j.1. Empirical cumulative distribution function and histogram

In the previous chapters we have dealt with probabilities. In this last section we present how to draw conclusions from data on the basis of probabilistic argumentations. As the cumulative distribution function contains all information about the random variable, our primary aim is to approximate it on the basis of data. Data have dual nature, before performing the sampling they are random variables, after performing the sampling they are real numbers as the results of observations of a random phenomenon. The statistical methods are executed on the numbers, but they are elaborated for the random variables.

First, clarify the concept of sample.

<u>Definition</u> Sample is a series of independent observations concerning a random variable  $\xi^*$ . More precisely, sample is  $\xi = (\xi_1, \xi_2, ..., \xi_n)$ ,  $\xi_i$  i =1,2,...,n are independent identically distributed random variable with common distribution function F. The number of elements of the sample equals n.

<u>Definition</u> Let the values of the sample be  $x_1, x_2, ..., x_n$ ,  $x_i \in \mathbb{R}$ , i=1,2,...,n. **Empirical** cumulative distribution function belonging to the values of the sample  $x = (x_1, x_2, ..., x_n)$ 

is defined as 
$$F_{(x_1, x_2, \dots, x_n)} : \mathbb{R} \to \mathbb{R}$$
  $F_{(x_1, x_2, \dots, x_n)}(z) = F_e(z) = \frac{\sum_{i=1}^n \mathbb{1}_{\{x_i < z\}}}{n}$ .

Remarks

- Argument of the function is denoted by z because the letter x is related to the sample.
- $F_{(x_1,x_2,...,x_n)}(z)$  is briefly denoted by  $F_e(z)$ .
- Cumulative distribution function is the relative frequency of the event  $\{\xi < z\}$  if we

perform independent experiments for this event.  $F_e(z) = \frac{\sum_{i=1}^{n} \mathbf{1}_{\{x_i < z\}}}{n}$  is a staggered function which has jumps at  $z = x_i$ . It is constantly zero previous to the smallest element of the sample, and it is constantly 1 following the greatest one.

- The elements of the sample  $x_i$  and  $x_j$  may be equal.
- The function  $F_e(z)$  has all properties of cumulative distribution function. Namely,
  - 1.  $\sum_{i=1}^{n} \mathbf{1}_{\{x_i < z\}} \leq \sum_{i=1}^{n} \mathbf{1}_{\{x_i < y\}}$  for any values of z < y, which implies monotone increasing property.
  - 2. Its limit is zero at  $-\infty$  and 1 at  $\infty$ .
  - 3. It is left hand-side continuous. Consequently, it is really cumulative distribution function.

• The random variable  $\theta \sim \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ \frac{1}{n} & \frac{1}{n} & \dots & \frac{1}{n} \end{pmatrix}$  has the same cumulative

distribution function if  $x_i$  are all different. If some  $x_i$  values are repeatedly in the sample, then the probability belonging to this value is the relative frequency of this element in the sample.

#### Example

E1. Let the elements of the sample be  $x_1 = 12$ ,  $x_2 = 10$ ,  $x_3 = 15$ ,  $x_4 = 12$ ,  $x_5 = 13$ . Draw the empirical cumulative distribution function belonging to these sample elements.

$$F_{e}(z) = \sum_{i=1}^{5} \mathbf{1}_{\{x_{i} < z\}} = \begin{cases} 0 & \text{if } z \le 10 \\ \frac{1}{5} & \text{if } 10 \le z < 12 \\ \frac{3}{5} & \text{if } 12 \le z < 13 \\ \frac{4}{5} & \text{if } 13 \le z < 15 \\ 1 & \text{if } 15 \le z \end{cases}$$

 $( \cap$ 

This function can be seen in Fig.j.1.



Figure j.1. Empirical distribution function belonging to the sample elements in E.1.

<u>Theorem</u> If  $F_e(z)$  is the empirical cumulative distribution function belonging to the sample elements  $(x_1,...,x_n)$  and F(z) is the cumulative distribution function of  $\xi_i$ , i=1,2,3,..., then for any value of  $x \in R$  and  $0 < \varepsilon$ ,  $P(|F_e(z) - F(z)| < \varepsilon) \rightarrow 1$  if  $n \rightarrow \infty$ .

<u>Proof</u> Let A be the event that the random variable  $\xi^*$  is less than z, that is  $A = \{\xi^* < z\}$ . Now  $F_e(z)$  is the relative frequency of A during n independent trials. Moreover, F(z) = P(A). The law of large numbers states that the relative frequency of an event and the probability of that are close to each other, that is  $P(|F_e(z) - F(z)| < \varepsilon) \ge 1 - \frac{F(z)(1 - F(z))}{n\varepsilon^2} \rightarrow 1 - 0$ , supposing  $n \rightarrow \infty$ . **Remarks** 

• The above theorem is the consequence of the law of large numbers.

• The theorem states that the values of the cumulative distribution function can be approximated by the empirical cumulative distribution function. The necessary number of simulations to a given accuracy can be determined by applying the central limit theorem presented in the previous section. For example, if  $\varepsilon = 0.01$ , then n = 9604, if the reliability level is 0.95.

# Example

E1. Let  $\xi^*$  be exponentially distributed random variable with parameter  $\lambda = 1$ . Take a sample of n elements independently with respect to  $\xi^*$ . Draw the empirical cumulative distribution function of the sample if n=10 and n=100 and n = 1000. The empirical cumulative distribution functions together with the exact one can be seen in

The empirical cumulative distribution functions together with the exact one can be seen in Figs.j.2. and j.3.



Figure j.2. Empirical distribution function belonging to an exponentially distributed sample of 10 and 100 elements



Figure j.3. Empirical distribution function belonging to an exponentially distributed sample of 1000 elements and a segment of the function

One can realize that there is hardly difference between the exact cumulative distribution function and the empirical one if the number of sample elements is large.
E2. The exact cumulative distribution function and the empirical one is presented in Fig. j.4. in case of  $\xi \sim \begin{pmatrix} 0 & 1 \\ 0.5 & 0.5 \end{pmatrix}$ . The number of sample elements was n=10 and n=100.



Fig.j.4. Empirical cumulative distribution function (blue) and exact one (red) in case of 10 and 100 sample elements

One can see that if the number of elements is large, then they are close to each other.

The following statement is a stronger one than the previously proved statement. We present it without proof.

#### Theorem (Glivenko)

If  $F_{e}(z)$  is the empirical cumulative distribution function belonging to the sample elements  $(x_1,...,x_n)$  and F(z) is the cumulative distribution function of  $\xi^*$  and  $\xi_i$ , i=1,2,3,...Then  $\sup_{z} |F_e(z) - F(z)| \to 0$  if  $n \to \infty$  with probability 1.

Remarks

- Glivenko's theorem is often used as fundamental theorem of mathematical statistics.
- Its philosophical interpretation is that the world is knowable.

The main differences of the Glivenko's theorem and the theorem presented at the • beginning of the section are that this later states uniform convergence (not for any z separately) and states probability 1 (strong law of large numbers).

Test for distribution function can be given on the maximal difference called as Kolmogorov-Smirnov's test, and will be presented in the last subsection.

Now we turn to the approximation of probability density function by histogram. Histograms were used for presentation of relative frequencies. We usually compared them to the probability density functions.

<u>Definition</u> Let  $x_1, x_2, ..., x_n$  be value of the sample. Let  $a = \min_{i=1,2,..,n} x_i$ ,  $b = \max_{i=1,2,..,n} x_i$  and  $1 \le m$  fixed. Then consider points  $y_0 = a - \frac{b-a}{2m}$ ,  $y_i = y_{i-1} + i\frac{b-a}{m}$ , i = 1, 2, ..., m. Let

$$k_{i}(n,m) = \sum_{j=1}^{n} \mathbf{1}_{\{x_{j} \in [y_{i-1}, y_{i})\}}, i = 1, 2, ..., m \text{ and}$$

$$f_{e}(z) = \begin{cases} \frac{k_{i}(n,m)}{n} \cdot \frac{1}{\frac{b-a}{m}} & \text{if } z \in [y_{i-1}, y_{i}) & i = 1, 2, ..., m \\ 0 & \text{otherwise} \end{cases}$$

The function  $f_e(z)$  is called as **histogram** with m equally lengthen subintervals belonging to the sample elements  $x_1, x_2, ..., x_n$ .

**Remarks** 

• Histogram strongly depends on the value of m. If m is too small or too large as compared to n the shape of the graph of histogram will not be appropriate. To see this, we present Fig.j.5. The number of sample elements sample was n=100 in all cases. The sample was uniformly distributed, m=4, m=10, m=50 and m=100. The sample elements were the same in case of all histograms.







Figure j.6. Histograms of a sample of 100 elements in case of m=50 and m=100

If the number of sample elements is 10000 and they are uniformly distributed in [0,1], then the histograms for m = 4, m = 10, m = 50 and m = 100 looks as follows:







j.5. Histograms of sample of 10000 elements in case of 51 and 101 subintervals

The histograms belonging to m=4 and m=10 seem to be better approximations of the probability density function of uniformly distributed random variable. The high of the first and last rectangular is the half of the others because the smallest value of the sample is about first subinterval zero, the is [-0.05, 0.05],and  $P(-0.05 \le \xi < 0.05) = P(0 \le \xi < 0.05) = 0.05$ , while  $P(0.05 \le \xi < 0.15) = 0.1$ . The last subinterval is (0.95, 1.05],  $P(0.95 \le \xi < 1.05) = 0.05$ .

• Although there are many theorems concerning the relationship of the empirical cumulative distribution function and the real cumulative distribution function, it is difficult to give limit theorem concerning the histogram and the probability density function. In abstruse phrasing, for appropriate fixed m values, the histogram is close the real probability density function, if n is large. Examples were presented in section g.

#### j.2. Estimation of probability, expectation and variance

After approximating the cumulative distribution function and the probability density function, we estimate the probability of an event, furthermore the expectation and the variance of a random variable. This will be done by a function of the sample.

<u>Definition</u> Let  $\xi = (\xi_1, \xi_2, ..., \xi_n)$  be sample and  $g: H \subset \mathbb{R}^n \to \mathbb{R}$  a real valued function with  $\text{Im}\xi \subset H$ . Then  $g \circ \xi = g(\xi)$  is called **statistics**.

**Remarks** 

• Statistics are the function of the sample. The question in which cases which function should be applied is important question of mathematical statistics.

• The function  $g \circ \eta : \Omega \to R$  is a random variable, and  $g(x_1, x_2, ..., x_n)$  is a real number. The dual property appears in this case, as well.

#### **Estimation of probability**

Let  $\xi = (\xi_1, \xi_2, ..., \xi_n)$  be a sample,  $\xi_i \ \xi_i = 1_A^i = \begin{cases} 1 & \text{if } A \text{ occurs at the ith experiment} \\ 0 & \text{if } \overline{A} \text{ occurs at the ith experiment} \end{cases}$ 

are characteristically distributed random variables with parameter  $0 . Let <math>g: \mathbb{R}^n \to \mathbb{R}$ 

 $g(y_1, y_2, ..., y_n) = \frac{\sum_{i=1}^n y_i}{n}. \text{ Then } g \circ \xi = g(\xi) = \frac{\sum_{i=1}^n \xi_i}{n} \text{ the sample average It can be considered}$ as the relative frequency of an event A with P(A) = p. Now,  $E(g(\xi)) = E\left(\frac{\sum_{i=1}^n \xi_i}{n}\right) = \frac{np}{n} = p, \ D(g(\xi)) = \sqrt{\frac{p(1-p)}{n}} \to 0. \text{ Consequently, if we estimate the}$ 

probability p = P(A) by  $p = \frac{\sum_{i=1}^{n} \xi_i}{n} = \frac{k_A(n)}{n}$ , then the expectation of the estimation equals the exact probability p and the dispersion of the estimation tends zero if  $n \to \infty$ . These two properties implies the consistency of the estimation, which means that the estimate value fluctuates around the value to be estimated and the fluctuation tends zero if the number of sample elements tends to infinity.

Moreover, applying the central limit theorem, for  $100 \le n$ ,  $10 \le np$ , we can write that  $P(p-u_{\alpha}\sqrt{\frac{p(1-p)}{n}} \le \frac{k_{A}}{n} \le p + u_{\alpha}\sqrt{\frac{p(1-p)}{n}}) = 1 - \alpha$ , with  $\Phi(u_{\alpha}) = 1 - \frac{\alpha}{2}$ . Arranging the sides of both inequalities, they end in (approximately)  $P\left(\frac{k_{A}}{n} - u_{\alpha}\sqrt{\frac{k_{A}}{n}(1-\frac{k_{A}}{n})}_{n} \le p \le \frac{k_{A}}{n} + u_{\alpha}\sqrt{\frac{k_{A}}{n}(1-\frac{k_{A}}{n})}_{n}}\right) = 1 - \alpha$  with  $\Phi(u_{\alpha}) = 1 - \frac{\alpha}{2}$ .

Summarizing, the interval

$$\left[\frac{\underline{k_{A}}}{n} - u_{\alpha}\sqrt{\frac{\underline{k_{A}}(1 - \underline{k_{A}})}{n}}, \frac{\underline{k_{A}}}{n} + u_{\alpha}\sqrt{\frac{\underline{k_{A}}(1 - \underline{k_{A}})}{n}}\right]$$

contains the exact probability p with probability (reliability level)  $1-\alpha$ . This interval is usually called as confidence interval for the probability belonging to the reliability level  $1-\alpha$ .

Remarks

• We list the values  $u_{\alpha}$  for some frequently used reliability levels  $1-\alpha$ , and give

confidence intervals for the probability in case of relative frequency  $\frac{\sum_{i=1}^{n} \xi_i}{n} = 0.450$  and n=500 in Table j.1.

$1-\alpha$	uα	Confidence interval
0.9	1.645	[0.413,0.487]
0.95	1.960	[0.406, 0.493]
0.98	2.326	[0.398,0.502]
0.99	2.575	[0.393, 0.507]

Table j.1. Values  $u_{\alpha}$  and confidence intervals for the probability belonging to reliability level  $1-\alpha$ 

• The larger the reliability, the wider the interval.

#### Estimation of the expectation in case of known value of dispersion

Let  $\xi = (\xi_1, \xi_2, ..., \xi_n)$  be a sample,  $\xi_i$  are random variables with expectation m and

dispersion  $\sigma$ . Let  $g: \mathbb{R}^n \to \mathbb{R}$   $g(y_1, y_2, ..., y_n) = \frac{\sum_{i=1}^n y_i}{n}$ . Then  $g(\xi) = \frac{\sum_{i=1}^n \xi_i}{n} = \overline{\xi}$  is the sample average. Now,  $E(g(\xi)) = E\left(\frac{\sum_{i=1}^n \xi_i}{n}\right) = \frac{nm}{n} = m$ ,  $D(g(\eta)) = \frac{\sigma}{\sqrt{n}}$ . Consequently, if we

estimate the expectation by the sample average, then  $E(m) = E(\frac{\sum_{i=1}^{n} \xi_i}{n}) = m$ , and

 $D\left(\frac{\sum_{i=1}^{n} \xi_{i}}{n}\right) \rightarrow 0.$  This means that the sample average is consistent estimation for the

expectation. Note that the sample average is the expectation belonging to the empirical cumulative distribution function. Moreover, if  $\xi_i \sim N(m,\sigma)$ , or  $100 \le n$ , then

 $\frac{\sum_{i=1}^{n} \xi_{i}}{n} \sim N(m, \frac{\sigma}{\sqrt{n}}), \text{ or this holds approximately. Applying the } k \cdot \sigma \text{ law with notation}$ 

#### 184 **Probability theory and math.statistics Basic concepts of mathematical statistics**

 $k = u_{\alpha}$ , we get  $P(m - u_{\alpha} \frac{\sigma}{\sqrt{n}} < \frac{\sum_{i=1}^{n} \xi_{i}}{n} < m + u_{\alpha} \frac{\sigma}{\sqrt{n}}) = 1 - \alpha$ . Arranging both sides of the

inequalities we end in  $P(\frac{\sum_{i=1}^{n} \xi_{i}}{n} - u_{\alpha} \frac{\sigma}{\sqrt{n}} < m < \frac{\sum_{i=1}^{n} \xi_{i}}{n} + u_{\alpha} \frac{\sigma}{\sqrt{n}}) = 1 - \alpha$ .

$$\left[\frac{\sum_{i=1}^{n}\xi_{i}}{n}-u_{\alpha}\frac{\sigma}{\sqrt{n}},\frac{\sum_{i=1}^{n}\xi_{i}}{n}+u_{\alpha}\frac{\sigma}{\sqrt{n}}\right]$$

is an interval in which the expectation m is situated with probability  $1-\alpha$ . It is called as confidence interval of the expectation belonging to the reliability level  $1-\alpha$ .

#### Remarks

- The above formula can be applied in the case when the dispersion is given.
- If we have the sample elements  $(x_1, x_2, ..., x_n)$ , we have to substitute these values

into the formula  $\left| \frac{\sum_{i=1}^{n} \xi_{i}}{n} - u_{\alpha} \frac{\sigma}{\sqrt{n}}, \frac{\sum_{i=1}^{n} \xi_{i}}{n} + u_{\alpha} \frac{\sigma}{\sqrt{n}} \right|$  to get the confidence interval for the

expectation belonging to the reliability level  $1-\alpha$ . For example, if  $x_1 = 1.5$ ,  $x_2 = 1.7$ ,  $x_3 = 1.4$ ,  $x_4 = 1.9$ ,  $x_5 = 1.7$  then

 $\frac{x_1 + x_2 + x_3 + x_4 + x_5}{5} = \frac{1.5 + 1.7 + 1.4 + 1.9 + 1.7}{5} = 1.64.$  The confidence interval

belonging to the reliability levels 0.9, 0.95, 0.98 and 0.99 are contained in the Table j.2.

$1-\alpha$	uα	$\left[1.64 - u_{\alpha} \cdot \frac{0.2}{\sqrt{5}}, 1.64 + u_{\alpha} \cdot \frac{0.2}{\sqrt{5}}\right]$
0.9	1.645	[1.493, 1.787]
0.95	1.960	[1.465, 1.815]
0.98	2.326	[1.432, 1.848]
0.99	2.575	[1.409, 1.871]

Table j.2. Confidence intervals for the expectation in case of reliability level  $1 - \alpha$ 

If the reliability level is increased, then the length of the interval increases, as well.

If the number of sample elements tends to infinity, the length of the confidence interval tends to zero.

• If the accuracy is given, we can compute the necessary number of sample elements to a given reliability level. For example, if we would like to have a confidence interval to

# **Probability theory and math.statistics Basic concepts of mathematical statistics** <sup>185</sup>

the reliability level 0.99 with length 0.1, then

$$\left(\frac{2.576}{0.05} \cdot 0.2\right)^2 = 107 \le n$$
. The number of the necessary elements is proportional to the

variance and to the square of the reciprocal of the accuracy.

If the dispersion of the random variable is not known then we have to estimate it on the basis of the sample.

#### Estimation of the variance and the dispersion

As the sample average is the expectation belonging to the empirical distribution function, it is coherent idea to estimate the variance  $\sigma^2$  by the variance belonging to the empirical distribution function.

Let 
$$s^{2}: \mathbb{R}^{n} \to \mathbb{R}$$
,  $s^{2}(y_{1}, y_{2}, ..., y_{n}) = \frac{\sum_{i=1}^{n} (y_{i} - \overline{y})^{2}}{n}$ . Then  
 $s^{2} \circ \xi = s^{2}(\xi_{1}, \xi_{2}, ..., \xi_{n}) = \frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n}$ , where  $\overline{\xi} = \frac{\sum_{i=1}^{n} \xi_{i}}{n} \cdot s^{2}(\xi_{1}, \xi_{2}, ..., \xi_{n})$  is a random variable.  
 $E(s^{2}(\xi_{1}, \xi_{2}, ..., \xi_{n})) = E\left(\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n}\right) = \frac{1}{n} E\left(\sum_{i=1}^{n} (\xi_{i} - m + m - \overline{\xi})^{2}\right)$   
 $= \frac{1}{n} E\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2} - 2\sum_{i=1}^{n} (\xi_{i} - m)(\overline{\xi} - m) + n(\overline{\xi} - m))^{2}\right) = \frac{1}{n} E\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2}\right) - E((\overline{\xi} - m)^{2}) \cdot E((\overline{\xi} - m)^{2}) = E\left(\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2}\right)^{2}\right) = \frac{1}{n^{2}} E\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2}\right) = \frac{1}{n^{2}} E\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2}\right) = \frac{1}{n^{2}} E\left(\sum_{i=1}^{n} (\xi_{i} - m)^{2}\right) = \frac{1}{n^{2}} e^{2} - \frac{1}{n} \sigma^{2} - \frac{1}{n} \sigma^{2}$ .

 $u_{\alpha} \cdot \frac{\sigma}{\sqrt{n}} \leq \frac{0.1}{2}, \left(\frac{u_{\alpha} \cdot \sigma}{0.05}\right)^2 \leq n$ , that is .

Consequently,  $E\left(\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n}\right) \neq \sigma^{2}$ . Let  $s^{*2}(y_{1}, y_{2}, ..., y_{n}) = \frac{\sum_{i=1}^{n} (y_{i} - \overline{y})^{2}}{n-1} = \frac{n}{n-1}s^{2}(y_{1}, y_{2}, ..., y_{n})$ .  $E(s^{*2}(\xi_{1}, \xi_{2}, ..., \xi_{n})) = E\left(\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n-1}\right) = \frac{n}{n-1} \cdot E\left(\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n}\right) = \frac{n}{n-1} \cdot \frac{n-1}{n}\sigma^{2} = \sigma^{2}$ .

 $s^{*2}(\xi_1,\xi_2,...,\xi_n)$  is briefly denoted by  $s^{*2}$ . It can be proved that if  $E(\xi_i^4)$  exists, then  $D^2(s^{*2}(\xi_1,\xi_2,...,\xi_n)) \rightarrow 0$ , if  $n \rightarrow \infty$ . Summarizing,  $s^{*2}$  is consistent estimation of the variance. Now it is worth estimating the dispersion by the statistics

$$s*(\xi_{1},\xi_{2},...\xi_{n}) = \sqrt{s*^{2}(\xi_{1},\xi_{2},...\xi_{n})} = \sqrt{\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n-1}} .$$
Definition The statistics  $s*(\xi_{1},\xi_{2},...\xi_{n}) = \sqrt{\frac{\sum_{i=1}^{n} (\xi_{i} - \overline{\xi})^{2}}{n-1}}$  is called as **corrected empirical**

#### dispersion.

To construct confidence interval for the variance and the dispersion we state the following theorem without proof (Fisher-Cochran's theorem)

<u>Theorem</u> If  $\xi_i \sim N(m, \sigma)$ , then  $(n-1)\frac{s^{*2}(\xi_1, \xi_2, ..., \xi_n)}{\sigma^2} \sim \chi_{n-1}^2$ , furthermore  $\overline{\xi}$  and  $s^{*2}(\xi_1, \xi_2, ..., \xi_n)$  are independent random variables. By definition of Student's t distribution (see chapter g), this also implies that  $\frac{\overline{\xi} - m}{s^*(\xi_1, \xi_2, ..., \xi_n)} \sqrt{n} \sim \tau_{n-1}$ .

Remarks

•  $\chi_n^2$  distributed random variables were presented in Chapter g. The explicit forms of their cumulative distribution functions are not usually used. There are tables (see Table 3.) which contain the real values  $\chi_{n,\alpha}^2$  for which  $P(\chi_{n,\alpha}^2 \le \theta) = \alpha$  supposing  $\theta \sim \chi_n^2$ . This means that  $P(\theta < \chi_{n,\alpha}^2) = 1 - \alpha$ . These values  $\chi_{n,\alpha}^2$  are called as critical values belonging to the reliability level  $1 - \alpha$ .

• By the help of the critical values belonging to  $1-\frac{\alpha}{2}$  and  $\frac{\alpha}{2}$  one can construct an interval in which the values of  $\chi_n^2$  distributed random variable are situated with probability  $1-\alpha$ . Namely,  $P(\chi_{n,1-\alpha/2}^2 \le \theta \le \chi_{n,\alpha/2}^2)$ . These intervals will be used to construct such intervals in which variance and dispersion are situated with probability  $1-\alpha$ .

**Probability theory and math.statistics Basic concepts of mathematical statistics** <sup>187</sup>

If 
$$\xi_i \sim N(m,\sigma)$$
, then  $(n-1)\frac{s^{*2}(\xi_1,\xi_2,...,\xi_n)}{\sigma^2} = \frac{\sum_{i=1}^n (\xi_i - \overline{\xi})^2}{\sigma^2} \sim \chi^2_{n-1}$ , consequently

 $P(\chi_{n,1-\alpha/2}^2 \le (n-1)\frac{s^{*2}}{\sigma^2} \le \chi_{n,\alpha/2}^2) = 1 - \alpha$ . Arranging the sides of the inequalities we end in

 $P((n-1)\frac{s^{*2}}{\chi^{2}_{n,\alpha/2}} \le \sigma^{2} \le (n-1)\frac{s^{*2}}{\chi^{2}_{n,1-\alpha/2}}) = 1 - \alpha .$  As a straightforward consequence,  $P(\sqrt{(n-1)\frac{s^{*2}}{\chi^{2}_{n,\alpha/2}}} \le \sigma \le \sqrt{(n-1)\frac{s^{*2}}{\chi^{2}_{n,1-\alpha/2}}}) = 1 - \alpha .$  Summarizing, supposing normally

distributed samples or large number of elements, the confidence interval for the variance belonging to the reliability level  $1 - \alpha$  looks like

$$\left[(n-1)\frac{s^{*2}}{\chi^2_{n,\alpha/2}},(n-1)\frac{s^{*2}}{\chi^2_{n,1-\alpha/2}}\right]$$

and that for the dispersion it is

$$\left[\sqrt{(n-1)\frac{s^{*2}}{\chi^2_{n,\alpha/2}}}, \sqrt{(n-1)\frac{s^{*2}}{\chi^2_{n,1-\alpha/2}}}\right]$$

Remarks

Due to the central limit theorem, the assumption of normally distributed sample can • be omitted if n is large.

If we have the value of the sample, we can construct the confidence intervals for the variance and the dispersion by the following steps: compute the value of  $s^{*2}$ , find the critical value belonging to the reliability levels  $\frac{\alpha}{2}$  and  $1-\frac{\alpha}{2}$ , then substitute them into the formulae in the boxes.

For example, assuming normally distributed sample, if  $x_1 = 1.5$ ,  $x_2 = 1.7$ ,

$$x_{3} = 1.4, x_{4} = 1.9, x_{5} = 1.7 \text{ then } \overline{x} = 1.64 \text{ and } s^{*2} = \frac{\sum_{i=1}^{3} (x_{i} - \overline{x})^{2}}{4} = \frac{(1.5 - 1.64)^{2} + (1.7 - 1.64)^{2} + (1.4 - 1.64)^{2} + (1.9 - 1.64)^{2} + (1.7 - 1.64)^{2}}{4} = 0.038.$$

Confidence intervals belonging to the reliability levels 0.9, 0.95, 0.98 and 0.99 are included in Table j.3.

$1-\alpha$	$\chi^2_{4,1-\alpha/2}$	$\chi^2_{4,\alpha/2}$	$\left[4\cdot\frac{\mathbf{s}^{\mathbf{*}^{2}}}{\chi^{2}_{4,\alpha/2}}, 4\cdot\frac{\mathbf{s}^{\mathbf{*}^{2}}}{\chi^{2}_{4-\alpha/2}}\right]$	$\left[\sqrt{(n-1)\frac{s^{*2}}{\chi^{2}_{4,\alpha/2}}},\sqrt{(n-1)\frac{s^{*2}}{\chi^{2}_{4,1-\alpha/2}}}\right]$
0.9	0.711	9.488	[0.016, 0.214]	[0.127,0.462]
0.95	0.484	8.496	[0.018, 0.314]	[0.134, 0.560]

0.98	0.297	13.277	[0.011, 0.512]	[0.107, 0.715]
0.99	0.207	14.86	[0.010, 0.734]	[0.101, 0.857]

Table j.3. Critical values and confidence intervals for the variance and dispersion in case of reliability levels  $1-\alpha$ 

• The greater reliability, the larger interval.

Finally let us return to the estimation of the expectation in case of unknown dispersion.

#### Estimation of the expectation in case of unknown dispersion

Taking the sample average does not require the knowledge of the dispersion. Furthermore,

estimating the expectation by the sample average,  $E(m) = E(\frac{\sum_{i=1}^{n} \xi_i}{n}) = m$ , and  $\left(\sum_{i=1}^{n} \xi_i\right)$ 

 $D\left(\frac{\sum_{i=1}^{n} \xi_{i}}{n}\right) \to 0 \text{ holds in the case of unknown value of } \sigma, \text{ as well.}$ 

Turning to the confidence interval for the expectation, apply Fisher-Cochran' theorem and the formula  $\frac{\overline{\xi} - m}{s^*}\sqrt{n} \sim \tau_{n-1}$  in case of normally distributed samples.

There are tables of Student's t distribution, in which one can find the real numbers  $t_{n,\alpha}$ , for which  $P(-t_{n,\alpha} \le t_n \le t_{n,\alpha}) = 1 - \alpha$ . The value  $t_{n,\alpha}$  is called as critical value belonging to the reliability level  $1 - \alpha$ . Now,  $P(-t_{n-1,\alpha} \le \frac{\overline{\xi} - m}{s^*} \sqrt{n} \le t_{n-1,\alpha}) = 1 - \alpha$ . Arranging both sides of the inequalities we ends in  $P(\overline{\xi} - \frac{t_{n-1,\alpha} \cdot s^*}{\sqrt{n}} \le m \le \overline{\xi} + \frac{t_{n-1,\alpha} \cdot s^*}{\sqrt{n}}) = 1 - \alpha$ . Summarizing, the confidence interval for the expectation belonging to the reliability level  $1 - \alpha$  is

$$\left[\overline{\xi} - \frac{t_{n-l,\alpha} \cdot s^*}{\sqrt{n}}, \overline{\xi} + \frac{t_{n-l,\alpha} \cdot s^*}{\sqrt{n}}\right].$$

#### **Remarks**

• Note that the confidence intervals for the expectation are very similar in the cases of known and unknown dispersion. In case of unknown dispersion,  $\sigma$  is replaced by its estimation, s\*, and the critical value is  $t_{n-1}$ , instead of  $u_{\alpha}$ .

- The larger the reliability level, the larger the interval.
- The larger the number of elements, the smaller the critical value.
- The limit of the critical values  $t_{n,\alpha}$  are  $u_{\alpha}$ , that is  $\lim_{n\to\infty} t_{n,\alpha} = u_{\alpha}$ . This is due to the

statement that the cumulative distribution functions of Student's t distributed random variables is the cumulative function of a standard normally distributed random variable.

### **Probability theory and math.statistics Basic concepts of mathematical statistics** 189

• The confidence intervals belonging to a given reliability level can be constructed after executing the following steps: compute s\* on the basis of the sample, find the critical value and substitute into the above formula. In case of normally distributed sample and  $x_1 = 1.5$ ,  $x_2 = 1.7$ ,  $x_3 = 1.4$ ,  $x_4 = 1.9$ ,  $x_5 = 1.7$ ,  $\overline{x} = 1.64$  and  $s^* = \sqrt{0.038}$ . The confidence intervals belonging to the reliability levels 0.9, 0.95, 0.98 and 0.99 are presented in Table j.5.

$1-\alpha$	$t_{4,\alpha}$	$\left[\overline{\xi} - \frac{t_{4,\alpha} \cdot s^*}{\sqrt{5}}, \overline{\xi} + \frac{t_{4,\alpha} \cdot s^*}{\sqrt{5}}\right]$
0.9	1. 533	[1.506, 1.774]
0.95	2.132	[1.454, 1.826]
0.98	2.999	[1.378, 1.901]
0.99	3.747	[1.313, 1.967]

Table j.5. Critical values and confidence intervals for the expectation in case of unknown value of dispersion

### j.3. Testing hypothesis

An important branch of mathematical statistics is testing hypothesis. Hypothesis is an idea about the value of probability, expectation, dispersion, a parameter or about the cumulative distribution function itself. We check that the hypothesis can be true or not, more exactly, data contradict to the hypothesis or not. The main idea of testing hypothesis is the following: if the hypothesis holds, then a certain function of the sample has a known distribution. This implies that one can determine an interval in which the function of the sample is situated with a given reliability  $1-\alpha$ . If the hypothesis does hold, the values of the function (test function) are out that interval with probability  $\alpha$ . The mentioned interval is called as acceptation region; its compliment is the critical region. Then, check whether the test function is really in the acceptation region. If it is, then the data do not contradict to the hypothesis holds and an event with small probability  $\alpha$  occurs. Statisticians vote for the later one, hence we do not accept the hypothesis, because we rather trust in the alternative than in the occurrence of rare event. Of course, the decision may be wrong.

The name of the basic idea is null hypotheses  $(H_0)$ , the name of the opposite is alternative hypothesis  $(H_1)$ . They have to be mutually exclusive but they may not cover all possibilities concerning the parameter. For example,  $H_0$  is that the probability of an event is 0.4, the alternative hypothesis is that the probability of the event is smaller than 0.4.

Decision, whether we accept (fail to reject)  $H_0$  or reject it, may be right or wrong. Following four cases can be distinguished:

	H <sub>0</sub> is accepted	$H_0$ is rejected
$H_0$ is true	Right decision	Wrong decision
$H_0$ is not true	Wrong decision	Right decision

Table j.6. Possibilities concerning the decisions in testing a hypothesis

# **Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>190</sup>

Decision that  $H_0$  is true, although it is rejected is called as error of the first kind (type I. error), its probability is  $\alpha$ . The probability of the first kind error is usually called as the level of significance.

Decision that H<sub>0</sub> is not true, although it is not failed to reject is called as error of the second kind (type II. error). Its probability depends on the value of the tested parameter, for example. Consequences of the different kind of errors are of various severities.

#### Remarks

Usually applied significance levels are  $\alpha = 0.05$  and  $\alpha = 0.01$ . ٠

Some test functions are connected with the statistics presented in the previous subsection.

The elaborated tests can be executed as a recipe in the kitchen. Their steps are the • followings:

State  $H_0$  and  $H_1$ , fix the level of significance.

Determine the critical region and the acceptance region.

Compute the actual value of the test function by substituting the values of the sample elements into the test function.

Check weather the actual value of the test function is in the critical region or in the acceptance region.

Make your decision: if the actual value of the test function is in the critical region, reject  $H_0$ , if it is in the acceptance region, accept  $H_0$ .

If  $H_0$  is accepted, then  $H_0$  may be untrue but the data do not contradict to this assumption. If you doubt in  $H_0$  you should take a sample of more elements.

In the latest part of this subsection we present tests for the probability, expectation, variance and cumulative distribution function. We explain the task, present the test function, critical and acceptance region and decision itself in all cases, separately.

#### Test for the probability

During this problem we have to decide about the probability of an event, whether it can be a  $\eta = (\xi_1, \xi_2, ..., \xi_n)$ fixed number or not. Let be the sample,  $\xi_{i} = 1_{A}^{i} = \begin{cases} 1 & \text{if A occurs at the ith experiment} \\ 0 & \text{if } \overline{A} \text{ occurs at the ith experiment} \end{cases}$ . Now,  $\sum_{i=1}^{n} \xi_{i} = k_{A}(n)$ , the frequency of

A, and  $\frac{\sum_{i=1}^{n} \xi_i}{n} = \frac{k_A(n)}{n}$  its relative frequency.

Let  $H_0: P(A) = p_0$ ,  $H_1: P(A) \neq p_0$ , where  $p_0$  is the idea about the probability of the event. If  $100 \le n$ ,  $10 \le np_0$  is satisfied, then by the central limit theorem we can state, that

 $\frac{n}{\sqrt{\frac{p_0(1-p_0)}{n}}} \sim N(0,1)$  supposing that H<sub>0</sub> holds. Consequently, let the test function

**Probability theory and math.statistics Basic concepts of mathematical statistics** <sup>191</sup>

$$u = \frac{\frac{k_{A}(n)}{n} - p_{0}}{\sqrt{\frac{p_{0}(1 - p_{0})}{n}}}. \quad \text{If} \quad H_{0} \quad \text{holds, then} \quad P(-u_{\alpha} \le \frac{\frac{k_{A}(n)}{n} - p_{0}}{\sqrt{\frac{p_{0}(1 - p_{0})}{n}}} \le u_{\alpha}) = 1 - \alpha, \quad \text{where}$$

 $\Phi(u_{\alpha}) = 1 - \frac{\alpha}{2}$ , coinciding with the previous subsection. Critical region is  $(-\infty, -u_{\alpha}) \cup (u_{\alpha}, \infty)$  and acceptance region is  $[-u_{\alpha}, u_{\alpha}]$ . Critical value  $u_{\alpha}$  and its  $(-\infty,-u_{\alpha})\cup(u_{\alpha},\infty)$  and acceptance region is  $\sum_{n=-\infty,\infty}^{\infty} \frac{k_{A}(n)}{n} - p_{0}$  is in the opposite are the bounds of the critical region. If the actual value of  $\frac{\frac{k_{A}(n)}{n} - p_{0}}{\sqrt{\frac{p_{0}(1-p_{0})}{n}}}$  is in the

interval  $\left[-u_{\alpha}, u_{\alpha}\right]$ , then H<sub>0</sub> is accepted, in the opposite case H<sub>0</sub> is rejected and H<sub>1</sub> is accepted. The level of significance equals  $\alpha$ .

Let 
$$H_0: P(A) = p_0$$
 and  $H_1: P(A) < p_0$  one sided alternative hypothesis. Then, if  $H_0$  holds,  
k  $(n)$ 

then 
$$\frac{\frac{K_A(\Pi)}{n} - p_0}{\sqrt{\frac{p_0(1-p_0)}{n}}} \sim N(0,1)$$
, and  $P(-u_{2\alpha} < \frac{\frac{K_A(\Pi)}{n} - p_0}{\sqrt{\frac{p_0(1-p_0)}{n}}}) = 1 - \alpha$  supposing  $100 \le n$ ,

 $10 \le np_0$ . The critical region is  $(-\infty, -u_{2\alpha})$ , the acceptance region is  $[-u_{2\alpha}, \infty)$ . If the actual value of the test function  $\frac{\frac{k_A(n)}{n} - p_0}{\sqrt{\frac{p_0(1-p_0)}{n}}}$  is at least  $-u_{2\alpha}$ , then we accept  $H_0$ , if it is

under  $-u_{2\alpha}$  we reject  $H_0$  and we accept  $H_1$ . Data rather support that  $P(A) < p_0$  and they contradict to  $P(A) = p_0$ .

#### Remarks

- Alternative hypothesis  $H_1: p_0 < p$  can be similarly handled.
- The smaller the significance level, the larger the acceptance region.
- The larger the number of sample elements, the smaller the value of  $\sqrt{\frac{p_0(1-p_0)}{p_0(1-p_0)}}$

and the larger of its reciprocal. Consequently, smaller difference can be accepted between the relative frequency and the real probability in case of small number of sample elements. Same difference between the relative frequency and the real probability may result in acceptance of H<sub>0</sub> for small number of elements of sample and in rejection of H<sub>0</sub> in case of large number of elements of the sample.

• Acceptance of  $H_0$  in case of two sided alternative hypothesis and rejection of  $H_0$ in case of one sided alternative hypothesis may happen at the same significance level  $\alpha$ . Example will be presented later.

Same difference between the relative frequency and the real probability may result in acceptance of H<sub>0</sub> for small number of elements of sample and in rejection of H<sub>0</sub> in case of large number of elements of the sample.

Example

E1. Let the relative frequency of an event A during n independent experiment be 0.35. Test the hypothesis  $H_0: P(A) = 0.4$  and  $H_1: P(A) \neq 0.4$  in case of significance levels  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and number of sample elements n = 100, n = 300, n = 600. Results are included in Table j.7.

a n		Critical ragion	Actual value of	Decision
0,11	u <sub>α</sub>	Critical region	Actual value of	Decision
			the test function	
$\alpha = 0.1$ ,	1.645	$(-\infty, -1.645) \cup (1.645, \infty)$	-1.0206	$H_0$ is accepted
n=100				0
$\alpha = 0.1$ ,	1.645	$(-\infty, -1.645) \cup (1.645, \infty)$	-1.7678	H <sub>0</sub> is rejected,
n=300				$H_1$ is accepted
$\alpha = 0.1$ ,	1.645	$(-\infty, -1.645) \cup (1.645, \infty)$	-2.5	H <sub>0</sub> is rejected,
n=600				H <sub>1</sub> is accepted
$\alpha = 0.05$ ,	1.96	$(-\infty, -1.96) \cup (1.96, \infty)$	-1.0206	$H_0$ is accepted
n=100				
$\alpha = 0.05,$	1.96	$(-\infty, -1.96) \cup (1.96, \infty)$	-1.7678	$H_0$ is accepted
n=300				0
$\alpha = 0.05,$	1.96	$(-\infty, -1.96) \cup (1.96, \infty)$	-2.5	H <sub>0</sub> is rejected,
n=600				H <sub>1</sub> is accepted
$\alpha = 0.01$ ,	2.576	$(-\infty, -2.576) \cup (2.576, \infty)$	-1. 0206	$H_0$ is accepted
n=100				0 -
$\alpha = 0.01$ ,	2.576	$(-\infty, -2.576) \cup (2.576, \infty)$	-1.7678	$H_0$ is accepted
n=300		· · · · · ·		· ·
$\alpha = 0.01$ ,	2.576	$(-\infty, -2.576) \cup (2.576, \infty)$	-2.5	$H_0$ is accepted
n=600				- –

Table j.7. Testing hypothesis p = 0.4 with two sided alternative hypothesis

E2. Let the relative frequency of an event A during n independent experiment be 0.35. Test the hypothesis  $H_0: P(A) = 0.4$  and  $H_1: P(A) < 0.4$  in case of significance levels  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and number of elements of the samples n = 100, n = 300, n = 600. Results are included in Table j.8.

		-		
a,n	$u_{2\alpha}$	Critical	Actual value of the test	Decision
		region	function	
$\alpha = 0.1$ ,	1.282	(−∞,−1.282)	-1. 0206	$H_0$ is accepted
n=100				0
$\alpha = 0.1$ ,	1.282	(−∞,−1.282)	-1.7678	$H_0$ is rejected, $H_1$ is
n=300				accepted
$\alpha = 0.1$ ,	1.282	(−∞,−1.282)	-2.5	$H_0$ is rejected, $H_1$ is
n=600				accepted
$\alpha = 0.05$ ,	1.645	(−∞,−1.645)	-1.0206	$H_0$ is accepted
n=100		· · · · · · · · · · · · · · · · · · ·		0
$\alpha = 0.05$ ,	1.645	(−∞,−1.645)	-1.7678	$H_0$ is rejected, $H_1$ is
n=600				accepted
$\alpha = 0.05,$	1.645	(−∞,−1.645)	-2.5	$H_0$ is rejected, $H_1$ is

n=600				accepted
$\alpha = 0.01$ ,	2.326	(-∞,-2.326)	-1.0206	$H_0$ is accepted
n=100				0 -
$\alpha = 0.01$ ,	2.326	$(-\infty, -2.326)$	-1.7678	$H_0$ is accepted
n=300				0
$\alpha = 0.01$ ,	2.326	$(-\infty, -2.326)$	-2.5	$H_0$ is rejected, $H_1$ is
n=600				accepted

**Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>193</sup>

Table j.8. Testing hypothesis p = 0.4 with one sided alternative hypothesis

#### Test for the expectation in case of known value of dispersion

Let  $\eta = (\xi_1, \xi_2, ..., \xi_n)$  be a sample,  $\xi_i$  are random variables with expectation m and with known dispersion  $\sigma$ . We would like to check weather  $H_0 : m = m_0$  holds or conversely,

 $H_1: m \neq m_0. \text{ If } \xi_i \sim N(m, \sigma) \text{ or } 100 \leq n \text{ , then } \frac{\sum_{i=1}^n \xi_i}{\frac{n}{\sqrt{n}}} \sim N(0, 1). \text{ Consequently, if } H_0$ 

holds, then

$$P\left(-u_{\alpha} < \frac{\sum_{i=1}^{n} \xi_{i}}{\frac{\sigma}{\sqrt{n}}} < u_{\alpha}\right) = 1 - \alpha. \text{ The critical region is } (-\infty, -u_{\alpha}) \cup (u_{\alpha}, \infty), \text{ the}$$

acceptance region is  $[-u_{\alpha}, u_{\alpha}]$ . Using the test function  $u = \frac{\frac{\sum_{i=1}^{n} \xi_{i}}{n} - m_{0}}{\frac{\sigma}{\sqrt{n}}}$ , if the actual value

of the test function is in the critical region  $H_0$  is rejected, if it is in the acceptance region  $H_0$  is accepted.

If the alternative hypothesis is  $H_1: m < m_0$ , then the critical region is  $(-\infty, -u_{2\alpha})$ , the

acceptance region is  $(-u_{2\alpha}, \infty)$ . If the actual value of the test function  $u = \frac{\sum_{i=1}^{n} \xi_i}{\frac{n}{\sqrt{n}}}$  is in

the acceptance region, then  $H_0$  is accepted, if it is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted.

Remarks

- The alternative hypothesis  $H_1: m_0 < m$  can be similarly handled.
- The smaller the significance level, the larger the acceptance region.

# **Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>194</sup>

• The larger the number of elements of the sample, the smaller difference between the average and the real expectation can be allowed if  $H_0$  is accepted.

• The necessary number of elements of the sample to detect difference  $\varepsilon$  between the real and the hypothetical expectation is  $\left(\frac{u_{\alpha}\sigma}{\varepsilon}\right)^2 \le n$ . It is proportional to variance and the square of the reciprocal of the difference to detect.

• The case when applying two sided alternative hypothesis  $H_0$  is rejected and applying one sided alternative hypothesis  $H_0$  is accepted may occur.

• The test function requires the knowledge of the dispersion.

Example

E3. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that the dispersion of the random variable investigated equals 1.2. Sample average is supposed to be computed as 100.5. Test the hypothesis that  $H_0: m = 100$  and  $H_1: m \neq 100$  if the level is significance is  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50. Results are included in Table j.9.

α, n	u <sub>a</sub>	Critical region	Actual value of the test function	Decision
$\alpha = 0.1,$ n=10	1.645	$(-\infty,-1.645)\cup(1.645,\infty)$	1. 3176	$H_0$ is accepted
$\alpha = 0.1,$ n=30	1.645	$(-\infty, -1.645) \cup (1.645, \infty)$	2. 2822	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.1,$ n=50	1.645	$(-\infty, -1.645) \cup (1.645, \infty)$	2. 9463	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.05$ , n=10	1.96	$(-\infty, -1.96) \cup (1.96, \infty)$	1. 3176	H <sub>0</sub> is accepted
$\alpha = 0.05$ , n=30	1.96	(−∞,−1.96)∪(1.96,∞)	2. 2822	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.05$ , n=50	1.96	(-∞,-1.96)∪(1.96,∞)	2. 9463	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.01,$ n=10	2.576	(-∞,-2.576)∪(2.576,∞)	1. 3176	H <sub>0</sub> is accepted
$\alpha = 0.01,$ n=30	2.576	$(-\infty, -2.576) \cup (2.576, \infty)$	2. 2822	$H_0$ is accepted
$\alpha = 0.01,$ n=50	2.576	(-∞,-2.576)∪(2.576,∞)	2. 9463	$H_0$ is rejected, $H_1$ is accepted

Table j.9. Testing hypothesis m = 10 with two sided alternative hypothesis

E4. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that the dispersion of the random variable investigated equals 1.2. Sample average is supposed to be computed as 100.5. Test the hypothesis that  $H_0: m = 100$  and  $H_1: 100 < m$ , if the level is significance is  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50. Results are in Table j.10.

a,n	$u_{2\alpha}$	Critical	Actual value of the test	Decision
		region	function	
$\alpha = 0.1$ ,	1.282	$(1.282,\infty)$	1. 3176	$H_0$ is rejected
n=10				0
$\alpha = 0.1$ ,	1.282	(1.282,∞)	2. 2822	$H_0$ is rejected, $H_1$ is
n=30				accepted
$\alpha = 0.1$ ,	1.282	(1.282,∞)	2.9463	$H_0$ is rejected, $H_1$ is
n=50				accepted
$\alpha = 0.05$ ,	1.645	$(1.645,\infty)$	1.3176	$H_0$ is accepted
n=10				0
$\alpha = 0.05,$	1.645	(1.645,∞)	2. 2822	$H_0$ is rejected, $H_1$ is
n=30				accepted
$\alpha = 0.05$ ,	1.645	$(1.645,\infty)$	2.9463	$H_0$ is rejected, $H_1$ is
n=50				accepted
$\alpha = 0.01$ ,	2.326	$(2.326,\infty)$	1. 3176	$H_0$ is accepted
n=10				0 1
$\alpha = 0.01$ ,	2.326	(2.326,∞)	2. 2822	$H_0$ is accepted
n=30				
$\alpha = 0.01$ ,	2.326	(2.326,∞)	2.9463	$H_0$ is rejected, $H_1$ is
n=50				accepted

**Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>195</sup>

Table j.10. Testing hypothesis m = 10 with one sided alternative hypothesis

#### Test for the expectation in case of unknown value of dispersion

Let  $\eta = (\xi_1, \xi_2, ..., \xi_n)$  be the sample,  $\xi_i$  are random variables with expectation m and dispersion  $\sigma$  but the value of the dispersion is unknown. Let us assume that  $\xi \sim N(m, \sigma)$  or the number of the elements of the sample is large. We would like to check weather  $H_0: m = m_0$  holds or conversely,  $H_1: m \neq m_0$ . If  $\xi_i \sim N(m, \sigma)$  or  $100 \le n$ , then  $\frac{\sum_{i=1}^{n} \xi_{i}}{\frac{n}{\sigma}} - \frac{m}{\sigma} \sim N(0,1)$ . As we do not know the value of  $\sigma$ , we can not compute the actual

value of the above statistics. If we use s\* instead of  $\sigma$ ,  $\frac{\sum_{i=1}^{n} \xi_{i}}{\frac{n}{\sqrt{n}}} \sim \tau_{n-1}$  supposing  $H_{0}$ 

holds. Consequently,

$$P\left(-t_{n-1,\alpha} < \frac{\sum_{i=1}^{n} \xi_{i}}{\frac{n}{\sqrt{n}}} < t_{n-1,\alpha} \\ \frac{\frac{s}{\sqrt{n}}}{\sqrt{n}} < t_{n-1,\alpha}\right) = 1 - \alpha.$$

# **Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>196</sup>

The critical region is  $(-\infty, -t_{n-1,\alpha}) \cup (t_{n-1,\alpha}, \infty)$ , the acceptance region is  $[-t_{n-1,\alpha}, t_{n-1,\alpha}]$ .  $\sum_{n=1}^{n} \xi_{n-1,\alpha}$ 

$$=\frac{\sum_{i=1}^{n}\xi_{i}}{n}-m_{0}$$

Using the test function  $t = \frac{n}{\frac{s^*}{\sqrt{n}}}$ , if the actual value of the test function is in the

critical region  $H_0$  is rejected, if it is in the acceptance region  $H_0$  is accepted. If the alternative hypothesis is  $H_1: m < m_0$ , then the critical region is  $(-\infty, -t_{2\alpha})$ , the

acceptance region is  $(-t_{2\alpha}, \infty)$ . If the actual value of the test function, that is  $\frac{\frac{\sum_{i=1}^{n} x_{i}}{n} - m_{0}}{\frac{s^{*}}{\sqrt{n}}}$ ,

is in the acceptance region, then  $H_0$  is accepted, if it is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted.

If  $H_0: m = m_0$  and  $H_1: m < m_0$ , then the critical region is  $(-\infty, -t_{n,2\alpha})$  and acceptance region is  $[-t_{2\alpha}, \infty)$ . If the actual value of the test function is in the acceptance region, then  $H_0$  is accepted, if it is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted.

#### Remarks

- Alternative hypothesis  $H_1: m_0 < m$  can be similarly handled.
- The smaller the significance level, the larger the acceptance region.

• The larger the number of elements of the sample, the smaller difference between the average and the real expectation can be allowed if  $H_0$  is expected.

• The case when applying two sided alternative hypothesis  $H_0$  is rejected and applying one sided alternative hypothesis  $H_0$  is accepted may occur.

• Note that test functions in case of known and unknown dispersion are very similar.

#### Example

E5. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that the corrected empirical dispersion computed from the sample equals 1.2. Sample average is supposed to be 100.5. Test the hypothesis that  $H_0: m = 100$  and  $H_1: m \neq 100$ , if the level is significance are  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50. The results can be seen in Table j.11.

α,n	t <sub>a</sub>	Critical region	Actual value	Decision	
	ŭ		of the test		
			function		
$\alpha = 0.1, n=10$	1. 383	(-∞,-1.383)∪(1.383,∞)	1.3176	H <sub>0</sub>	is
				accepted	
$\alpha = 0.1, n=30$	1.311	(−∞,−1.311)∪(1.311,∞)	2. 2822	H <sub>0</sub>	is
				rejected,	$H_1$
				is accepted	d

$\alpha = 0.1, n=50$	1. 299	(−∞,−1.299)∪(1.299,∞)	2.9463	H <sub>0</sub>	is
				rejected,	$H_1$
				is accepte	d
$\alpha = 0.05,$	1.311	(−∞,−1.311)∪(1.311,∞)	1.3176	H <sub>0</sub>	is
n=10				rejected,	$H_1$
				is accepte	d
$\alpha = 0.05,$	1.833	(-∞,-1.833)∪(1.833,∞)	2. 2822	H <sub>0</sub>	is
n=30				rejected,	$H_1$
				is accepte	d
$\alpha = 0.05,$	1. 699	(−∞,−1.699)∪(1.699,∞)	2.9463	H <sub>0</sub>	is
n=50				rejected,	$H_1$
				is accepte	d
$\alpha = 0.01$ ,	2. 821	$(-\infty, -2.821) \cup (2.821, \infty)$	1.3176	H <sub>0</sub>	is
n=10				accepted	
$\alpha = 0.01$ ,	2.462	$(-\infty, -2.462) \cup (2.462, \infty)$	2. 2822	H <sub>0</sub>	is
n=30				accepted	
$\alpha = 0.01$ ,	2.405	$(-\infty, -2.405) \cup (2.405, \infty)$	2.9463	H <sub>0</sub>	is
n=50				rejected,	$H_1$
				is accepte	d

**Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>197</sup>

Table j.11. Testing hypothesis m = 100 in case of unknown dispersion with two sided alternative hypothesis

E6. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that corrected empirical dispersion computed by the sample equals 1.2. Sample average is supposed to be 100.5. Test the hypothesis that  $H_0: m = 100$  and  $H_1: 100 < m$  if the level is significance are  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50.

a,n	$t_{2\alpha}$	Critical region	Actual value	Decision
			of the test	
			function	
$\alpha = 0.1, n=10$	0.883	$(0.883,\infty)$	1.3176	$H_0$ is rejected
$\alpha = 0.1, n=30$	0.854	$(0.854,\infty)$	2. 2822	H <sub>0</sub> is
				rejected, H <sub>1</sub> is
				accepted
$\alpha = 0.1, n=50$	0.849	$(0.849,\infty)$	2.9463	H <sub>0</sub> is
				rejected, H <sub>1</sub> is
				accepted
$\alpha = 0.05,$	1. 383	(1.383,∞)	1.3176	H <sub>0</sub> is
n=10				accepted
$\alpha = 0.05,$	1. 311	(1.311,∞)	2. 2822	H <sub>0</sub> is
n=30				rejected, H <sub>1</sub> is
				accepted
$\alpha = 0.05$ ,	1. 299	(1.299,∞)	2.9463	H <sub>0</sub> is
n=50				rejected, $H_1$ is

Results can be followed in Table j.12.

**Probability theory and math.statistics** Basic concepts of mathematical statistics <sup>198</sup>

				accepted
$\alpha = 0.01$ ,	2.398	(2.398,∞)	1.3176	H <sub>0</sub> is
n=10				accepted
$\alpha = 0.01$ ,	2.150	(2.150,∞)	2. 2822	$H_0$ is rejected
n=30				H <sub>1</sub> is
				accepted
$\alpha = 0.01$ ,	2.110	(2.110,∞)	2.9463	H <sub>0</sub> is
n=50				rejected, $H_1$ is
				accepted

Table j.12. Testing hypothesis m = 100 in case of unknown dispersion with one sided alternative hypothesis

#### Test for the value of variance

Let  $\eta = (\xi_1, \xi_2, ..., \xi_n)$  be a sample,  $\xi_i$  are random variables with expectation m and dispersion  $\sigma$ . We would like to check weather  $H_0: \sigma^2 = \sigma_0^2$  holds or conversely,  $H_1: \sigma^2 \neq \sigma_0^2$ . Recall that if  $\xi_i \sim N(m, \sigma)$  or n is large, then  $\frac{(n-1)s^{*2}}{\sigma_0^2} \sim \chi_{n-1}^2$  supposing  $H_0$  holds. Consequently,  $P(\chi_{n-1,1-\alpha/2}^2 \leq \frac{(n-1)s^{*2}}{\sigma_0^2} \leq \chi_{n-1,\alpha/2}^2) = 1 - \alpha$ . The test function is  $\chi^2 = \frac{(n-1)s^{*2}}{\sigma_0^2}$ . The critical region is  $(0, \chi_{n-1,1-\alpha/2}^2) \cup (\chi_{n-1,\alpha/2}^2, \infty)$ , the acceptance region is  $\left[\chi_{n-1,1-\alpha/2}^2, \chi_{n-1,\alpha/2}^2\right]$ . If the actual value of the test function is in the acceptance region  $H_0$  is accepted, if it is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted. If the actual value of the test function is  $[0, \chi_{n-1,1-\alpha}^2] = 1 - \alpha$ . Now, critical region is  $(\chi_{n-1,1-\alpha}^2, \infty)$ , acceptance region is  $[0, \chi_{n-1,1-\alpha}^2]$ . If the actual value of the test function is  $[0, \chi_{n-1,1-\alpha}^2] = 1 - \alpha$ . Now, critical region is  $(\chi_{n-1,1-\alpha}^2, \infty)$ , acceptance region is  $[0, \chi_{n-1,1-\alpha}^2]$ . If the actual value of the test function is  $[0, \chi_{n-1,1-\alpha}^2] = 1 - \alpha$ . Now, critical region is  $(\chi_{n-1,1-\alpha}^2, \infty)$ , acceptance region is  $[0, \chi_{n-1,1-\alpha}^2]$ . If the actual value of the test function is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted.

Finally, if the alternative hypothesis is  $H_1: \sigma_0^2 < \sigma^2$ , then apply  $P(\frac{(n-1)s^{*2}}{\sigma_0^2} \le \chi_{n-1,\alpha}^2) = 1 - \alpha$ . Now, critical region is  $[0, \chi_{n-1,\alpha}^2)$ , acceptance region is  $[\chi_{n-1,\alpha}^2, \infty)$ . If the actual value of the test function is in the acceptance region,  $H_0$  is accepted, if it is in the critical region,  $H_0$  is rejected and  $H_1$  is accepted.

E7. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that corrected empirical dispersion computed by the sample equals  $s^*=1.3$ . Test the hypothesis that  $H_0: \sigma = 1.1$  and  $H_1: \sigma \neq 1.1$  if the level is significance are  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50.

α, n	$\chi_{1-\alpha/2}$	χ <sub>α/2</sub>	Critical region	Actual value of the test statistics	Decision
$\alpha = 0.1,$ n=10	16. 919	3. 325	[0,3.325)∪(16.919,∞)	12. 57	H <sub>0</sub> is
$\alpha = 0.1,$ n=30	42. 557	17.708	[0,17.708)∪(42.557,∞)	40. 504	$H_0$ is
$\alpha = 0.1,$ n=50	66. 339	33.93	[0,33.93)∪(42.557,∞)	68. 438	$H_0$ is rejected.
					$H_1$ is accepted
$\alpha = 0.05$ , n=10	19. 023	2. 7004	[0,2.70043.93)∪(19.023,∞)	12. 57	$H_0$ is
$\alpha = 0.05$ , n=30	45. 722	16. 047	[0,16047)∪(45.722,∞)	40. 504	$H_0$ is
$\alpha = 0.05,$ n=50	70. 222	31. 555	[0,31.555)∪(70.222,∞)	68. 438	$H_0$ is rejected,
					H <sub>1</sub> 1s accepted
$\alpha = 0.01,$ n=10	23. 589	1. 7349	[0,1.7349)∪(23.589,∞)	12. 57	H <sub>0</sub> is accepted
$\alpha = 0.01,$ n=30	52. 336	13. 121	[0,13.121)∪(52.336,∞)	40. 504	$H_0$ is rejected $H_1$ is
$\alpha = 0.01,$ n=50	78. 231	23.983	[0,23.983)∪(78.231,∞)	68. 438	$\frac{\text{accepted}}{\text{H}_0}$ is accepted

**Probability theory and math.statistics Basic concepts of mathematical statistics** <sup>199</sup>

Table j.13. Testing hypothesis  $\sigma = 1.1$  with two sided alternative hypothesis

E8. Let  $\xi_i \sim N(m, \sigma)$ . Let us assume that corrected empirical dispersion computed by the sample equals  $s^*=1.3$ . Test the hypothesis that  $H_0: \sigma = 1.1$  and  $H_1: 1.1 < \sigma$  if the level is significance are  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  and the number of sample elements are n = 10, n = 30, n = 50.

α, n	$\chi_{\alpha}$	Critical region	Actual value of	Decision
			the test statistics	
$\alpha = 0.1,$ n=10	14. 684	(14.684,∞)	12. 57	$H_0$ is accepted
$\alpha = 0.1,$ n=30	39.087	(39.087,∞)	40. 504	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.1,$ n=50	62.038	(62.038,∞)	68. 438	$H_0$ is rejected, $H_1$ is accepted
$\alpha = 0.05,$	16. 919	(16.919,∞)	12. 57	H <sub>0</sub> accepted

n=10				
$\alpha = 0.05$ ,	42.557	(42.557,∞)	40. 504	$H_0$ is accepted
n=30				-
$\alpha = 0.05,$	66. 339	(66.339,∞)	68.438	$H_0$ is rejected, $H_1$ is
n=50				accepted
$\alpha = 0.01$ ,	21.666	(21.666,∞)	12.57	$H_0$ is accepted
n=10				
$\alpha = 0.01$ ,	49. 588	(49.588,∞)	40. 504	$H_0$ is rejected
n=30				$H_1$ is accepted
$\alpha = 0.01$ ,	74.919	(74.919,∞)	68.438	$H_0$ is accepted
n=50				× •

**Probability theory and math.statistics** Basic concepts of mathematical statistics

Table j.12. Testing hypothesis  $\sigma = 1.2$  with one sided alternative hypothesis

#### Kolmogorov-Smirnov' test for the cumulative distribution function

Finally, we present Komogorov-Smirnov' test to test the distribution of the sample. Namely, the hypothesis is that the cumulative distribution function is a given function or data contradict to that. To do that we use the maximum difference between the empirical distribution function constructed by the sample and the hypothetical distribution function. Let  $\eta = (\xi_1, \xi_2, ..., \xi_n)$  be the sample, its values are  $x_1, x_2, ..., x_n$ . Let  $F_e(z)$  be the empirical distribution function constructed on the basis of the sample. Let the null hypothesis be  $H_0: F = F_0$  and  $H_1: F \neq F_0$ . If  $H_0$  holds, then  $K(y) = P(\lim_{n \to \infty} \sqrt{n} \sup_{z \in \mathbb{R}} |F_e(z) - F(z)| < y)$  can be given for any value of y. The values of this function are included in Table 4.

Therefore, if H<sub>0</sub> holds,, fixing the value  $1 - \alpha$ , then one can find the value  $k_{\alpha}$  for which  $P(\lim_{n \to \infty} \sqrt{n} \sup_{z \in \mathbb{R}} |F_e(z) - F(z)| \le k_{\alpha}) = 1 - \alpha$ . The critical region is  $(k_{\alpha}, \infty)$ , acceptance region

is  $[0, k_{\alpha}]$ . Test function is  $\sqrt{n} \sup_{z \in \mathbb{R}} |F_e(z) - F(z)|$ . If the actual value of the test function is in

the critical region then  $H_0$  is rejected, if it is in the acceptance region  $H_0$  is accepted. Referring to the shape of the empirical distribution function, the supremum can be computed as the maximal difference of the cumulative distribution function and the empirical distribution function and its right hand side limit at the points of the values of the sample. Consequently, it is enough to compute the values of the empirical distribution function at the points of the sample values, the right hand side limit of that at the same points, furthermore the values of the empirical distribution function and their limits at these points. Taking the differences, and their maximum we get the actual value of the test function.

#### Example

E9. Let the elements of the sample be  $x_1 = 2$ ,  $x_2 = 0.5$ ,  $x_3 = 0.1$ ,  $x_4 = 0.7$ ,  $x_5 = 0.2$ . Test that  $H_0: F(z) = 1 - e^{-z}$ ,  $H_1: F(z) \neq 1 - e^{-z}$ .

First note that the basis of Kolmogorov's test is an asymptotic theorem, hence it is not recommended using for a sample of 5 elements. Nevertheless, for the sake of simplicity we do that.

200

Empirical cumulative distribution function is  $F_e(z) = \begin{cases} 0 \text{ if } z \le 0.1 \\ 0.2 \text{ if } 0.1 < z \le 0.2 \\ 0.4 \text{ if } 0.2 < z \le 0.5 \\ 0.6 \text{ if } 0.5 < z \le 0.7 \\ 0.8 \text{ if } 0.7 < z \le 2 \\ 1 \text{ if } 2 < z \end{cases}$ 

x <sub>i</sub>	$F_e(x_i)$	$\lim_{z\to x_i^+} F_e(z)$	$F_0(x_i)$	$\left F_{e}(x_{i})-F_{0}(x_{i})\right $	$\lim_{z \to x_i^+} F_e(z) - F_0(x_i)$
0.1	0	0.2	0.095	0.195	0.105
0.2	0.2	0.4	0.181	0.019	0.219
0.5	0.4	0.6	0.393	0.077	0.277
0.7	0.6	0.8	0.503	0.097	0.297
2	0.8	1	0.865	0.065	0.135

Table j.13. Testing hypothesis  $F(z) = 1 - e^{-z}$ 

One can see that  $\max |F_e(x_i) - F_0(x_i)| = 0.195$ ,  $\max |\lim_{z \to x_i+} F_e(z) - F_0(x_i)| = 0.297$ , therefore  $\max_{x \in \mathbb{R}} |F_e(x) - F_0(x)| = 0.297$ . The actual value of the test function is  $\sqrt{5} \cdot 0.297 = 0.664$ .

The critical values for  $\alpha = 0.1$ ,  $\alpha = 0.05$ ,  $\alpha = 0.01$  are, consequently  $H_0$  is accepted in all cases of level of significance. One can check that the hypothesis  $H_0: F(z) = 1 - e^{-1.1z}$  is also excepted on the basis of this data. This means that conclusion " $H_0$  is accepted" means that data do not contradict to the hypothesis.

Of course, many other tests exist for testing hypothesis, but their presentations are out of the frame of this booklet.

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Cumulative distribution function of standard normally distributed random variables

 $\Phi(x) = P(\xi < x)$  $\xi \sim N(0,1)$ 

Х	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
.1	.5398	.5438	.5478	.5517	.5557	.5596	.5636	.5675	.5714	.5753
.2	.5793	.5832	.5871	.5910	.5948	.5987	.6026	.6064	.6103	.6141
.3	.6179	.6217	.6255	.6293	.6331	.6368	.6406	.6443	.6480	.6517
.4	.6554	.6591	.6628	.6664	.6700	.6736	.6772	.6808	.6844	.6879
.5	.6915	.6950	.6985	.7019	.7054	.7088	.7123	.7157	.7190	.7224
.6	.7257	.7291	.7324	.7357	.7389	.7422	.7454	.7486	.7517	.7549
.7	.7580	.7611	.7642	.7673	.7704	.7734	.7764	.7794	.7823	.7852
.8	.7881	.7910	.7939	.7967	.7995	.8023	.8051	.8078	.8106	.8133
.9	.8159	.8186	.8212	.8238	.8264	.8289	.8315	.8340	.8365	.8389
1.0	.8413	.8438	.8461	.8485	.8508	.8531	.8554	.8577	.8599	.8621
1.1	.8643	.8665	.8686	.8708	.8729	.8749	.8770	.8790	.8810	.8830
1.2	.8849	.8869	.8888	.8907	.8925	.8944	.8962	.8980	.8997	.9015
1.3	.9032	.9049	.9066	.9082	.9099	.9115	.9131	.9147	.9162	.9177
1.4	.9192	.9207	.9222	.9236	.9251	.9265	.9279	.9292	.9306	.9319
1.5	.9332	.9345	.9357	.9370	.9382	.9394	.9406	.9418	.9429	.9441
1.6	.9452	.9463	.9474	.9484	.9495	.9505	.9515	.9525	.9535	.9545
1.7	.9554	.9564	.9573	.9582	.9591	.9599	.9608	.9616	.9625	.9633
1.8	.9641	.9649	.9656	.9664	.9671	.9678	.9686	.9693	.9699	.9706
1.9	.9713	.9719	.9726	.9732	.9738	.9744	.9750	.9756	.9761	.9767
2.0	.9772	.9778	.9783	.9788	.9793	.9798	.9803	.9808	.9812	.9817
2.1	.9821	.9826	.9830	.9834	.9838	.9842	.9846	.9850	.9854	.9857
2.2	.9861	.9864	.9868	.9871	.9875	.9878	.9881	.9884	.9887	.9890
2.3	.9893	.9896	.9898	.9901	.9904	.9906	.9909	.9911	.9913	.9916
2.4	.9918	.9920	.9922	.9925	.9927	.9929	.9931	.9932	.9934	.9936
2.5	.9938	.9940	.9941	.9943	.9945	.9946	.9948	.9949	.9951	.9952
2.6	.9953	.9955	.9956	.9957	.9959	.9960	.9961	.9962	.9963	.9964
2.7	.9965	.9966	.9967	.9968	.9969	.9970	.9971	.9972	.9973	.9974
2.8	.9974	.9975	.9976	.9977	.9977	.9978	.9979	.9979	.9980	.9981
2.9	.9981	.9982	.9982	.9983	.9984	.9984	.9985	.9985	.9986	.9986
3.0	.9987	.9987	.9987	.9988	.9988	.9989	.9989	.9989	.9990	.9990
3.1	.9990	.9991	.9991	.9991	.9992	.9992	.9992	.9992	.9993	.9993
3.2	.9993	.9993	.9994	.9994	.9994	.9994	.9994	.9995	.9995	.9995
3.3	.9995	.9995	.9995	.9996	.9996	.9996	.9996	.9996	.9996	.9997
3.4	.9997	.9997	.9997	.9997	.9997	.9997	.9997	.9997	.9997	.9998
3.5	.9998	.9998	.9998	.9998	.9998	.9998	.9998	.9998	.9998	.9998
3.6	.9998	.9998	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999
3.7	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999
3.8	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999	.99999

Table 1. Cumulative distribution function of standard normally distributed random variables

### Critical values of Student's t distributed random variables

$$P(t_n, \alpha < |\xi|) = \alpha$$
$$\xi \sim \tau_n$$

n\α	0.2	0.1	0.05	0.025	0.01	0.001
1	3.078	6.314	12.706	25.452	63.657	636.621
2	1.886	2.920	4.303	6.205	9.925	31.599
3	1.638	2.353	3.182	4.177	5.841	12.924
4	1.533	2.132	2.776	3.495	4.604	8.610
5	1.476	2.015	2.571	3.163	4.032	6.869
6	1.440	1.943	2.447	2.969	3.707	5.959
7	1.415	1.895	2.365	2.841	3.499	5.408
8	1.397	1.860	2.306	2.752	3.355	5.041
9	1.383	1.833	2.262	2.685	3.250	4.781
10	1.372	1.812	2.228	2.634	3.169	4.587
11	1.363	1.796	2.201	2.593	3.106	4.437
12	1.356	1.782	2.179	2.560	3.055	4.318
13	1.350	1.771	2.160	2.533	3.012	4.221
14	1.345	1.761	2.145	2.510	2.977	4.140
15	1.341	1.753	2.131	2.490	2.947	4.073
16	1.337	1.746	2.120	2.473	2.921	4.015
17	1.333	1.740	2.110	2.458	2.898	3.965
18	1.330	1.734	2.101	2.445	2.878	3.922
19	1.328	1.729	2.093	2.433	2.861	3.883
20	1.325	1.725	2.086	2.423	2.845	3.850
25	1.316	1.708	2.060	2.385	2.787	3.725
30	1.310	1.697	2.042	2.360	2.750	3.646
35	1.306	1.690	2.030	2.342	2.724	3.591
40	1.303	1.684	2.021	2.329	2.704	3.551
50	1.299	1.676	2.009	2.311	2.678	3.496
60	1.296	1.671	2.000	2.299	2.660	3.460
70	1.294	1.667	1.994	2.291	2.648	3.435
80	1.292	1.664	1.990	2.284	2.639	3.416
90	1.291	1.662	1.987	2.280	2.632	3.402
100	1.290	1.660	1.984	2.276	2.626	3.390
8	1.282	1.645	1.960	2.241	2.576	3.291

Table 2. Critical values of Student's t distributed random variables

Critical values of  $\chi^2$  distributed random variables

$$P(\chi_{n,\alpha}^2 < \xi) = \alpha$$
$$\xi \sim \chi_n^2$$

n∖α	0.999	0.99	0.975	0.95	0.90	0.10	0.05	0.025	0.01	0.001
1	.00	.00	.00	.00	.02	2.71	3.84	5.02	6.63	10.83
2	.00	.02	.05	.10	.21	4.61	5.99	7.38	9.21	13.82
3	.02	.11	.22	.35	.58	6.25	7.81	9.35	11.34	16.27
4	.09	.30	.48	.71	1.06	7.78	9.49	11.14	13.28	18.47
5	.21	.55	.83	1.15	1.61	9.24	11.07	12.83	15.09	20.52
6	.38	.87	1.24	1.64	2.20	10.64	12.59	14.45	16.81	22.46
7	.60	1.24	1.69	2.17	2.83	12.02	14.07	16.01	18.48	24.32
8	.86	1.65	2.18	2.73	3.49	13.36	15.51	17.53	20.09	26.12
9	1.15	2.09	2.70	3.33	4.17	14.68	16.92	19.02	21.67	27.88
10	1.48	2.56	3.25	3.94	4.87	15.99	18.31	20.48	23.21	29.59
11	1.83	3.05	3.82	4.57	5.58	17.28	19.68	21.92	24.72	31.26
12	2.21	3.57	4.40	5.23	6.30	18.55	21.03	23.34	26.22	32.91
13	2.62	4.11	5.01	5.89	7.04	19.81	22.36	24.74	27.69	34.53
14	3.04	4.66	5.63	6.57	7.79	21.06	23.68	26.12	29.14	36.12
15	3.48	5.23	6.26	7.26	8.55	22.31	25.00	27.49	30.58	37.70
16	3.94	5.81	6.91	7.96	9.31	23.54	26.30	28.85	32.00	39.25
17	4.42	6.41	7.56	8.67	10.09	24.77	27.59	30.19	33.41	40.79
18	4.90	7.01	8.23	9.39	10.86	25.99	28.87	31.53	34.81	42.31
19	5.41	7.63	8.91	10.12	11.65	27.20	30.14	32.85	36.19	43.82
20	5.92	8.26	9.59	10.85	12.44	28.41	31.41	34.17	37.57	45.31
25	8.65	11.52	13.12	14.61	16.47	34.38	37.65	40.65	44.31	52.62
30	11.59	14.95	16.79	18.49	20.60	40.26	43.77	46.98	50.89	59.70
35	14.69	18.51	20.57	22.47	24.80	46.06	49.80	53.20	57.34	66.62
40	17.92	22.16	24.43	26.51	29.05	51.81	55.76	59.34	63.69	73.40
50	24.67	29.71	32.36	34.76	37.69	63.17	67.50	71.42	76.15	86.66
60	31.74	37.48	40.48	43.19	46.46	74.40	79.08	83.30	88.38	99.61
70	39.04	45.44	48.76	51.74	55.33	85.53	90.53	95.02	100.43	112.32
80	46.52	53.54	57.15	60.39	64.28	96.58	101.88	106.63	112.33	124.84
90	54.16	61.75	65.65	69.13	73.29	107.57	113.15	118.14	124.12	137.21
100	61.92	70.06	74.22	77.93	82.36	118.50	124.34	129.56	135.81	149.45

Table 3.Critical values of  $\chi^2$  distributed random variables

## Kolmogorov's function

$$K(y) = P(\lim_{n \to \infty} \sqrt{n} \sup_{z \in R} \left| F_e(z) - F(z) \right| < y)$$

у	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.4	.003	.004	.005	.007	.010	.013	.016	.020	.025
0.5	.036	.043	.050	.059	.068	.077	.088	.099	.110
0.6	.136	.149	.163	.178	.193	.208	.224	.240	.256
0.7	.289	.305	.322	.339	.356	.373	.390	.406	.423
0.8	.456	.472	.488	.504	.519	.535	.550	.565	.579
0.9	.607	.621	.634	.647	.660	.673	.685	.696	.708
1.0	.730	.741	.751	.761	.770	.780	.789	.798	.806
1.1	.822	.830	.837	.845	.851	.858	.864	.871	.877
1.2	.888	.893	.898	.903	.908	.912	.916	.921	.925
1.3	.932	.935	.939	.942	.945	.948	.951	.953	.956
1.4	.960	.962	.965	.967	.968	.970	.972	.973	.975
1.5	.978	.979	.980	.981	.983	.984	.985	.986	.986
1.6	.988	.989	.989	.990	.991	.991	.992	.992	.993
1.7	.994	.994	.995	.995	.995	.996	.996	.996	.996
1.8	.997	.997	.997	.998	.998	.998	.998	.998	.998
1.9	.999	.999	.999	.999	.999	.999	.999	.999	.999

Table 4. Kolmogorov's function